

# SAIA® PLC Programmable controllers

Manual of the series PCA 1 Hardware



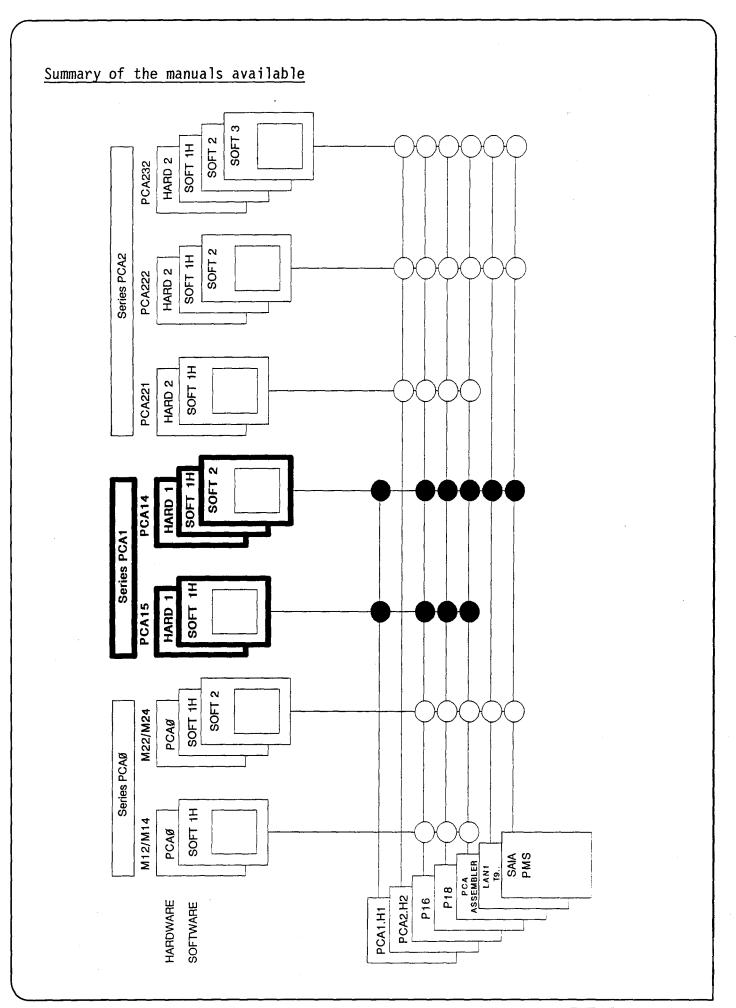
## **HARDWARE - PCA1**

## **GENERAL**

PART A BASIC MODULES

PART B INPUT/OUTPUT MODULES as well as ADDITIONAL and DISPLAY MODULES

PART C OPERATING MODES



## Overview of the SAIA°PLC, system family PCA

Series PCA2	User memory  We program steps  + 8K text characters  + 8K byte data  256 or 512 I/0	PCA222C30C30  User memory max. 8K program steps max. 8K text characters/data	PCA221C3ØC3ØC3ØC3ØC3ØC3Ø	max. 8K program steps
Series PCA1		PCA141 PCA147 PCA147 +C45 M41M47C45  32(56) 64(112) 128(224) 1/0  User memory max. 8K program steps max. 8K text characters/data	PCA151 PCA156 PCA157 +C45  PCA151M56M57C45  32(56) 64(112) 128(224) I/0  User memoryC45	max. 4K program steps
Series PCA0		Standard versions and OEM  PCAB.M22  PCAB.M24  -M22  max. 32 I/O  User memory max. 4K program steps max. 4K text characters/data	Standard versions           PCAØ.M12         PCAØ.M14          M12        M14           24/32 1/0         48/64 1/0           User memory max 4K program stens	max. 4% pi ugi ani steps
	Soft level 2  Soft level 2 + 32 word instructions for - arithmetic ± 9 digits - data transfer - word register	Soft level 1H  Soft level 1H + Serial interface + Date-time + Data register + Parameter instructions (soft interrupt, FIFO, PID)	Instruction set with 32 basic instructions for timers and counters - parallel programs and subroutines - indexing, etc.  20 additional instructions for arithmetic - data transfer - check-sum	

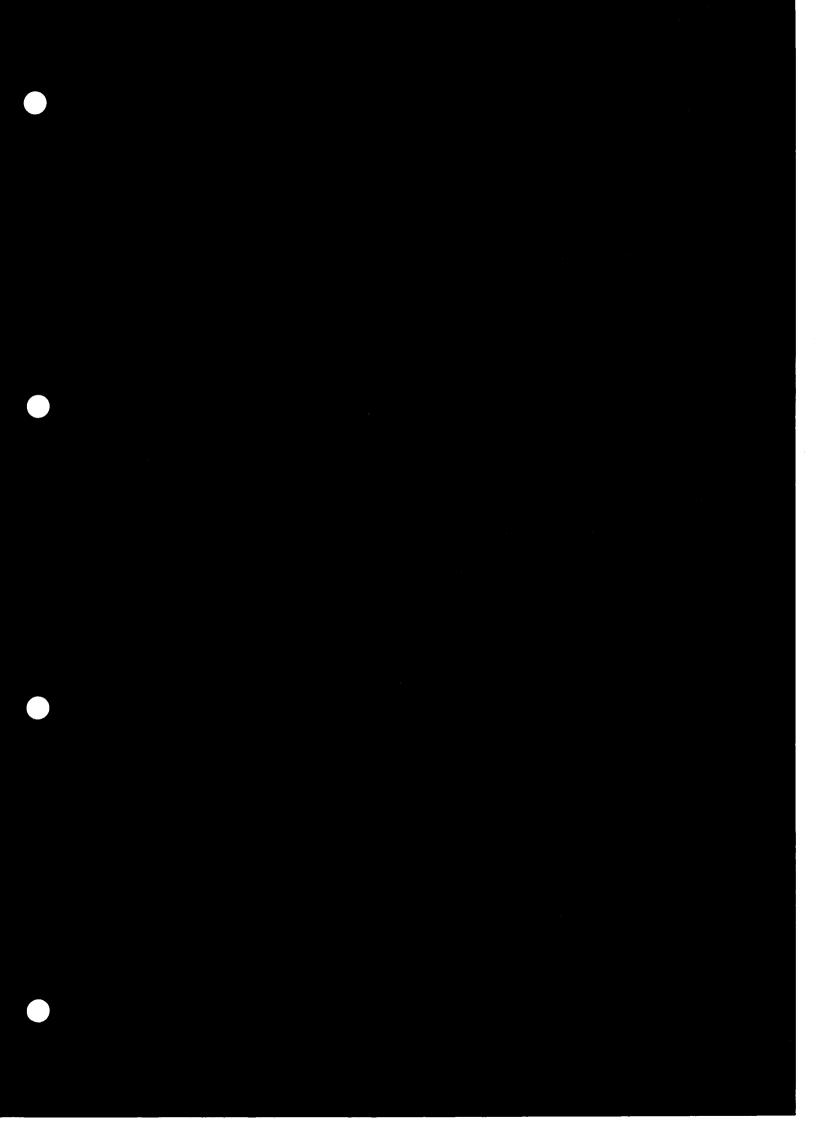
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Selling price: sFr 60.-

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PART A BASIC MODULES

Chapter A 1 System structure

Chapter A 2 Technical data of system series PCA15

Chapter A 3 Technical data of system series PCA14

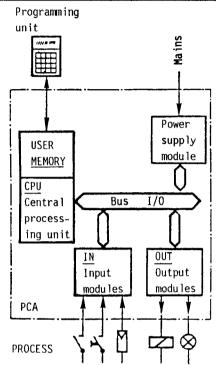
Chapter A 4 Extension housing ..C45

Chapter A 5 Voltage supply, watchdog, reset, dimensions

## **PART A Hardware**

#### A 1 System structure

## A 1.1 Block circuit diagram of the SAIA°PLC



The SAIA°PLC is subdivided into the following hardware modules:

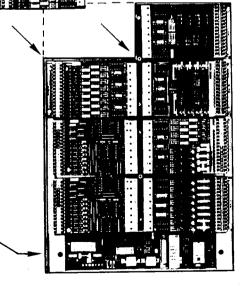
- Central processing unit CPU
- User MEMORY
- SUPPLY module
- Serial communication interface
- Input modules (digital or analog)
- Output modules (digital or analog)

All listed modules can be plugged onto the common bus.

Program input takes place via the programming unit.

4 or 8 plug-in locations for I/O modules which may be arranged as desired

Basic module (without I/O) comprising processor section (CPU), supply section and rack. Some basic modules allow the connection to an extension housing.



#### Instruction WHAT WHERE Line Counters Flags ΙN (address Timers OPERAND STEP CODE Ø÷255 25<u>6</u>÷287<sup>1)</sup> 288÷999 13 WHERE 14 15 Address L Da ta 0123 STH 0011 Ĺ CODE **。** 36 OUT 0124 ANH 0014 **o** 37 Processor 0125 ORH 0017 **-** 38 WHAT Data 39 0126 OUT ØØ38 **•** 40 Address **-0** 42 FII - E14 STEP ACCU COUNTER User memory Central processing unit (CPU) Inputs/Outputs

## A 1.2 Functional description of the SAIA°PLC

The instructions for linking the input signals and formation of the actual output states are entered by the user in the user memory, arranged in "words". Each word having a length of 16 bits comprises a complete instruction, subdivided into CODE and OPERAND. The CODE states "what" is to be executed, whilst the OPERAND states "where" the element in question is located.

The instructions are read and interpreted consecutively by the CPU. After an instruction has been processed, the step counter reading is incremented by 1 and the next instruction in the user memory is read. Additionally, the logical states of the elements (H or L) are interrogated by the CPU via the data bus. Each linkage result is stored in the accumulator (ACCU). With an output instruction, the result of the operation for example is transferred to an output.

The CPU contains all units required for auxiliary functions, such as e.g. timer and counter registers, flag memories, index registers, etc. The return addresses for subroutines are stored in additional memories.

<sup>1)</sup> The registers 288 to 479 may be used as counters with the PCA14 from version V6.034 onwards.



## A 2 Technical data of system series PCA15

CPU

 $\mu P$  8085.2, system program V6.3.. 1)

Cycle time

70μs per program line (average of logic instructions)

Instruction set

Software level 1H

32 basic instructions + 20 additional instructions for transfer functions, arithmetics  $(+, -, x, \div)$  and

check sum

Parallel programs and

subroutines

Up to 16 parallel programs, any number of subroutines

nested down through 3 levels

Index register

1 per parallel program (max. 16)

User memory

1K, 2K or 4K program lines on EPROM,

RAM or buffered RAM chip

Inputs and outputs

32, 64 or 128 input/output addresses corresponding to

the housing size

Up to 56, 112 or 224 inputs/outputs corresponding to the housing size, with compact module PCA1.B90 or B80

Flag memory

712 flags, 235 of which are non-volatile

477 are volatile or non-volatile 2)

Timer and counter or arithmetic registers

32 timer or counter registers +

Counting or

32 counter registers, volatile 2)

computing capacity

65'535 (216-1) per counter register, extendible as

desired by means of cascading

Time range

Ø.1...6553s (Ø.Ø1...655s) 2)

<sup>1)</sup> When switching on the PLC, the CPU system version is displayed on the programming unit ..P10 or ..P05 for one second.

<sup>2)</sup> Please refer to PCA15, page 8A for modification possibilities

### A 2.1 Versions of system series PCA15

3 versions are available, corresponding to the required number of input and output addresses.

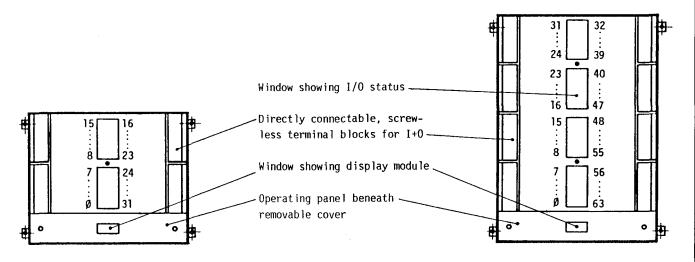
### Type of system PCA151

em PCA151 Type of system PCA156

32 I+O addresses

56 I+O with compact module PCA1.B9Ø

64 I+O addresses 112 I+O with compact module PCA1.B9Ø



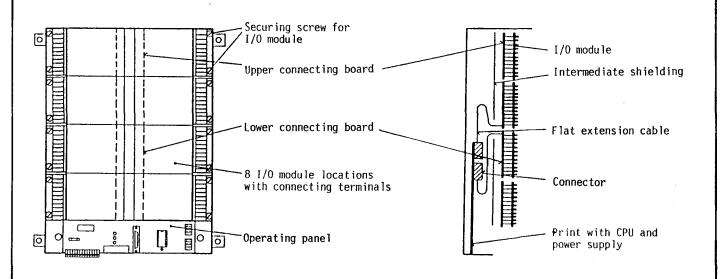
Basic module PCA1.M51

Basic module PCA1.M56

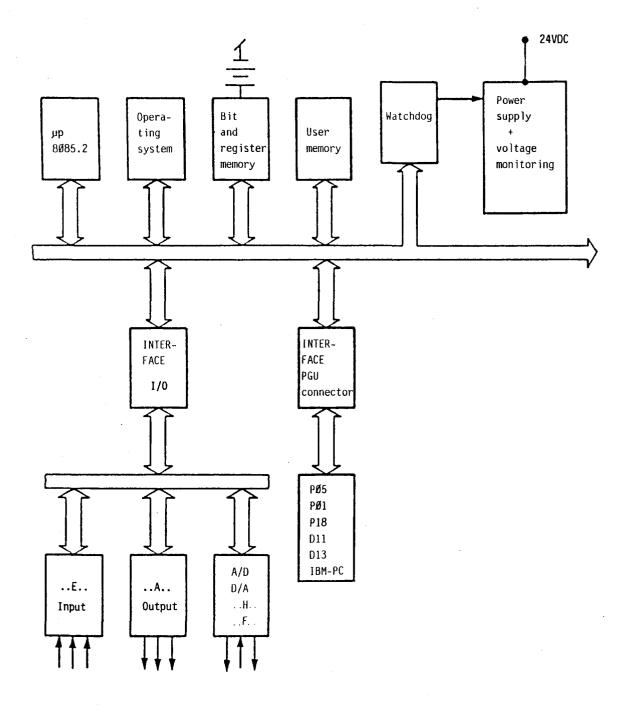
#### PCA1.M51 and PCA1.M56 Basic modules

In addition to the processor (CPU), the basic modules of the system series PCA15 also include the internal power supply and the housing.

#### Presentation (PCA1.M56)



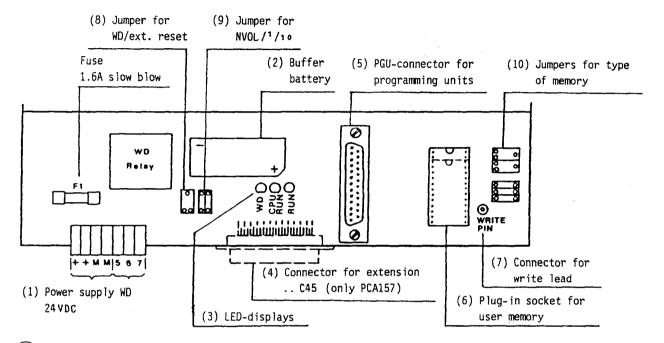
## A 2.2 Block circuit diagram PCA15



#### A 2.3 Basic modules

## A 2.3.1 Operating panel of the basic modules PCA1.M51/M56/M57

All operating elements for the PCA15 are clearly arranged on the operating panel which can be covered.



- 1 The terminal board is plugged onto the circuit board. Wires with cross-sections up to  $1.5~\mathrm{mm^2}$  are accepted by the screw terminals.
- The buffered battery supplies the non-volatile flags, counters/timers and, if used, the 6116 or 6264 RAM chip user memory. Data are retained approx. 2 months with the PLC switched off. The pluggable NiCd cell lasts approx. 5 years (order no. for spare batteries: no. 4'507'1360'0).
- The LED "CPU RUN" (yellow) blinks every 2s during normal operation. When the time base is set to 0.01s, the blinking rate is 0.2s. If the LED stays on or off, there is either no power available, the PLC is in RESET mode, the CPU has a malfunction or a trap has been produced in the software sequence.

The LED "RUN" (green) is illuminated when the CPU is in the operating mode RUN and the user program is executed normally.

The watchdog monitoring indicator (green) is illuminated when the watchdog relay is excited.

- The 25-pole connector for the extension cable (only on the PCA157) allows connection to housing ...C45 which means that the number of I+O addresses is increased from 64 to 128 I+O or 112 to 224 I+O respectively.
- 5) The 25-pole PGU connector is used to connect the programming unit ..PØ5 or any other programming unit by using the programming interface PCAØ.PØ1. Also the display modules PCA1.D11 and ..D13 can be connected here.

The 28-pole plug-in socket accommodates the user memory. When inserting, please make sure that the index groove is at the top. If memory chips with a 24-pole socket are used (e.g. 6116, 2716, 2732A), please insert in such a way that they are flush with the lower edge of the socket.

The following memory chips can be used:

- unbuffered RAM chips, on plug-in socket
No. 4'502'4512'0 (type 6116) for 1K program lines (24-pole)
No. 4'502'4718'0 (type 6264 or 8464) for 4K program lines (28-pole)

Comment: The RAM 6116 and 6264 or 8464 allow writing, erasing and modification of a program. On voltage failure, the memory contents are stored via the buffered battery for approx. 2 months. The program, however, is not transportable, because the data stored is lost, if the RAM chip is removed.

- buffered RAM chips, on plug-in socket
PCA1.R92 for 2K program lines (24-pole, with write lead) 19
PCA1.R95 for 4K program lines (28-pole) see page 81B
PCA1.R96 for 4K program lines (28-pole)

In contrast to the unbuffered RAM chip, the program in this memory is transportable, since it is protected by an integrated circuit and a lithium battery which lasts approx. 8 years (..R96 approx. 6 years). These chips are therefore particularly suitable for starting the controller.

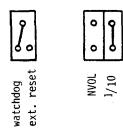
EPROM chips, on plug-in socket
 No. 4'502'4373'Ø (type 2716) for 1K program lines (24-pole)
 No. 4'502'4644'Ø (type 2732A) for 2K program lines (24-pole)
 No. 4'502'4719'Ø (type 2764) for 4K program lines (28-pole)

According to the prior art, reliable operation of user programs over a period of several years is only ensured, if EPROM memories are used. The manufacturers chosen by us guarantee program safety for at least 10 years.

It is recommended to protect the window of the EPROM by means of a sticker to prevent the memory from being accidently subjected to UV-radiation.

- 7) Connector for the write lead for the types PCA1.R91/R92/R94 (..R91 and ..R94 are no more available).
- Attention: Neither the write lead nor the connector WR must be touched or get into contact with the frame, since otherwise changes in contents may occur.

## Function of the preselection jumpers



- 8 Watchdog/external reset (factory setting: jumper in position watchdog)
  According to the block circuit diagram in chapter "Power supply", terminal
  7 of the terminal board can be preselected either for the break contact of
  the WD-relay or as a fast reset input (see chapter "Fast external RESET
  circuit").
- 9 NVOL (factory setting: not inserted)
  If the jumper is inserted, all flags, timer and counter registers are non-volatile (retentive).

1/10 (factory setting: jumper inserted) If the jumper is <u>inserted</u>, the time-base is 1/10s. If the jumper is <u>not inserted</u>, the time-base is to 1/100s.

Preselection for the user memory
Corresponding to the type of memory and storage capacity the jumpers must be inserted differently (see the following table).

Attention: Do not use any other combinations, as these can cause damage to the CPU.

				R	AM				bu	ffere	d R	AM					EP	ROM		
R95 EPROM	3	1)	61	16	62 84		RS	91 <sup>1)</sup>	R	92	R	94 <sup>1)</sup>	R9		27	16	27	32 A	27	64
RAM	9 0	8	08	مـ	0	_	90	8	٥٥	9	٥٥	8	٥٥	8	90	Ŷ	9 0	۶	٥٥	8
2764	0	_	Ьo	8	0.	2)0	90	~	90	9	00	9	60	2)	90	~	0 8	~	00	~
8464 R95	3	.)																		
6116	0	0	<b>~</b>	<b>~</b>	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	•
2716	0	0	0	0	0	0	0-	•	0	0	0	0	0	0	0	•	0	0	0	0
8464 2732/64	9	•	٥	٥	•	<b>-</b>	0	°	0-	<u>~</u>	٥	•	٥	•	0	٥	0-	<b></b> ○	0-	•

<sup>1)</sup> memory chips which are no more available

<sup>2)</sup> position "write disable"

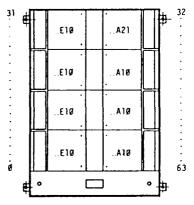
<sup>3)</sup> factory setting for ..R95/..R96

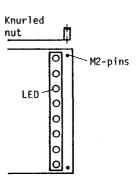
## 2.4 Register organization Register 1 bit 16 bits Element address 999 F Flags (NV) 765 8 bits 764 PP 15 1R Flags Index registers (VOL\*) **(V)** PP Ø 320 319 F/C Flags (VOL\*) Counters С Counters (VOL\*) 288 287 C/T Counters (VOL\*) Timers T Timers (VOL\*) 256 255 1/0 inputs (V) Outputs ØØØ (V) volatile (NV) non-volatile (VOL\*) volatile, can be made non-volatile with jumper NVOL



## A 2.5 Brief instruction for operating a PCA15

a) Installation of I/O modules

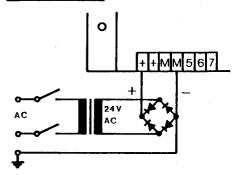




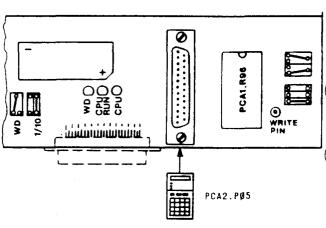
In order to try out the programming examples, it is recommended that addresses Ø...31 of a PCA156 should be equipped with ..E1Ø I-modules, while O-modules should use the addresses 32...63.

- 1. Undo fastening screw to remove the cover and lift.
- 2. Center I/O modules above the two M2pins and carefully press them into the blade connectors.
- 3. Tighten M2-knurled nuts and cheese head screws with tooth washers on the terminal side.
- 4. Provide the LEDs with the corresponding address labels.

b) Power supply



- 5. Take a transformer (for "playing" 30VA are sufficient) with a secondary voltage of 24VAC and connect the terminals + and M of the PLC via the bridge rectifier.
- 6. A switch has the advantage that all resettable elements and the STEP-counter can easily be reset to their defined starting positions by switching off the PLC.
- c) Connecting the user memory ..R96 and the programming unit ..PØ5



- All jumpers must be positioned as evident from the figure (factory setting), so that the PCA1.R96 buffered RAM chip can be used.
- 8. Insert the buffered RAM chip ..R96 as shown with the index groove at the top.
- 9. Connect the ..PØ5 programming unit at the 25-pole PGU-connector.

- d) Example program "Blinker"
  - (10.) Switch on the power supply of the PLC. The yellow "CPU RUN" of the 3 LEDs on the operating panel blinks, 1s on, 1s off, while the green LED does not light up.
  - (11.) Actuate the mode selecting key P (PROG) at the programming unit for approx. 1/2s, until the LED "PROG" lights up.
  - (12.) Type in the following "Blinker" program:

	STEP	CODE	OPERAND	Programm in mnemocode
A,E	(ØØØØ)1>	<del>(ØØ)</del>	$(\emptyset\emptyset\emptyset\emptyset)$	
Ε	(ØØØ1)	Ø2	256	r-►STL 256
Ε	(ØØØ2)	14	256	STR 256
Ε	(ØØØ3)	ØØ	5	Ø.5s
Ε	(ØØØ4)	13	32	C00 32
E	(ØØØ5)	2Ø	1	L JMP 1
E	(ØØØ6)	(ØØ)	(ØØØØ)	•

- 1) The values in brackets need not be keyed in, but will be displayed.
- $\widehat{(13.)}$  Actuate the mode selecting key  $\boxed{R}$  (RUN) for approx. 1/2s.
  - --> Red LED "RUN" on ..PØ5 is illuminated
  - --> Green LED "RUN" on PCA15 is illuminated
  - --> Program will be run, i.e. output 32 will blink Ø.5s on and Ø.5s off (frequency 1Hz).
- 14. If the time base is to be changed to 1/100s proceed as follows: switch off the PLC, remove jumper from 1/10 and insert at 1/100. Switch the PLC on again. Push the mode selecting key R (RUN) for approx. 1/2s.
  - --> Output 32 blinks ten times faster, i.e. at 10Hz. The selection of the time base 1/100s is also evident from the higher blinking frequency of the yellow LED "CPU RUN".
- e) Example program "Blinker" with watchdog activated

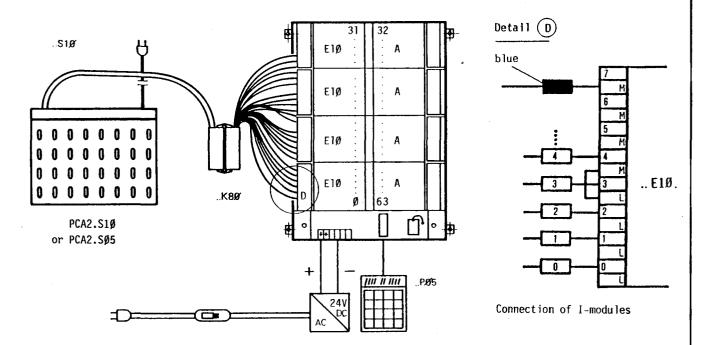
If it is desired that the watchdog function be activated for the preceding example program, the instruction COO 255 must be added to this circulating program. To ensure that this instruction is executed in every cycle independently of the blinker program, SEA must precede it. This alteration is programmed as follows:

- (15.) Actuate the mode selecting key [P] (PROG) for approx. 1/2s.
- (16.) Type in:

	_		4.3	mnemo	code
Α	5	(20)	(1)		
Ε	(ØØØ5)	19	Ø	<b>Å</b> SEA	Ø
Ε	(ØØØ6)	13	255	C00	255
Ε	(ØØØ7)	2Ø	1	└─ JMP	1
Ε	(0008)	(ØØ)	(ØØØØ)		

- $\widehat{(17.)}$  Actuate the mode selecting key  $\boxed{\mathsf{R}}$  (RUN) for approx. 1/2s.
  - --> The program will be run and the green WD lamp will light because the watchdog circuit receives a frequency of approx. 1000Hz. If an operating mode is selected other than "RUN" the WD relay will release and the green WD lamp will go out. In order to provide effective protection for the controller, terminals 5 and 6 should be wired as described in chapter A 5.4 "The watchdog monitoring circuit".
- f) Connection of the input simulation unit
  A complete programming work station is obtained by using the PCA2.S1Ø input simulation unit with a PCA1.K8Ø connecting cable; many program examples can be tested with it.

(18.



If a program starts, for example, at address  $11\emptyset$ , proceed as follows:

- 19. Actuate the mode selecting key  $\boxed{S}$  (STEP) for approx. 1/2s and type in  $\boxed{A}$  110  $\boxed{+}$
- (20.) Actuate the mode selecting key (RUN) for approx. 1/2s
  - --> Program starts to run from address  $11\emptyset$ .

Proceed similarly for all other examples.

Technical data of system series PCA14

 $\mu P = 8085.2$ , system program V6.0...

Cycle time 70μs (per program line, average)

Instruction set 32 basic instructions, 20 additional in-

structions for arithmetics, text output,

communication and parameter functions

Parameter functions - PID-loops

- Shift registers

- Check sum

- Interrupt management

Number of parallel programs 16 (PP 15 for interrupt control)

Number of index registers 16 (1 per parallel program)

Number of subroutines as desired, 3 levels per parallel program

User memory 1K, 2K, 4K or 8K program lines on EPROM,

RAM or buffered RAM memory

Text or data memory 2K, 4K or 8K character or data bytes on

EPROM, RAM or buffered RAM memory, memory extension up to 40K characters with

modules PCA1.R20/R25

Number of input and output addresses (depending on the housing size)

32, 64, 128

Max. no. of inputs + outputs (B9Ø)

56, 112, 224

Flags

712 (477 volatile 2), 235 non-volatile)

No. of timers

32 (ADD 256...287)

No. of counters or arithmetic reg.

224 (ADD 256...479) as of V6.Ø34

Counting capacity

or arithmetic registers

65 535 (216-1)

with cascading as desired

Time range

 $\emptyset.1 \ (\emptyset,\emptyset1)s...6553 \ (655)s$ 

Date-time (software) 3)

Week, day of the week, year, month, day,

hour, minute, second

Accuracy of date-time 3)

<3s/day

Serial data interface

20mA current loop, active or passive depending on cabling, for input/output of text or communication acc. to DIN 66019

Baud rate 110...9600 bauds 4)

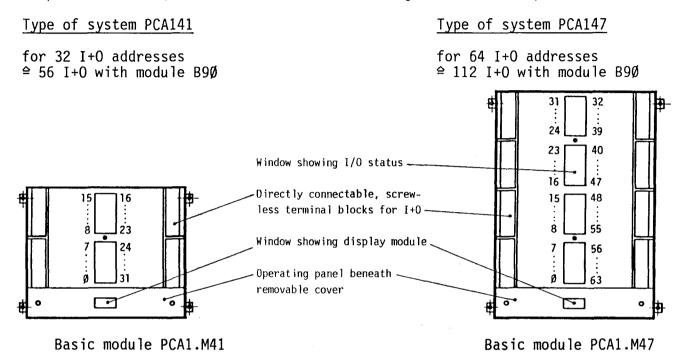
Hardware date-time see chapter PCA1.E4Ø.

<sup>1)</sup> When switching on the PLC, the system version is displayed on the programming unit P10 or P05 for one second. For this reason, the operating mode selector switch has to be in operating mode RUN. Please refer to the text for modification possibilities.

<sup>4)</sup> Owing to the high baud rates an appropriate program structure is required.

## A 3.1 Versions of system series PCA14

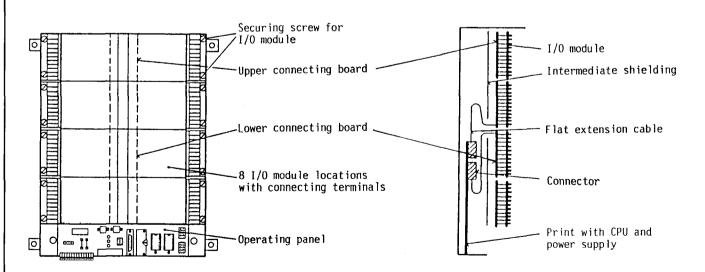
3 versions are available, corresponding to the required number of input and output addresses (PCA1.M47 and extension housing ..C45, see chapter A 4).



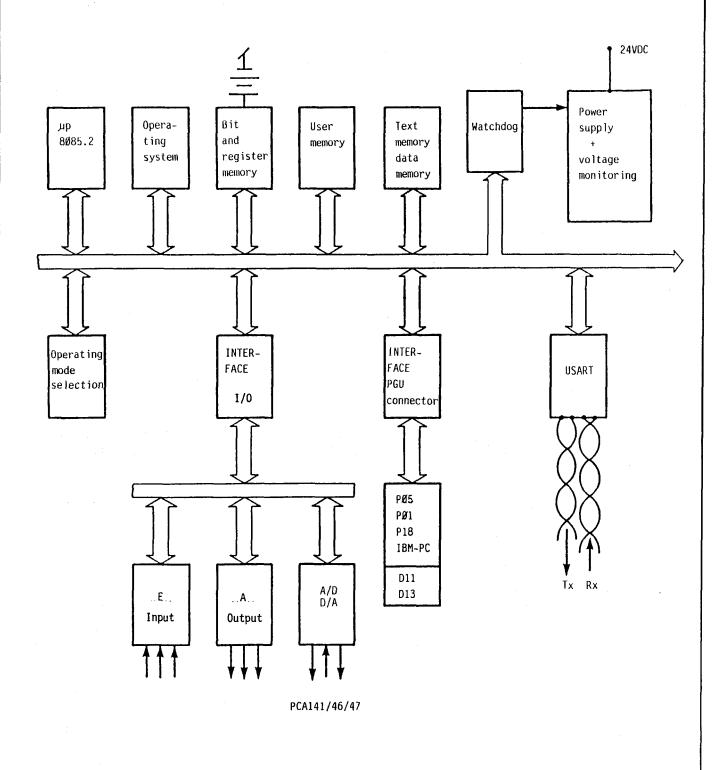
## Types PCA1.M41 and M47 basic modules

In addition to the processor (CPU), the basic module of the system series PCA14 also includes the internal power supply and the housing.

#### Presentation (type of system PCA1.M47)



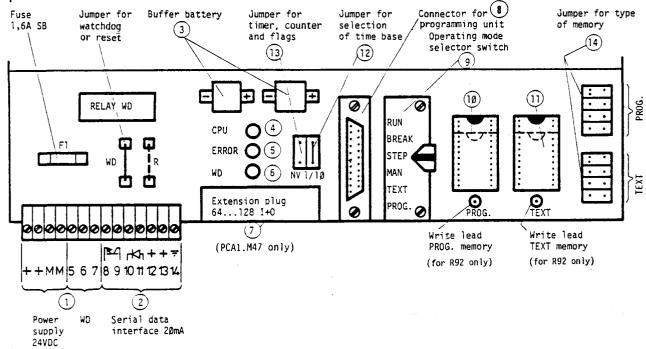
## A 3.2 Block circuit diagram PCA14



#### A 3.3 Basic modules

### A 3.3.1 Operating panel of the basic modules PCA1.M41/M47

All operating elements for the PCA14 are clearly arranged on the operating panel which can be covered.



- 1) The terminal strip is plugged onto the circuit board. Wires with diameters up to 1.5 mm² are accepted by the screw terminals.
- 2 The serial data interface is connected on the circuit board. Depending on wiring, it can be defined whether the PCA14 is active or passive at the 20mA-current loop.
- The buffer battery supplies the retentive flags, counters/timers and, if used, the 6116 or 6264 RAM chip user memory. The data is protected for approx. 2 months when the PLC is switched off. The NiCd cells last approx. 5 years. Spare battery no. 4'507'1195'0. A new version with a plug-in battery is available as of 1989 (no. 4'507'1360'0).
- The CPU monitoring lamp (yellow) blinks every 2s during normal operation. When the time-base is set to  $\emptyset.\emptyset1s$ , the blinking rate is  $\emptyset.2s$ . If the light stays on or off, there is either no power available, the PLC is in RESET mode, the CPU has a malfunction or a trap has been produced in the software sequence.
- 5) The ERROR lamp (red) indicates errors at the serial data interface. For details refer to chapter "The serial data interface" (see manual software level 2).
- 6 The watchdog monitoring lamp (red) is illuminated when the watchdog relay is excited. Please refer to chapter "The watchdog monitoring circuit" for details.
- 7 The 25-pole connector of the extension cable (only on the PCA147) allows an increase in I/O from 64 or 112 to 128 or 224 inputs/outputs owing to the connecting cable attached to the extension housing ...C45.



- 8 The 25-pole connector (PGU) is used to connect the programming unit. A latch is not provided, because the mode selected on the operating mode selector switch remains operative (unlike the PCA2) when the programming unit is removed.
- 9 The operating mode selector switch is used for starting up, trouble-shooting and editing of texts. Position "LCM" (transfer from e.g. RAM to EPROM) is not available, because this function is not possible with the PCA1; the PCA2.P16 copying unit is required.
- The two 28-pole sockets accommodate the user or text memory "PROG" or "TEXT" respectively (see chapter "Organization of program and text memory"). When inserting them, make sure that the groove points to the top. If 25-pole sockets are used (e.g. 6116, 2716, 2732A), please insert in such a way that they are flush with the lower edge of the socket. The following memory types can be used.
  - RAM chip on socket

    4 502 4512 0 (type 6116) for 1K program lines (24-pole)

    4 502 4718 0 (type 6264 or 8464) for 4K program lines (28-pole)

<u>Comment:</u> The 6116 and 6264 or 8464 RAMs allow writing, erasing and modification of a program. On power failure, the memory contents are stored by the buffer battery for approx. 2 months. The program, however, is not transportable, because the data stored is lost, if the RAM chip is removed.

Buffered RAM memory module Type PCA1.R92 for 2K program lines (24-pole) Type PCA1.R95 for 4K program lines (28-pole) See chapter B 2 Type PCA1.R96 for 4K program lines (28-pole)

User programs can be introduced on the left socket (PROG) as well as on the right socket (TEXT). Text can only be introduced on the right socket. For programming or introduction of texts please insert the write lead for the left socket on the left and that for the right socket on the right. In order to avoid program mutations interrupt both connections during continuous operation in the RUN mode.

Contrary to the 6116 or 6264 RAM chip, the program in this memory is transportable, since it is protected by an integrated circuit and a lithium battery which lasts approx. 8 years. This module is therefore particularly suitable for starting up the controller.

For copying of programs please refer to chapter "PCA2.P16 EPROM-copying unit".

<sup>1)</sup> Attention: Neither the wire lead nor the connector WR must be touched or get into contact with the ground, since otherwise changes in contents may occur.



EPROM chips on socket No. 4 502 4373 0 (type 2716) for 1K program lines (24-pole) No. 4 502 4644 0 (type 2732A) for 2K program lines (24-pole)

No. 4 502 4719 0 (type 2764) for 4K program lines (28-pole)

According to prior art, reliable operation of user programs over a period of several years is only ensured, if EPROM memories are used. The manufacturers chosen by us guarantee program safety for at least 10 years.

It is recommended to protect the window of the EPROM by means of a sticker in order to prevent the memory from being accidently subjected to UVradiation.

An extension of the text and data memory up to 40K bytes is possible by using the modules PCA2.R2Ø and R25.

(12)

The selector jumpers allow various selections:

The selection of the time base for the timers

1/10s: jumper inserted (factory

setting)

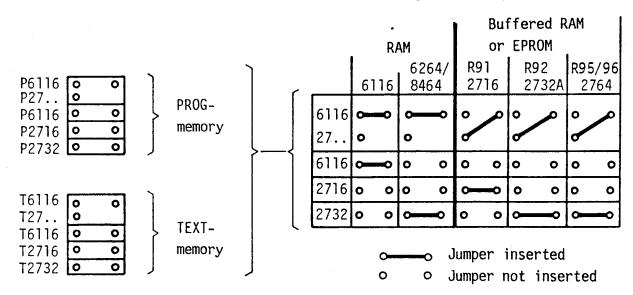
1/100s: jumper not inserted

NV 1/1Ø

The selection of the retentive flags (13)

If the jumper is inserted, all flags, timers and counter registers are retentive. If the jumper is not inserted (factory setting), only the flags 765...999 are retentive.

. The selection of the user or text memory (14) When using the various RAM or EPROM for user program or text, the jumpers have to be inserted as is shown in the following table.



Attention: Do not use any other plug combinations, as these can cause damage to the CPU!

Example: When using an EPROM 2732 for the user program (P) and a RAM 6116 for the text (T), insert the jumpers as follows:

P6116 P27.. P6116 P2716 P2732

Note:

The preselection jumpers of the PCA14 for RAM R91 or EPROM 2716 respectively are inserted (factory setting).

T6116 T27.. T6116 T2716 T2732

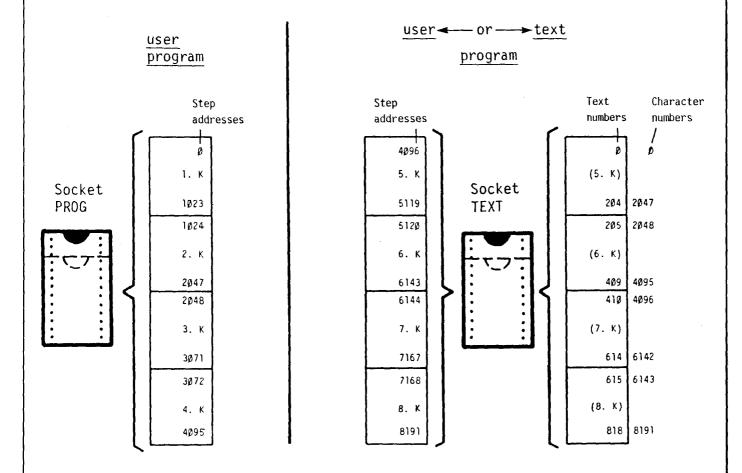
## A 3.4 Organization of program and text memory

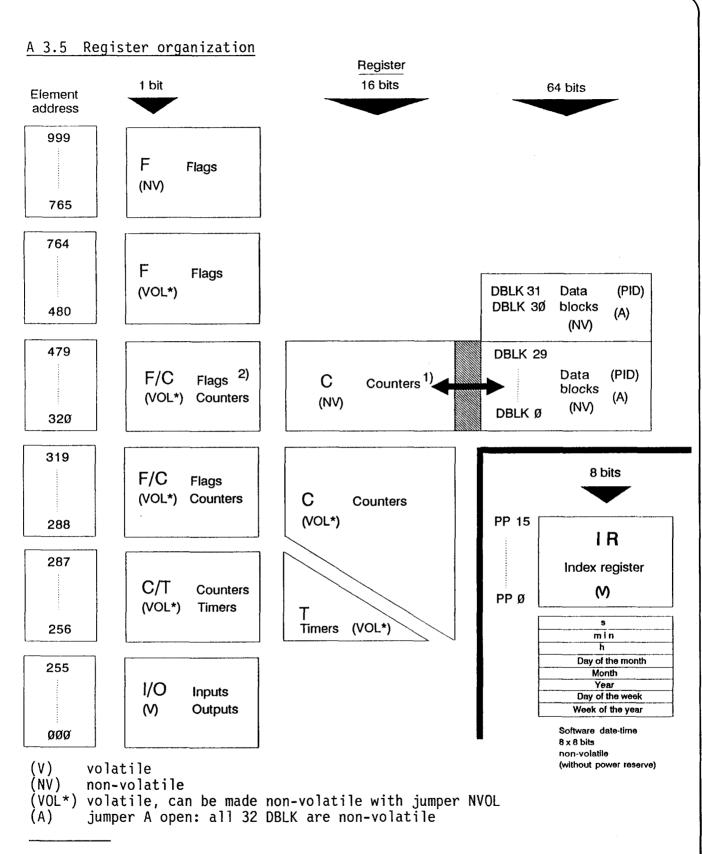
All RAM, EPROM or buffered RAM-memory modules mentioned in paragraph "28-pole socket for user memory" can be used both for user programs and texts.

User programs can have a length of up to 8K program lines (at 16 bits). With user programs having a length of more than 4K, the first 4K are stored in the PROG memory on the left (1K...4K) and up to 4K more can be stored in the TEXT memory on the right (5K...8K).

If, e.g., only 2K-memories are available and a user program of > 2K has to be prepared, the 1. and the 2.K can be stored on the left socket PROG (addresses  $\emptyset...2\emptyset47$ ) and the 3. and the 4.K on the right socket (addresses  $4\emptyset96...6143$ ).

 $\underline{\text{Texts}}$  having a length of up to 8K characters (at 8 bits) can only be stored in the TEXT memory on the right.





<sup>1)</sup> Counter registers C320...C479 and PID-data blocks 0...29 use the same memory area. It is therefore recommended to start with DBLK 31 for PID-control tasks.

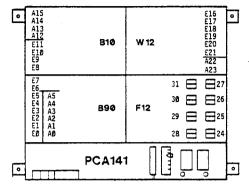
<sup>2)</sup> The counter registers  $C32\emptyset...C479$  are available from system program version  $V6.\emptyset34$  onwards.

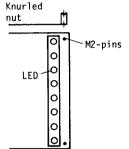
Notes:



## A 3.6 Instructions for operating a PCA14 in brief

#### a) <u>Installation of I/O modules</u>

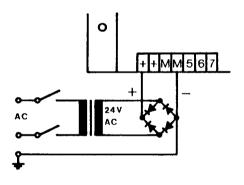




In order to test the programming examples, the I/O-equipment must be selected as evident from the accompanying figure. For a short test it suffices to install the I/O-module B9 $\emptyset$  using the address range  $\emptyset$ ...7.

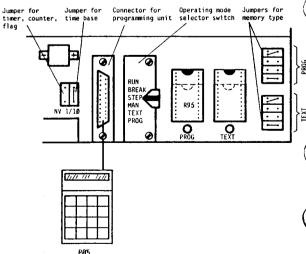
- (1.) Undo fastening screw of the cover and lift.
- 2. Center I/O-modules above the two M2-pins and carefully press them into the blade connectors.
- (3.) Tighten knurled nuts M2 and ZK-screws with tooth washers on the terminal side.
- 4. Provide the LEDs with the corresponding address labels.

## b) Power supply



- 5. Take a transformer (for "playing" 30VA is enough) with a secondary voltage of 24VAC and connect the terminals + and M of the PLC via a bridge rectifier.
- 6. A switch has the advantage that all resettable elements and the STEP-counter can easily be reset to their defined starting positions by switching off the PLC.

## c) Connection of the user memory or text memory R95 or R96 and the programming unit $P\emptyset 5$



- 7. For employment of the buffered RAM memory module R95/96 the preselection jumpers on the outer right must be inserted correspondingly (see fig.). For the following simple example (without text output) it is sufficient to use the program memory and to insert the jumpers in position "PROG" accordingly.
- (8.) The buffered RAM-module R95/96 must be inserted in the marked position notch at the top.
- 9. The programming unit PØ5 is connected to the 25-pole connector.

## d) Programming example "Blinker"

- (10.) Set operating mode selector switch to "PROG".
- Switch on power supply of the PLC. The CPU lamp (yellow) flashes 1s on, 1s off. The watchdog lamp (red) is not illuminated.
- (12.) Enter the following blinker program:

	STEP	CODE	OPERAND	Program in mnemocode
A,E E E E E E E E E E E E	(ØØØØ)* (ØØØ1) (ØØØ2) (ØØØ3) (ØØØ4) (ØØØ5) (ØØØ6) (ØØØ6) (ØØØ8) (ØØØ9)	(ØØ) Ø1 Ø4 14 ØØ 13 Ø1 1Ø 2Ø (ØØ)	(ØØØØ) 1 256 256 5 4ØØ 4ØØ 5 1 (ØØØØ)	STH E1  ANL T 256  STR T 256  Ø.5 s  COO M4ØØ  STH M4ØØ  OUT A5  JMP 1

- \*) The values in brackets do not have to be entered, but they are displayed
- (13.) Set the operating mode selector switch to "RUN". Switch PLC off and on again.
  - The program is executed. In order that output A5 flashes, a voltage of +24V must be applied to input E1. The easiest way to do this is to lead a wire from the power supply terminal + to input terminal E1. As long as this connection exists, A5 flashes at a frequency of 1Hz (if present, the jumper on the B9Ø-module must be "-" (minus)).
- 14. If the time base is to be changed to 1/100s, proceed as follows:

  Switch off PLC, remove jumper "1/10". Switch on PLC again.

  Output A5 flashes 10 times faster, i.e. at 10Hz. The selection of the time base of 1/100s is also recognizable by the higher flashing frequency of the CPU-lamp (yellow).

## e) Blinker example with watchdog activated

If in the preceding example the watchdog is to be activated, the instruction COO 255 must be added to this circulating program. In order that this instruction be executed during each cycle independently of the indicator program, it must be preceded by SEA. This is programmed as follows:

- $\widehat{ ext{15.}}$  Set operating mode selector switch to "PROG".
- (16.) Enter:

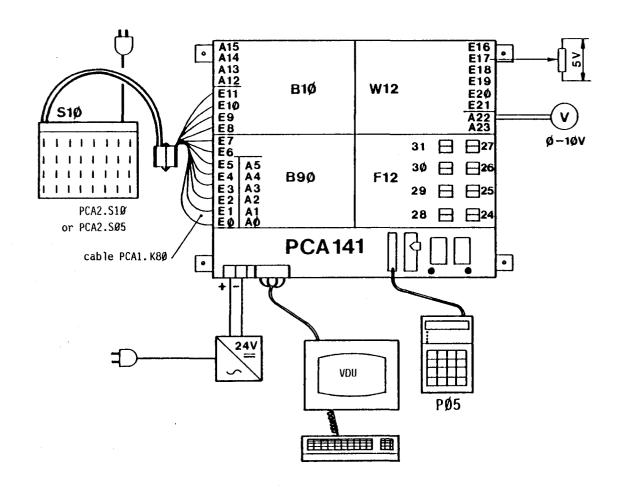
		(04)	(-)	Mnemocode	
Α	8	(2Ø)	(1)		
Ε	(ØØØ8)	19	ø	<b>Å</b> SEA	Ø
Ε	(ØØØ9)	13	255	C00	255
E	(ØØ1Ø)	2Ø	1	L JMP	1
Ε	(ØØ11)	$(\emptyset\emptyset)$	(ØØØØ)		

17. Set operating mode selector to "RUN" again.

The program is executed, the red WD-lamp is illuminated, as the WD-circuit receives a frequency of approx. 700Hz. If the operating mode selector switch is set to any other position than "RUN", the WD-relay is released, the red WD-lamp goes out. In order to provide effective WD-protection for the controller, the connectors 5 and 6 and the power supply line must be wired accordingly.

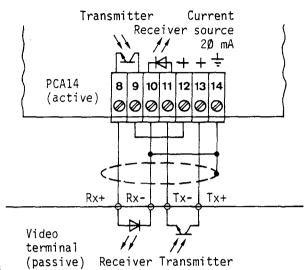
## f) Connection of the input simulation unit PCA2.S1Ø

(18.) The input simulation unit, further modules, a variable DC-voltage of  $\emptyset...5V$  as well as a voltmeter  $\emptyset...1\emptyset VDC$  ( $1\emptyset k\Omega$ ) and a video terminal with a  $2\emptyset mA$ -data input (or with an adapter  $2\emptyset mA$ /(RS232c) form a complete program developing and simulation unit for the following programming examples.



The above configuration corresponds to the simulation case V-PCX8.

- g) <u>Installation of the 20mA-serial data interface with a video terminal</u> for text input and output
- g1) Establishing the cable connection PCA14 <---> video terminal



It must be provided that the video terminal is fitted with a 20mA-current loop interface for full-duplex operation (or a suitable adapter 20mA/RS 232c).

19. The cable connection (max. length of 100m) can be established according to the accompanying figure. The terminal must be "passive", i.e. the 20mA are supplied by the PCA14.

- g2) Installation of the text memory module
  - 20. The RAM-memory module R95/96 is inserted to the right of the user memory for the storage of texts. The jumpers are preselected according to chapter point (7.) of this chapter.
- g3) Selection of the communication parameters

They are defined according to chapter "Activation of the interface via the software ...".

21. Assumed values for setting the video terminal:

Most of the following values can be preselected via the DIL-switches.

If a switch or a key for "Full Duplex" is available, it should be locked in position (for details refer to the manual of the video terminal).

Communication parameters for PAS 100 (assumed)

. Baud rate	48ØØ	6
. Data bits	7	Ø
. Parity	yes	128
. Even	yes	256
. Stop-bit	1	<u>512</u>
Total		9ø2

This value must be added in line 2 of the 10-line assignment instruction PAS 100.

- g4) Activation of the PCA14 data interface as editor and for checking the text output
  - 22. The PAS 100-instruction for activating the editor and test output of the text just edited is given at the end of the user memory e.g. at address 4001.

4001 4002 4003 4004 4005 4006 • •	PAS	29 Ø1 ØØ ØØ ØØ ØØ	100 902 12 254 254 0	Transmission parameters (4800 bauds etc.) 01 for text editor, A12 for Text Busy The higher address of 2 elements permanently remain "L", e.g. elements 254 and 253
4Ø11 4Ø12	PAS	29 ØØ	23 \ 3Ø }	Text output from text no. 3Ø on
4013	JMP	2Ø ØØ	9 4Ø11	(Ø1 1963)

## g5) Enter a text into the text memory

- 23. Set operating mode selector switch to "STEP".
- 24. By pressing  $\boxed{\text{A}}$  4001  $\boxed{\text{+}}$  on the P05 input unit jump to the beginning of the assignment.
- 25. By pressing + execute assignment up to 4011.
- 26. Type in  $\emptyset3\emptyset$  "CR" on the VDU terminal.

<u>Ø3Ø "CR"</u>	The displayed text is random in case of an uncleared text memory. A point <u>preceding</u> a character means that this character is part of the visible section of the ASCII-table (32127). Control in-
Ø3Ø:.A.B ^@^@^@^@ Ø3Ø:	structions from the "control case" are preceded by an arrow or a ^.

## Display on the screen

27. To activate the text input mode, press keys CTRL and T (CTRL/T) simultaneously.

28. Then enter 5 spaces using the special character \$\infty\$, the followed by the

character \$, the followed by the SAIA°PLC logo.

031:.P.L.C^M^J.C.R.O.W.N — 29. Note that as soon as 10 characters have been entered, the screen automatically proceeds to the following text number.

- 30. To enter "CR" without changing the text mode, must be pressed first. The CPU answers with ^M (CTRL/M = "CR").

31. To enter "LF" = Line Feed, CTRL/J is pressed which corresponds to "LP" ^J appears.

32. NUL is entered to end text input. This is possible via <a href="CTRL/@">CTRL/@</a> (may differ from one peripheral unit to another).

33. To exit from the editor mode enter "CR".

## g6) Output of this text

033:.A.1.4^M^J^@^@^@^@^@

033:

34. With + + on the PØ5 unit the program loop 4Ø11 to 4Ø14 is executed once, as a result of which the text is output.

SAIA°PLC CROWNED WITH PCA14

After this sample text has been input/output successfully, the programming examples in the "Software" manual can be entered and tested.

- g4) Activation of the PCA14 data interface as editor and for checking the text output
  - 22. The PAS 100-instruction for activating the editor and test output of the text just edited is given at the end of the user memory e.g. at address 4001.

4001 4002 4003 4004 4005 4006 • •	PAS	29 Ø1 ØØ ØØ ØØ ØØ	100 902 12 254 254 0	Transmission parameters (4800 bauds etc.) 01 for text editor, A12 for Text Busy The higher address of 2 elements permanently remain "L", e.g. elements 254 and 253 NUL
4Ø11 4Ø12 4Ø13	PAS JMP	29 ØØ 2Ø	23 3Ø }	Text output from text no. 3Ø on
4013	UMP	ØØ	4Ø11	(Ø1 1963)

# g5) Enter a text into the text memory

- 23. Set operating mode selector switch to "STEP".
- 24. By pressing  $\boxed{\text{A}}$  4001  $\boxed{\text{+}}$  on the P05 input unit jump to the beginning of the assignment.
- 25. By pressing + execute assignment up to 4011.
- 26. Type in  $\emptyset 3 \emptyset$  "CR" on the VDU terminal.

<u>Ø3Ø "CR"</u>	The displayed text is random in case of an uncleared text memory. A point preceding a character means that this character is part of the visible section of the ASCII-table (32127). Control in-
Ø3Ø:.A.B ^@^@^@^@ Ø3Ø:	structions from the "control case" are preceded by an arrow or a ^.

#### Display on the screen

\_\_\_\_\_27. To ac<u>tivate</u> the <u>tex</u>t input mode, press CTRL/T keys CTRL and T (CTRL/T) simultaneously. - 28. Then enter <u>5</u> spaces using the special character \$ , the followed by the 030: \$. .0.0.5.S.A.I.A.-SAIA°PLC logo. 031:.P.L.C^M^J.C.R.O.W.N —— 29. Note that as soon as 10 characters have been entered, the screen automatically 032:.E.D. .W.I.T.H. .P.C proceeds to the following text number. 032: - 30. To enter "CR" without changing the text 033: A.1.4^M^J^a^a^a^a^a mode, must be pressed first. The CPU answers with  $^M$  (CTRL/M = "CR"). --- 31. To enter "LF" = Line Feed, CTRL/J is pressed which corresponds to "LP" ^J appears. - 32. NUL is entered to end text input. This is possible via CTRL/@ (may differ from one peripheral unit to another).

33. To exit from the editor mode enter "CR".

# g6) Output of this text

34. With + + on the PØ5 unit the program loop 4Ø11 to 4Ø14 is executed once, as a result of which the text is output.

SAIA°PLC CROWNED WITH PCA14

After this sample text has been input/output successfully, the programming examples in the "Software" manual can be entered and tested.

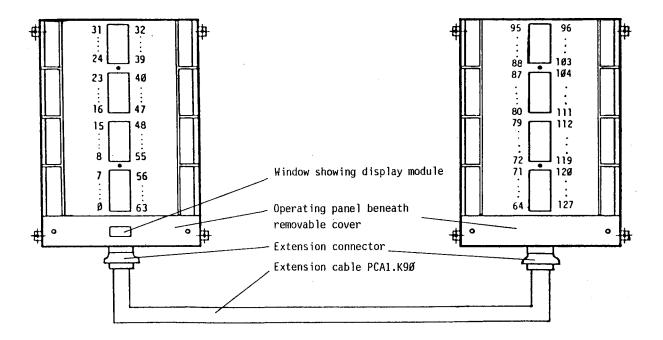
# A 4 Extension housing ... C45

# A 4.1 Basic module PCA1.M57/M47 with extension housing PCA1.C45

In addition to the entire circuitry of the PCA1.M47/M57, the basic module PCA1.M56 also contains the switching circuits and the connector for connection to the extension housing.

The extension housing PCA1.C45 is connected via the connecting cable PCA1.K90. It also has a power supply unit of its own.

# A 4.2 Type of system PCA157/147 with extension housing PCA1.C45 128 I+O addresses, 224 I+O with compact module PCA1.B9Ø

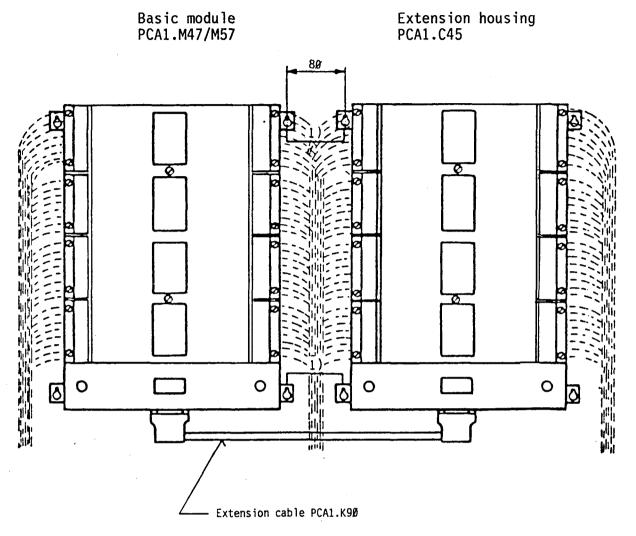


Basic module PCA1.M57 or PCA1.M47

Extension housing PCA1.C45

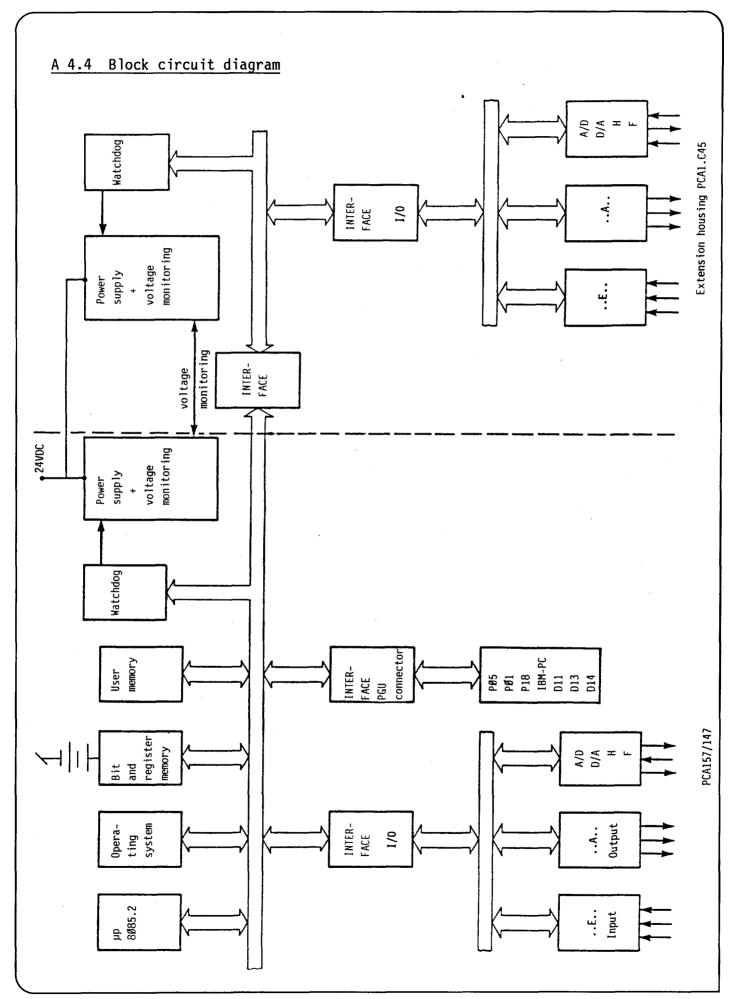
The three versions are completely compatible as regards hardware and software and can be equipped with all the old and new I/O modules of the series PCA1.

# A 4.3 Arrangement of the PCA157/147 with extension housing ..C45



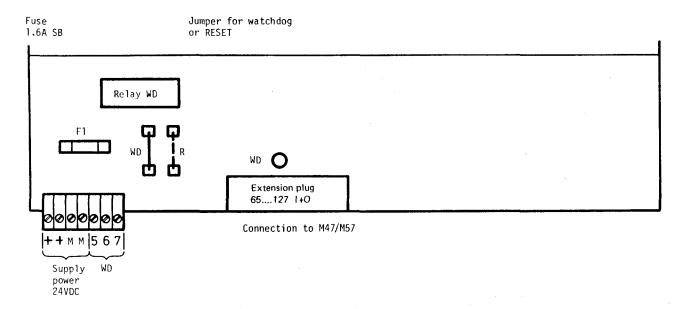
1) There has to be a good metallic bond between both housings.

The extension cable PCA1.K90 is screened so that the I/O wiring and other lines can be laid above this cable.



# A 4.5 Operating panel of extension housing ..C45

As with PCA157/147, all operating elements for extension housing ..C45 are logically arranged on the operating panel which can be covered.



The operating elements described here have the same functions as those of the PCA1 (see chapter "Operating panel").

# A 5 Power supply, watchdog, reset, dimensions

#### A 5.1 Power supply of PCA1

Supply voltage  $V_{in}$  24VDC, smoothed or pulsating

Voltage tolerance normally ±20% (see following page for details)

Supply current max. 1A for basic modules and ..C45

Output voltages to 24VDC, smoothed, for internal output driver

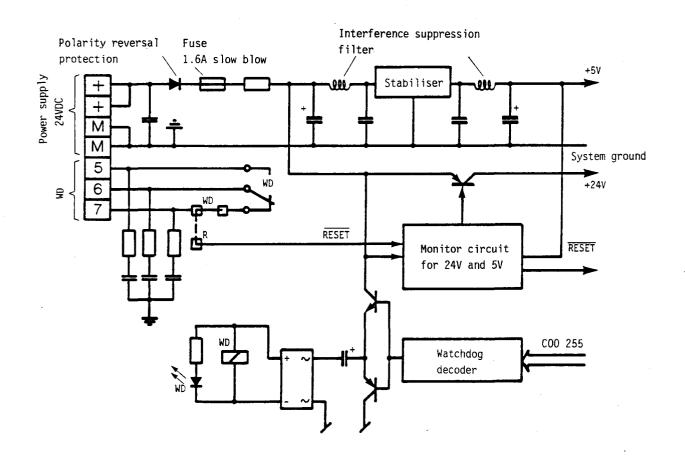
electronics 5VDC, stabilised ±3%, for remaining electronics

Output current 5V 1.1A

Ambient temperature Ta  $\emptyset...50^{\circ}$ C (see following page for details)

As indicated on the following page, the PCA15 can be operated with pulsating (P) or smoothed (G) direct current. It may also be connected to the same power supply available for the sensors and actuators. Several components protect the PLC against interference voltages, polarity reversal and low voltages. The 5VDC for supply of the electronic components is generated by a stabiliser.

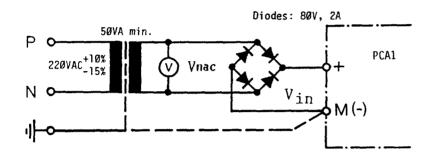
# Block circuit diagram for PCA1 and extension housing ..C45



# A 5.2 Various external power supply circuits

In order to provide the PCA1 and the extension housing ...C45 with the reasonably priced power supplies, a stabiliser has been included in the power section of the PCA1 and the extension housing ...C45, in addition to interference and polarity reversal protection. In case of PCA1.A2.. output modules, this smoothed 24VDC is used for the internal excitation of the relays. One differentiates between two types of power supply, "P" and "G".

P Power supply with pulsating DC from a transformer with a bridge rectifier



The following information is based on the assumption that the mains supply and therefore the secondary voltage will vary +10/-15%; the AC voltages are based on 220VAC primary.

P1

Without relay output modules
Secondary alternating voltage  $V_{\text{nac}}$ : 22...24.5VAC ( $T_{\text{a}} = \emptyset...5\emptyset^{\circ}\text{C}$ ) (complete range incl. primary voltage fluctuations of +10/-15%:

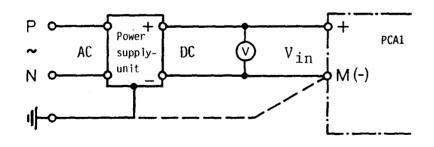
18.7...27VAC).

P2

With max. 4 relay output modules PCA1.A2.. Secondary alternating voltage  $\frac{V_{\text{nac}}}{V_{\text{nac}}}$ :  $\frac{24\text{VAC}}{V_{\text{nac}}}$  (T<sub>a</sub> =  $\emptyset$ ...50°C) (complete range incl. primary voltage fluctuations of +10/-15%: 20.4...26.4VAC)

P optimal For all combinations  $V_{nac}$ : 24VAC

G Power supply with smoothed DC from power supply unit



It is assumed that the external power supply will not only smoothen but will also stabilise the DC voltage.

G1

Without relay output modules

Direct voltage range  $V_{in}$ :  $2\emptyset$ ...32VDC ( $T_a = \emptyset$ ...5 $\emptyset$ °C)

G2

With max. 4 relay output modules PCA1.A2..

Direct voltage range  $V_{in}$ : 24...30VDC ( $T_a = \emptyset...50^{\circ}$ C) Direct voltage range  $V_{in}$ : 22...32VDC ( $T_a = \emptyset...35^{\circ}$ C)

G optimal For all combinations Vin: 26VDC

# A 5.3 Voltage monitoring

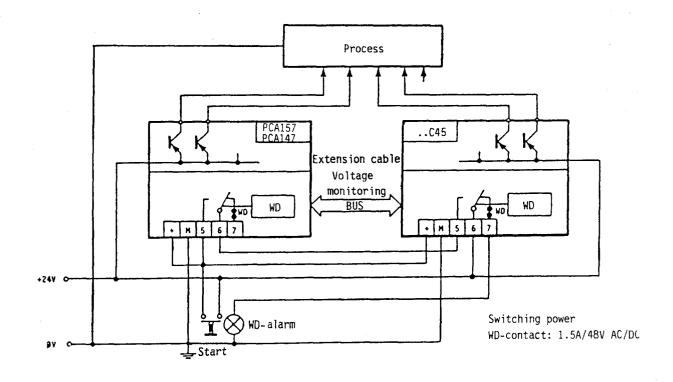
Both the supply voltage  $V_{\text{in}}$  and the 5V of the PCA1 and the extension housing the CPU is set in RESET mode, i.e. all volatile flags as well as all outputs are reset. When the input voltage is switched on (or switched on again), the CPU is cleared for operation after 100ms. This delay allows safe resetting of all outputs and provides a clearly defined starting position for program execution.

# A 5.4 Watchdog monitoring circuit

Both the PCA15/14 and the housing ..C45 incorporate this circuit. The two watchdog circuits of the PCA157/147 and the extension housing ..C45 are connected with an extension cable. Via the watchdog circuit, correct user program execution can be monitored reliably and, if a malfunction occurs, effective safety measures can be taken.

The watchdog relay remains excited (contact 5 and 6 closed) as long as address 255 receives a square-wave signal of  $\geq$  5Hz. This signal is generated easily with the COO 255 instruction in a circulating monitoring program. Terminals 5 and 6 remain connected (refer to the block circuit diagram for "Power supply") as long as the CPU functions properly in the RUN mode. If a malfunction occurs in the CPU or if any operating mode but RUN is selected, contact 5 and opens and the WD warning lamp is illuminated.

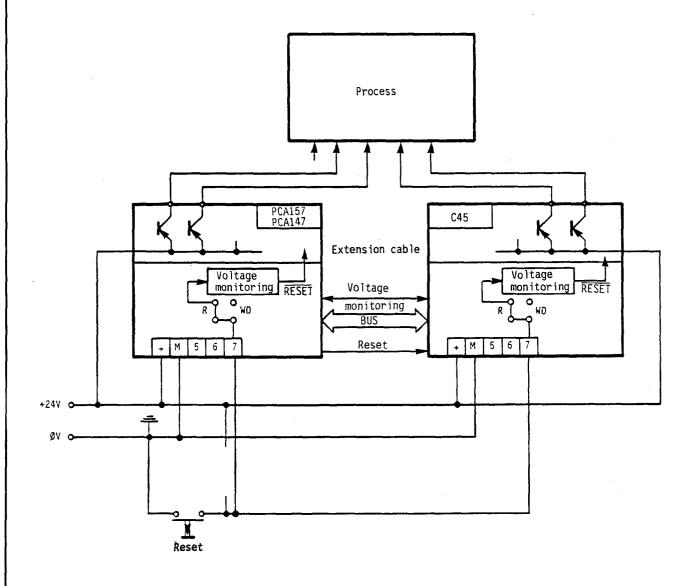
The following safety circuit is recommended (factory setting of watchdog jumper(s)), where the WD-contact 5 interrupts the power supply of the PLC (as well as of the extension housing ..C45) in case of drop of a WD-relay. The CPU provides resetting of the outputs. The breaking capacity of WD-contacts 5, 6 and 7 is 1.5A, 48VAC or DC. The WD-contact is therefore not to be used for direct switching of the total output current.



# A 5.5 Fast external RESET circuit

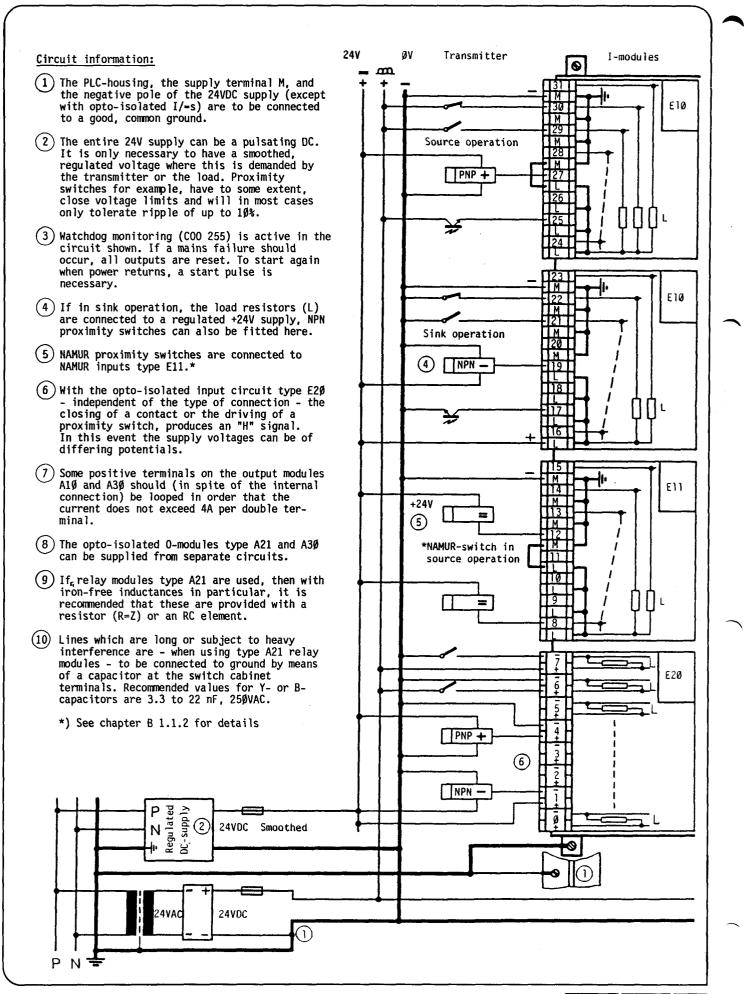
The watchdog monitoring circuit is in any case recommended as a safety measure. As an alternative, the external reset can be used for an extremely fast resetting of the microprocessor and all the outputs.

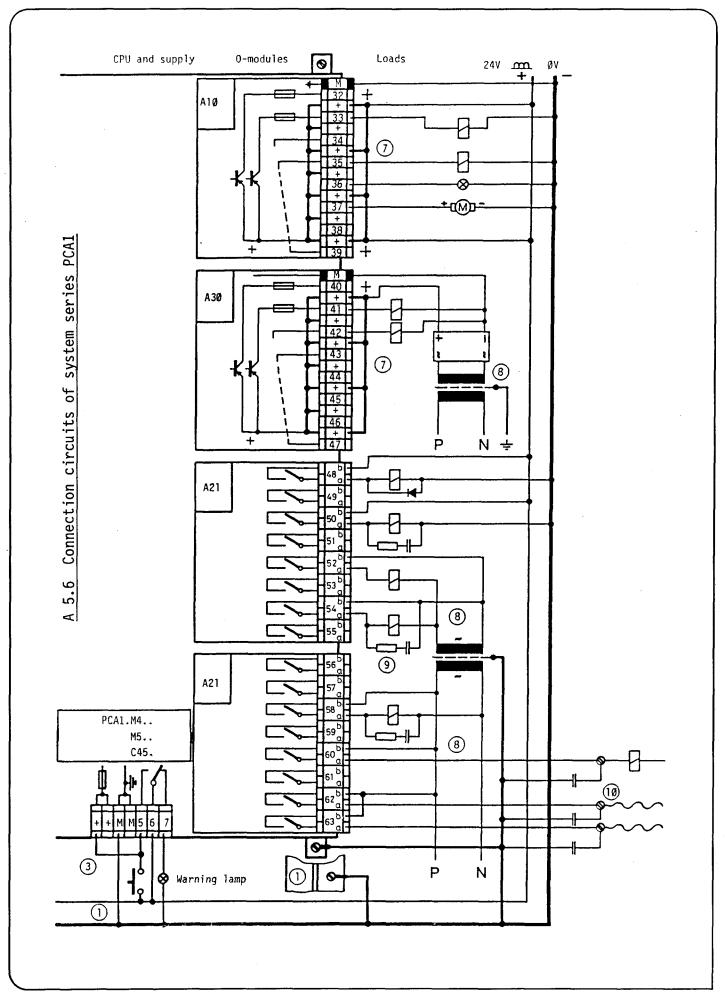
Terminal 7 can be connected to the RESET circuit (instead of being connected to the WD-contact) by moving the jumper from WD to RESET. After applying the ground potential (M) at terminal 7, all the outputs are reset within 2ms. They remain reset for at least 100ms. If a RESET signal is applied over a longer time, the outputs remain reset for t +25ms. Apart from the outputs, all the other volatile (non-retentive) registers are reset.



Notes:







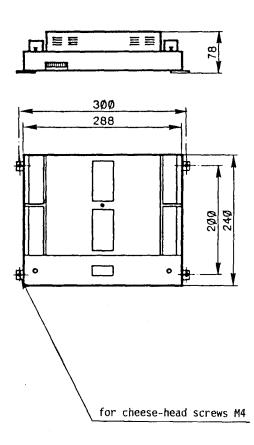
# A 5.7 Dimensions of system series PCA1

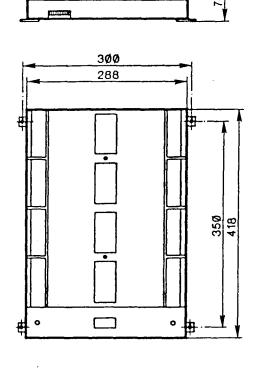
Small housing for 4 I/O modules

max. 32 or 56 I+0

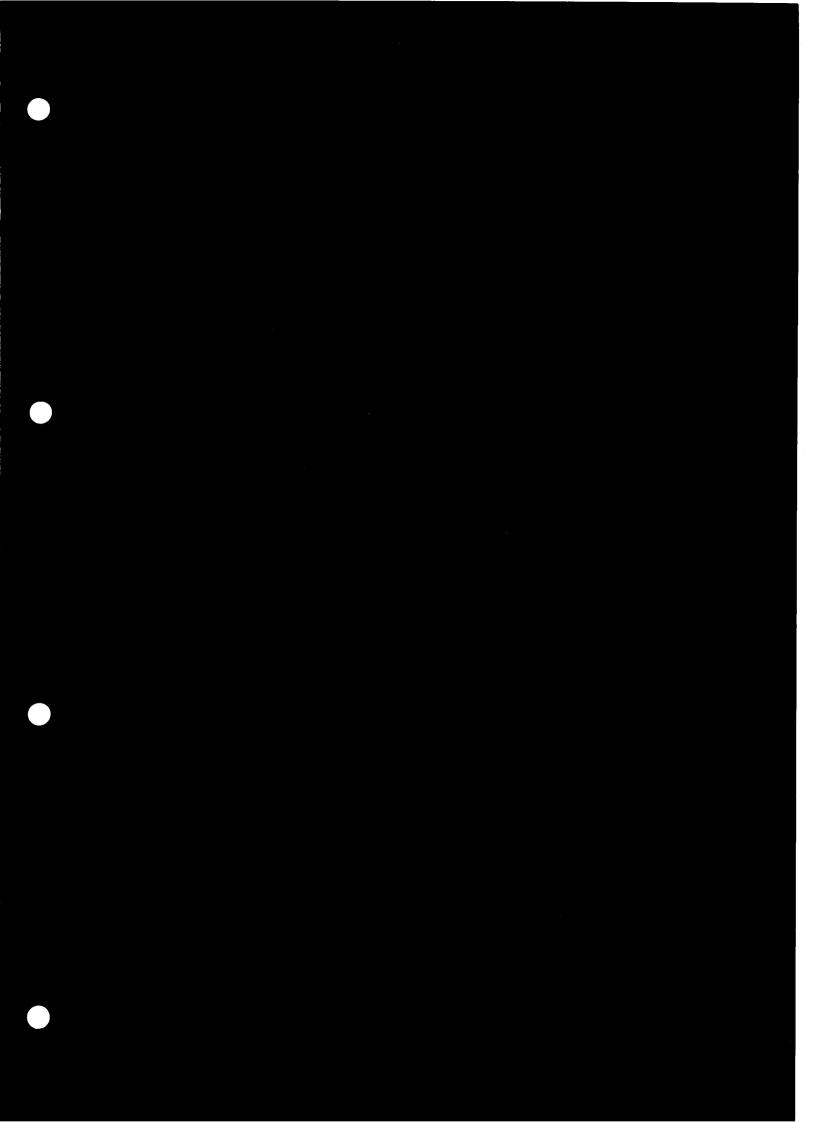
Large housing for 8 I/O modules

max. 64 or 112 I+0





System type	Basic module, CPU incl. housing	System type	Basic module, CPU incl. housing
PCA141 PCA151	PCA1.M41 PCA1.M51	PCA147 PCA156 PCA157	PCA1.M47 PCA1.M56 PCA1.M57 + PCA1.C45



Part B Input/output modules as well as additional and display modules

Chapter B 1 Plug-in input/output modules (pluggable onto basic modules)

Chapter B 2 Programming units, additional units and accessories

# B 1 Plug-in input/output modules

#### B 1.1 I+O modules of series PCA1

- Modules with 8 digital inputs

PCA1.E10 - electrically connected, 24V- smoothed or pulsating, Input current: 10mA

PCA1.E11 - for NAMUR proximity switch, 24V- smoothed Input current: Ø...6mA

PCA1.E2Ø - opto-isolated, 24V- smoothed or pulsating, Input current: 12mA

PCA1.E5Ø - 11Ø...24ØVAC, opto-isolated Input current: 1ØmA, 22ØVAC

- Modules with 8 digital outputs

PCA1.A1Ø - 5...36VDC electrically connected, 1(2)A, positive switching

PCA1.A21 - 25ØVAC/3A, opto-isolated, output with relay contacts

PCA1.A3Ø - 5...36VDC, opto-isolated, 1(2)A, positive switching

PCA1.A50 - 24...240VAC/1A opto-isolated, Triac

- Combined digital input/output modules

PCA1.B10 - 4 inputs 24VDC smoothed or pulsating, electrically connected, 4 outputs 24VDC, 1(2)A electrically connected, positive switching

PCA1.B8Ø - 8 inputs, 24VDC smoothed or pulsating, electrically connected 6 outputs, 8...32VDC, 5mA...Ø.5A positive switching, smoothed and short-circuit protected

PCA1.B9Ø - 8 inputs 24VDC smoothed or pulsating, electrically connected, 6 outputs 24VDC, Ø.5A electrically connected, positive switching

- Combined date-time and input module

PCA1.E4Ø - Date-time with power reserve
7 digital inputs 24VDC smoothed or pulsating,
electrically connected
Input current: 10mA

- Analog input/output modules
  - PCA1.W1.. 6 input channels of 8 bits each, Ø...5V (Ø...1ØV bzw. Ø...2ØmA) electrically connected Ø...2 output channels of 7 bits each, Ø...1ØV (Ø...2.56V) electrically connected
  - PCA1.W2.. 2 or 4 analog output channels of 12 bits  $\emptyset...1\emptyset V$  ( $\emptyset...5V$ , -5...5V,  $-1\emptyset...1\emptyset V$ )
  - PCA1.W3.. 4 input channels of 12 bits  $(\emptyset...1\emptyset V, -5...5V, -1\emptyset...1\emptyset V)$   $\emptyset$  or 2 output channels of 12 bits  $\emptyset...1\emptyset V$   $(\emptyset...5V, -5...5V, -1\emptyset...1\emptyset V)$
  - PCA1.W4Ø 6 input channels of 8 bits for PT 100 temperature sensor for sensors with 2, 3 or 4 conductors
- Preselector modules for input of numerical values
  - PCA1.F11 for direct selection of 4 two-digit BCD-preselector switches
  - PCA1.F12 for direct selection of 8 two-digit BCD-preselector switches
- Data line switching module with conversion 20mA/RS 232c
  - PCA1.F21 for 1 interface with conversion 20mA/RS 232c
  - PCA1.F22 for 2 interfaces with conversion 20mA/RS 232c
- Counter module up to 10kHz
  - PCA1.H1.. Counter, frequency generator and frequency measurement
- Internal power consumption of the PCA1 modules

# B 1.1.1 Type PCA1.E1Ø Electrically connected input module

#### Technical data

Number of inputs per module

8, electrically connected

Input voltage Vin

24VDC, smoothed or pulsating

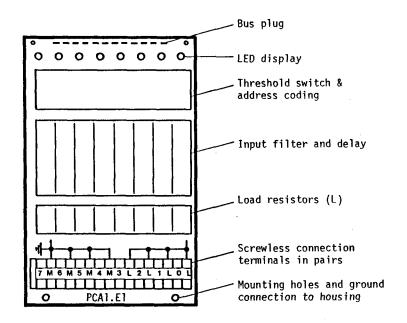
Input current at 24VDC

1ØmA

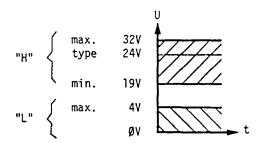
Input delay (typical)

8ms

# Presentation and terminal layout



# <u>Definition of input voltages</u>



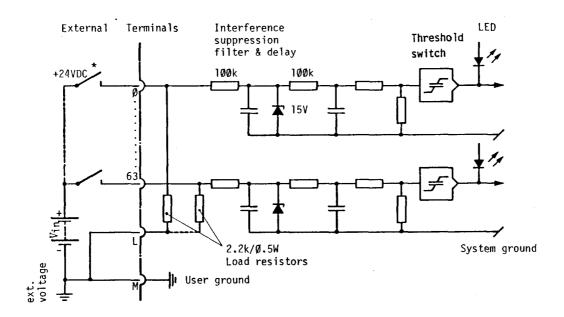
Because of the input delay of 8ms, pulsating DC is adequate as external supply voltage.

Connection terminals for the I+O modules: By depressing the grey rib with a screwdriver, the screwless terminal is opened for one wire of max. 1.5mm². Two terminals for the same connection are located opposite one another to facilitate installation of jumpers when needed. Plug-in connectors on request.

# Input circuit

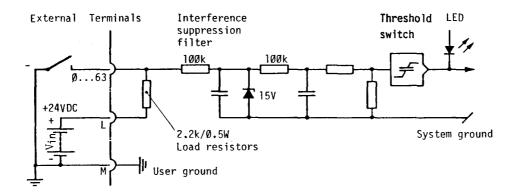
This module can be used either in source or sink operation, depending on the external circuitry.

Source operation or positive logic (normal case):



\*) PCA1.E1Ø is also suitable for NAMUR proximity switches which can carry a current of 10mA at 24VDC and 2.2k $\Omega$ .

# Sink operation or negative logic:



Switch closed (negative at input): "L" 

LED OFF
Switch open (positive at input): "H" 

LED ON

# B 1.1.2 Type PCA1.E11 Input module for NAMUR proximity switches

On the basis of the object distance NAMUR proximity switches give a current of  $\emptyset...6$ mA. To take these special conditions into consideration, two resistors are changed per input in the NAMUR version as opposed to the standard PCA1.E1 $\emptyset$ .

#### Technical data

Number of inputs per module

8, electrically connected

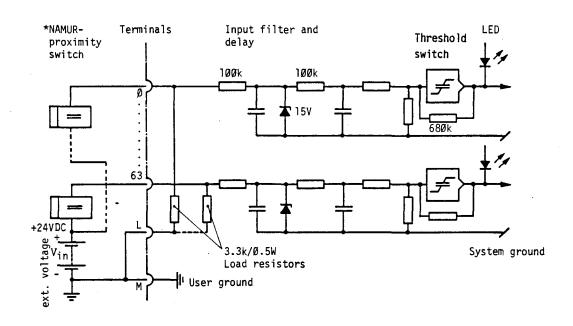
Voltage source in series with NAMUR proximity switches V<sub>in</sub>

24VDC smoothed

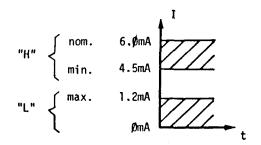
Input delay (typical)

8ms

#### Input circuit



# Definition of input current



"H": LED <u>ON</u> = proximity switch de-energized

"L": LED  $\underline{OFF}$  = proximity switch  $\underline{energized}$ 

<sup>\*)</sup> PCA1.E11 is suitable for NAMUR proximity switches which can carry a current of 6mA at 24VDC and  $3.3k\Omega$ .

# B 1.1.3 Type PCA1.E2Ø Opto-isolated input module

# Technical data

Number of inputs per module

8, electrically isolated between

process, CPU and mutually

Input voltage Vin

24VDC, smoothed or pulsating

Input current at 24VDC

12mA

Input delay (typical)

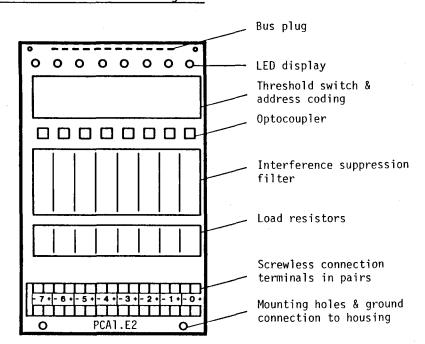
7ms

Dielectric strength of

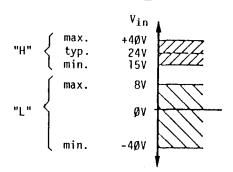
optocouplers

min. 2000V

# Presentation and terminal layout



# Definition of input voltage Vin

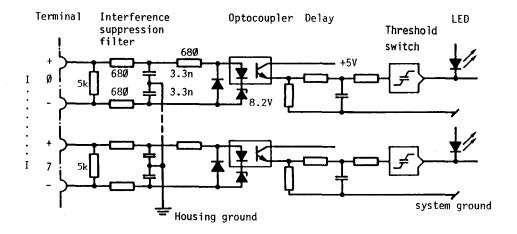


# Input circuit operating modes

Pulsating DC is adequate as supply voltage because of 7ms input delay.

The LED lights in both cases when the input contact is closed.

# Input circuit



"H" \( \text{LED ON} \( \text{\text{\$\}}\$}}}}}}}}} \endotinitiles \end{tikle}}}} \end{times}} \end{tikle}}}} \end{times}}} \end{tikles}}} \end{tikles}}} \end{tikles}}} \end{tikles}}} \end{tikles}}} \end{tikles}}} \end{tikles}}} \end{tikles}}} \end{tikles}}} \end{tinput}}}} \end{tikles}}} \end{tikles}}

# B 1.1.4 Type PCA1.E5Ø Opto-isolated input module for VAC

# Technical data

Number of inputs per module

8, galvanically isolated

Input voltage range

95...280VAC eff. (110...240VAC nom.)

Input voltage at 220VAC

1ØmA

Overvoltage max.

15ØØV/1Øμs 5ØØV/ 3ms

Input delay (typical)

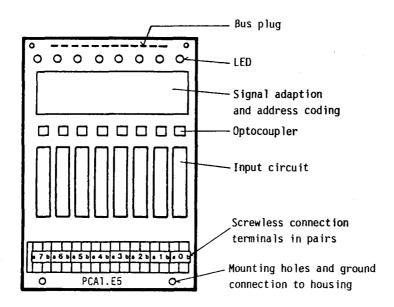
typ. 15ms

Isolation voltage of optocoupler

25ØØV eff.

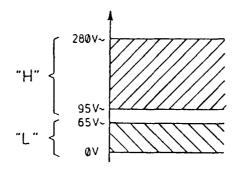
Isolation resistance of optocoupler  $100M\Omega$ 

# Presentation and terminal layout

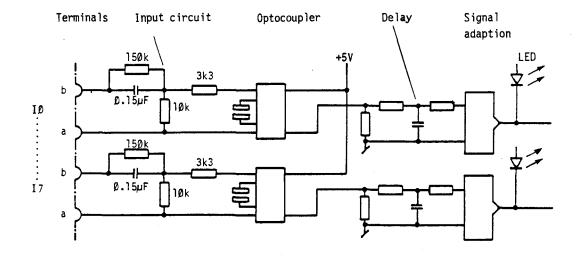


For opto-isolation very long lasting (>100'000h) optocouplers are used. This results from the use of threshold switches in the diode circuit of the optocoupler.

# Definition of input voltage



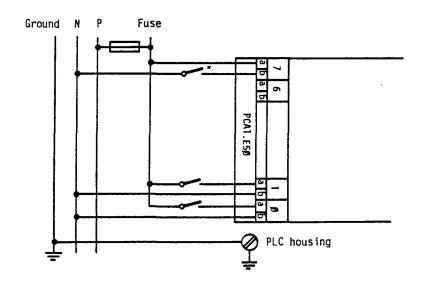
# Input circuit



#### Warning

For reasons of protection of data transmission lines, displays and user input elements use low voltage material when connecting low voltage on the PLC.

All connections of an E5Ø-module are to be connected on the same circuit; that means at one point in such a way that they are all protected against  $\underline{one}$  AC-phase by  $\underline{one}$  fuse.



<sup>\*)</sup> The neutral conductor is only to be interrupted if local regulations are not violated.



# B 1.1.5 Type PCA1.A1Ø Electrically connected output module for 1(2)A

#### Technical data

Number of outputs per module

8, electrically connected

Output current

5mA - 1A (2A)\*

When operated at 5...25VDC, the load resistance should be at least  $24\Omega$ .

Short-circuit protection

1.6A guick-acting fuse

Operating mode

Source operating positive switching

Total current

See diagram

Voltage range Vout

5...36VDC, smoothed or pulsating

Voltage drop

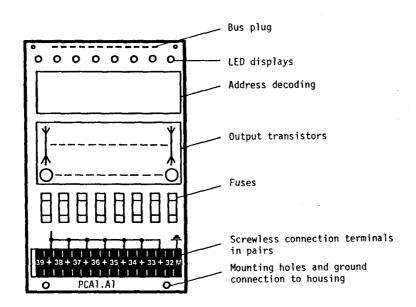
max. 1.5V at I = 1A

Output delay (typical)

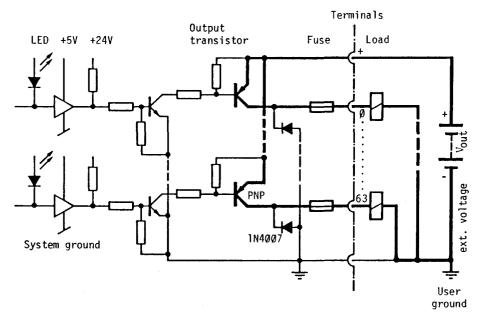
 $10\mu s$  (With an inductive load, the turn-off delay is greater due to the protective diode.)

\* Two outputs per module can carry a load of 2A each if the total current does not exceed that shown in the diagram. For such outputs, a quick-acting 2.5A fuse should be used. Please note however, that the voltage drop at the terminals is approx. 2.5V with a load of 2A.

# Presentation and terminal layout

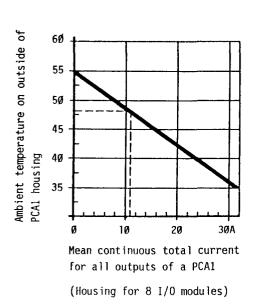


# Output circuit



Output conducting (set) 
□ LED ON
Output non-conductive (reset) □ LED OFF

Max. permissible total current for complete PCA1 (housing for 8 I/O modules)
The average (thermal) continuous total current is relevant.



Example: 4Ø outputs assigned Vout = 24V	I mean
8 multiplex outputs at 10mA (10%ED)	Ø.Ø1A
6 display lamps at 2W (100%ED)	Ø.5ØA
16 valves at 24W (4Ø%ED)	6.4ØA
2 valves at 48W (25%ED)	1.ØØA
8 control relays at 8W (100%ED)	2.7ØA
Mean total current	1Ø.61A
Permissible ambient temperature	48°C

# Note:

In spite of the internal loops of the positive, several terminals are to be used since the current is not to exceed 4A per double terminal.

# B 1.1.6 Type PCA1.A21 Output module with relay contacts

# Technical data

Number of outputs per module

8, galvanically isolated normally-open contacts

Power rating

3A, 25ØVAC AC1 1A, 25ØVAC AC11 (3A, 24VDC DC1)\* (1A, 24VDC DC11)\*

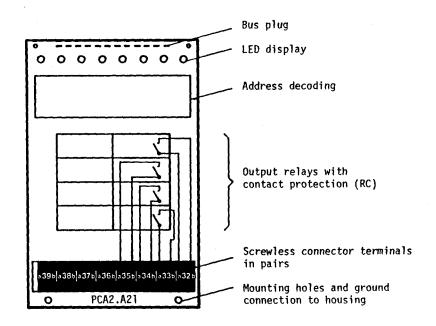
Contact protection

3.3nF mit  $33\Omega$ 

Contact life (AC1)

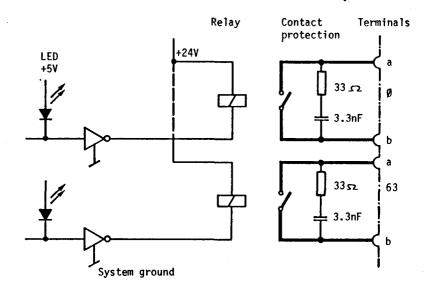
3A, 220VAC Ø.1 mio. switching cycles 1.5A, 220VAC Ø.5 mio. switching cycles Ø.3A, 220VAC 5 mio. switching cycles

# Presentation and terminal layout



<sup>\*)</sup> Transistor outputs A10 or A30 should be used when switching DC for reasons associated with contact life and to ensure positive switching.

# Output circuit



# **Important**

For safety reasons however, it is recommended that extra-low voltages (up to 50V) and low voltages (51 to 250V) should not be used on the same card, or that one channel should be left unused between them.

If highly inductive, 220VAC loads are to be switched (e.g. control relays or valves), it is recommended that an additional spark protection be connected across the load or the contact. Thus, arcing to the coil circuit can be prevented successfully. The following values are recommended:

R 
$$(\Omega) \approx \text{load Z }(\Omega)$$
  
C  $(\mu F) \approx \text{current }(A)$ 

For DC-voltages the transistor output modules are recommended.

# B 1.1.7 Type PCA1.A3Ø Opto-isolated output module for 1(2)A

#### Technical data

Number of outputs per module 8, galvanically isolated between process

and CPU

Output current 5mA - 1A (2A) \*

When operated at 5...24VDC, the load resistance should be at least  $24\Omega$ .

resistance should be at least 24w.

Operating mode Source operation (pos. switching voltage)

Short-circuit protection 1.6A quick-acting fuse

Total current refer to graph

Voltage range Vout 5...36VDC

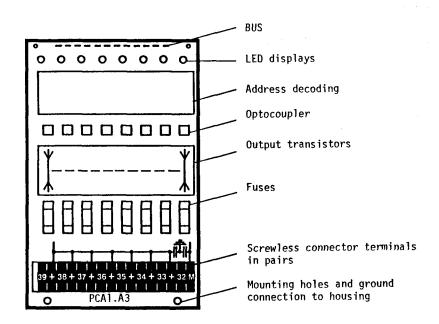
Voltage drop  $\max. 1.5V \text{ at } I = 1A$ 

Isolation voltage of optocouplers

optocouplers 2000V

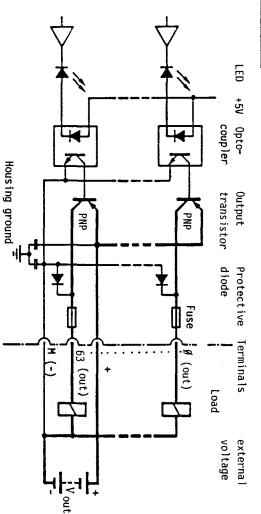
Output delay (typical)  $500\mu s$  (i.e. approx. 7 cycles at  $70\mu s$ )

# Presentation and terminal layout



<sup>\*)</sup> Two outputs per module can carry a load 2A each if the total current does not exceed that shown in the figure. For such outputs, a quick-acting 2.5A fuse should be used. Please note, however, that the voltage drop at the terminals is approx. 2.5V with a load of 2A.

# Output circuit



Output conducting (set)
Output non-conductive (reset)

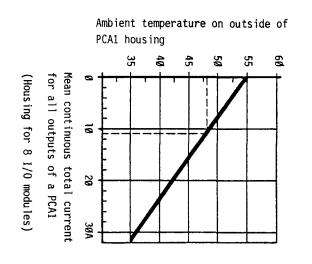
≙ LED ON ≙ LED OFF

# Note

Terminal M is to be connected to the negative of the external voltage. It is used for the internal supply of the module. Accordingly the positive terminal is omitted on the first output per card (in the example above on AØ). However because the positive terminals are looped, connection is via one of the remaining positive terminals.

Max. permissible total current for the entire PCA1 (housing for ω I/O modules)

The average (thermal) continuous total current S. relevant



Max. ambient temperature	Mean total current	4 control relays at 12W 100%ED	4 valves at 48W 30%ED	8 valves at 18W 100%ED	Example: (24V)
48°C	10.4A	2.ØA	2.4A	6.ØA	I mean

# Note:

In spite of the internal loops of the positive, several terminals are to be used, since the current is not to exceed 4A per double terminal.

# B 1.1.8 Type PCA1.A5Ø Output module for VAC with static relay (Triac)

# Technical data

Number of outputs per module

8, galvanically isolated

Output voltage range

24...28ØVAC eff. (24...24ØVAC nom.)

Output current nom.

1A eff.

Output current min.

60mA eff.\*

Overcurrent max.

28A peaks 20ms, non-repetitive 1s, non-repetitive 7A peaks

Overvoltage max.

600V peaks, non-repetitive

Voltage drop max.

1.40

Isolation voltage of

2500V eff.

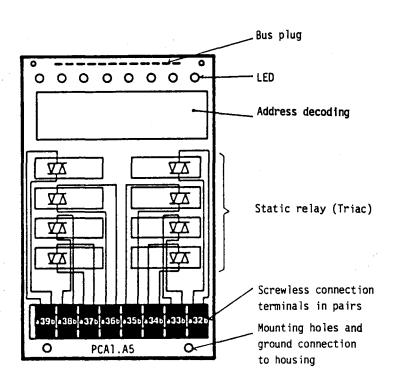
optocoupler

Isolation resistance of

optocoupler

 $100M\Omega$ 

# Presentation and terminal layout



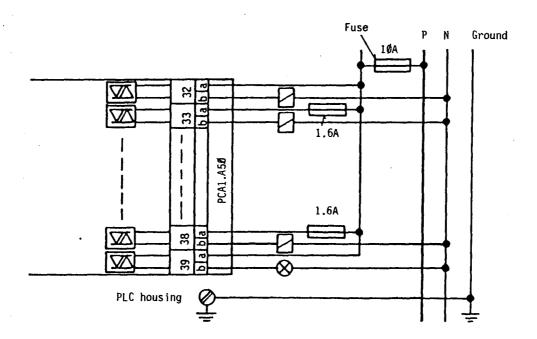
<sup>\*)</sup> Important: Due to minimal current of 60mA, for example contactors with a hold-power of <13VA have to be provided by an adequate shunt over the coil!

The output module PCA1.A5Ø with static relay can be used to control resistor loads (lamps, heating equipment) and to control inductive loads (motors, valves, contactors). The outputs are opto-isolated against the CPU and against one another. The integrated zero-switches who set load at the zero-passage, have a very positive effect on lifetime, number of switch operations and interference suppression.

# Warning

For reasons of protection of data transmission lines, displays and user input elements use low voltage material when connecting low voltage on the PLC.

All connections of an A50-module are to be connected on the same circuit; that means at one point in such a way that they are all protected against one AC-phase by one fuse. Each load circuit may be protected individually by a fuse of max. 1.6A.



# B 1.1.9 Type PCA1.B1Ø Electrically connected input/output module

The B10 module is a combination of modules E10 and A10. The I/O-division and therefore also the modularity can be reduced to four.

# Technical data

# Inputs:

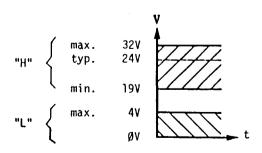
Number of inputs per module Input voltage V<sub>1n</sub> Input current at 24V Input delay (typical) Operating modes 4, electrically connected 24VDC, smoothed or pulsating 10mA 8ms Source or sink operation, depending on connection

#### Outputs:

Number of outputs per module Output voltage

Short-circuit protection Operating mode Total current Voltage range V<sub>out</sub> Voltage drop Output delay (typical) 4, electrically connected 5mA - 1A (2A) \* When operated at 5...24V, the load resistance should be at least  $24\Omega$ . 1.6A quick-acting fuse Source operation (pos. switching voltage) See diagram for type PCA1.A1Ø 5...36VDC, smoothed or pulsating max. 1.5V at I = 1A 10 $\mu$ s (with an inductive load, the turn-off delay is greater due to the protective diode.)

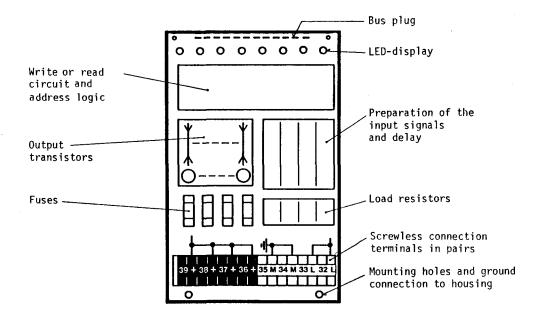
# Definition of the input voltages



Pulsating DC is adequate as supply voltage because of the 8ms input delay.

<sup>\*)</sup> Two outputs per module can carry a load of 2A each if the total current does not exceed that shown in the figure. For such outputs, a quick-acting 2.5A fuse should be used. Please note however, that the voltage drop at the terminals is approx. 2.5V with a load of 2A.

# Presentation and terminal layout



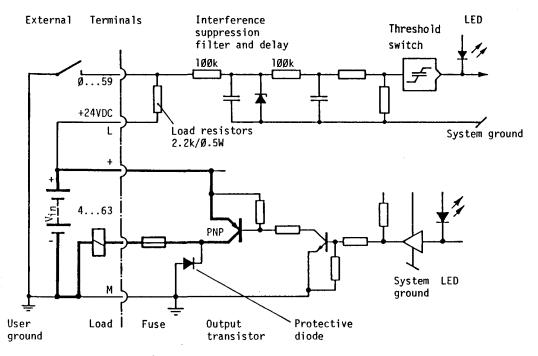
#### Input/output circuit

The inputs can be used in either source or sink operation, depending on the external circuitry.

The outputs can only be driven in source operation.

# <u>Inputs in sink operation or negative logic</u>

Switch closed (negative at input) : "L"  $\triangleq$  LED OFF Switch open (positive at input) : "H"  $\triangleq$  LED ON

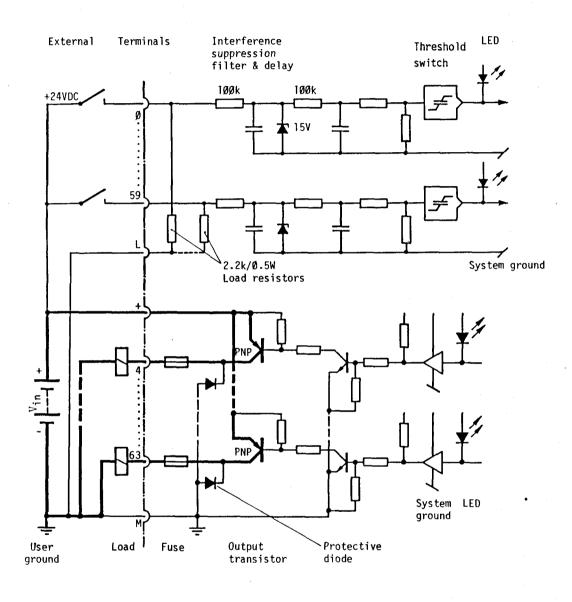


Output conducting (set) 

□ LED ON Source
Output non-conductive (reset) □ LED OFF operation

# Inputs in source operation or positive logic (normal case)

Switch closed (positive at input): "H"  $\triangleq$  LED ON Switch open (negative at input) : "L"  $\triangleq$  LED OFF



Output conducting (set)  $\triangleq$  LED ON  $\geqslant$  Source Output non-conductive (reset)  $\triangleq$  LED OFF  $\geqslant$  operation

Max. permissible total current for complete PCA1 (housing for 8 I/O modules)

Refer to data on PCA1.A1Ø output module

# B 1.1.10 PCA1.B8Ø Compact input/output module with short-circuit-protected outputs

The PCA1.B8Ø module is a compact input/output module similar to the PCA1.B9Ø, but with short-circuit-protected outputs. The inputs and outputs are electrically connected and fed by the same power supply unit. As they use the same addresses, only the instructions OUT, SEO and REO can be used for the outputs. Any interrogation commands refer to the corresponding inputs.

## Technical data

## Inputs

Number of inputs per module

8, electrically connected

Input voltage V<sub>in</sub>

24VDC, smoothed or pulsating

Input current at  $V_{in} = 24V$ 

10mA

Input delay (typical)

9ms

Operating mode

Source or sink operation

#### **Outputs**

Number of outputs per module

6, electrically connected

Output current range

 $5mA - \emptyset.5A$ 

In the voltage range 5 - 24VDC the load resistance has to be at least 480.

Operating mode

Source operation

Voltage range Vout

8 - 32V smoothed

Residual ripple of Vout

max. 10%

Voltage drop

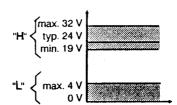
max. 1.5V at  $I = \emptyset.5A$ 

Output delay (typical)

10us

In case of inductive load, the output delay is greater due to the freewheeling diode.

#### Input voltage



Owing to the input delay of 9ms, pulsating DC-voltage is sufficient for the external power supply (in source operation).

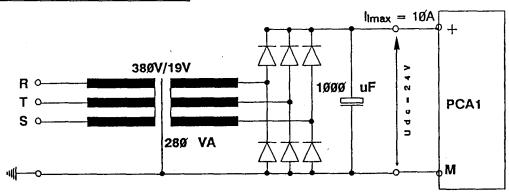
## What to do in the event of a short-circuit

In a short-circuited load circuit, the output current is limited to 1A. If the short-circuit remains, the output is switched off after  $\emptyset.5$  - 2s. From this moment on, every  $\emptyset.5$ s a new attempt is made of switching it on again. When the short-circuit is removed, the output is automatically switched on again.

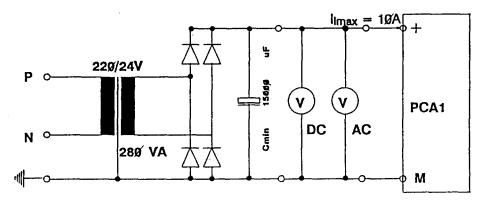
## User power supply of the PCA1 when using the PCA1.B8Ø module

The short-circuit protection feature makes higher demands on the power supply of the PCA1.B8Ø module. Therefore, two suggestions will be made in the following with regard to the user power supply.

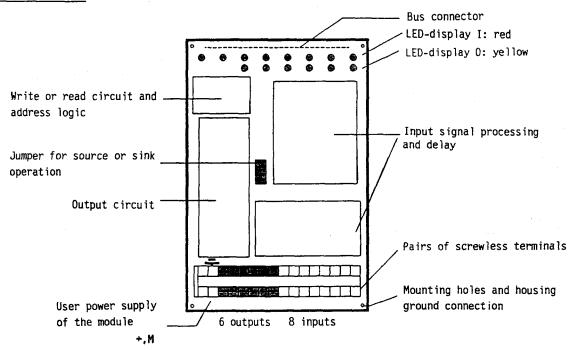
#### When using a 3-phase transformer

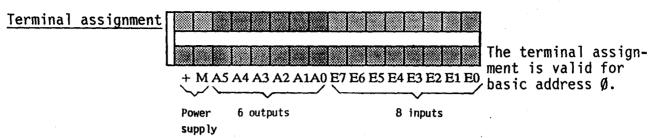


## When using a 1-phase transformer



#### Presentation



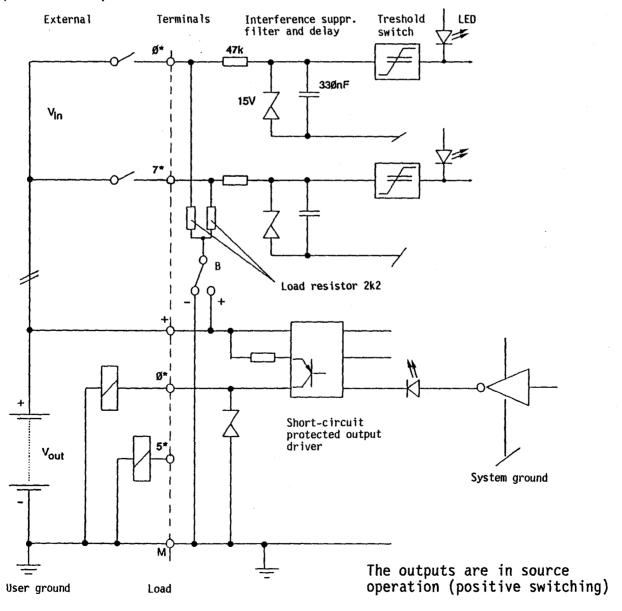


## Electric input and output circuit

Depending on the external circuitry, the inputs can be used in source or sink operation. Outputs can only be used in source operation.

## <u>Inputs in source operation or positive logic (normal case)</u>

Switch closed (positive at input): "H" = LED ON Switch open (negative at input) : "L" = LED OFF Jumper B is in position "-".



\*) Absolute address = basic address + relative address

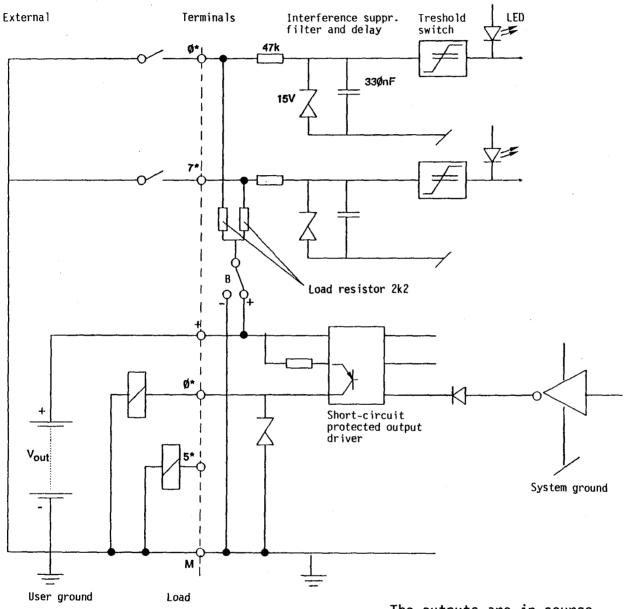
Vout: smoothed voltage

Vin: smoothed or pulsating voltage



## Inputs in sink operation or negative logic

Switch closed (negative at input): "L" = LED OFF Switch open (positive at input) : "H" = LED ON Jumper B is in position "+".



The outputs are in source operation (positive switching)

\*) Absolute address = basic address + relative address

Vout: smoothed voltage

## B 1.1.11 Type PCA1.B9Ø Electrically connected compact I/O module

The I/O capacity of the PCA1 series can be expanded economically to 56 or 112 inputs and outputs through this module. I/O circuits use a common supply voltage and operate in the source mode. Inputs and outputs use the same addresses. Only the three instructions OUT, SEO and REO can be used for outputs. Interrogation commands refer to the respective inputs.

## Technical data

## Inputs:

Number of inputs per module

8, electrically connected

Input voltage V<sub>in</sub>

24VDC, smoothed or pulsating

Input current at 24V

10mA

Input delay (typical)

9ms

Operating mode

Source operation,

sink operation by commuting jumper B

#### Outputs:

Number of outputs per module

6, electrically connected

Output voltage

 $5mA - \emptyset.5A$ 

When operated at 5...24VDC, the load resistance should be at least 480.

Operating mode

Source operation (positive switching)

Voltage range Vout

5...36VDC, smoothed or pulsating

Voltage drop

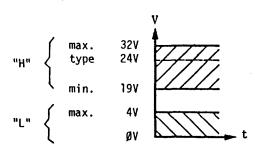
max. 1.5V at  $I = \emptyset.5A$ 

Output delay (typical)

 $10\mu s$  (With an inductive load, the turnoff delay is greater due to the free-

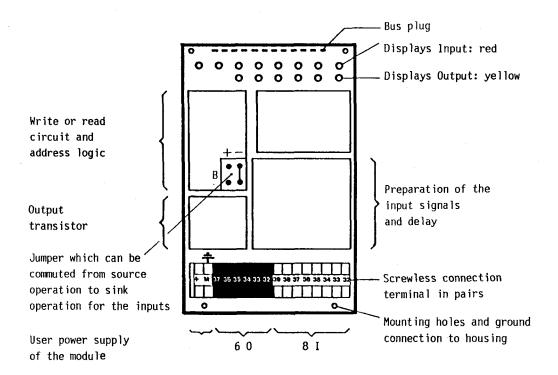
wheeling diode.)

# Definition of the input voltages



Pulsating DC is adequate as supply voltage because of the 9ms input delay.

#### Presentation and terminal layout

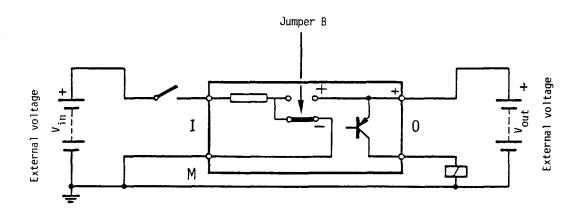


## Input/output circuit

All inputs are switched to source operation (-) (factory setting). The inputs can be switched to sink operation by commuting jumper B to "+".

The outputs may only be used in sink operation.

# Connection of inputs and outputs

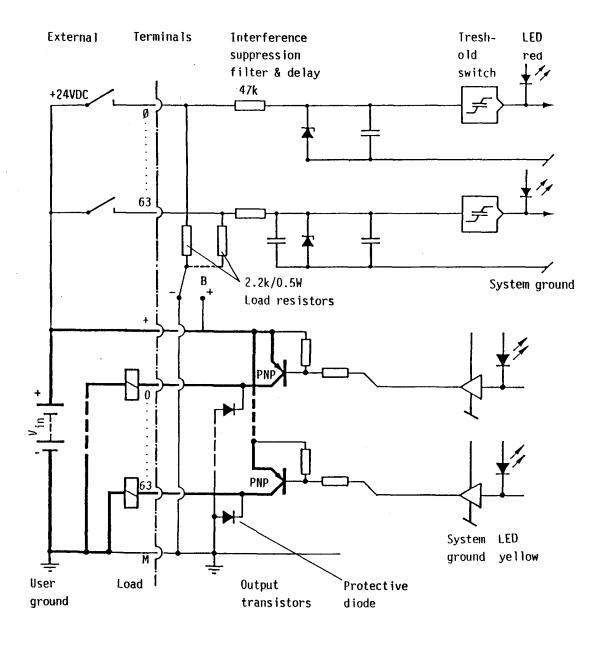


Factory setting: jumper B on "-": source operation



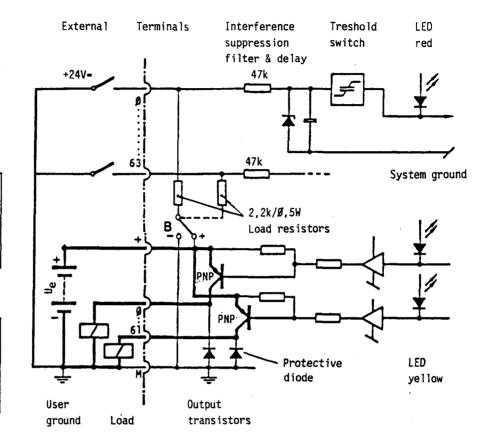
```
Inputs in source operation or positive logic
(factory setting: jumper B on "-")
```

Switch closed (positive at input): "H" = LED ON Switch open (negative at input): "L" = LED OFF



Output conducting (set) = LED ON Source
Output non-conductive (reset) = LED OFF operation

# Inputs in sink operation or negative logic, outputs in source operation (jumper B on "+")



Inputs: Sink operation

•Switch closed (- at input): H = LED OFF •Switch open (+ at input): L = LED ON

Outputs: Source operation

Output conducting (set) 

LED ONOutput non-conductive (reset) 

LED OFF

## B 1.1.12 Type PCA1.E4Ø Combined date-time and input module (only PCA14)

In addition to <u>7 inputs</u>, the module PCA1.E4Ø contains a precise <u>date-time</u> with power reserve. This buffered date-time can only be evaluated with the system series PCA14 in connection with its software date-time.

#### Technical data

#### Inputs:

Number of inputs per module 7, electrically connected

(addr. 1...7)

Input voltage V<sub>in</sub> 24VDC, smoothed or pulsating

Input current at 24VDC 10mA

Input delay (typical) 9ms

Operating mode Source or sink operation

Date-time:

Accuracy <15s/month at  $T = 15 - 30^{\circ}C$ 

Power reserve 2 months due to NiCd battery 3)

Date-time values Day of the week  $\emptyset1...\emptyset7^{2}$ 

Year ØØ...99
Month Ø1...12
Day of the month Ø1...31 19
Hours ØØ...23
Minutes ØØ...59
Seconds ØØ...59

Internal power consumption of

the module (5V)

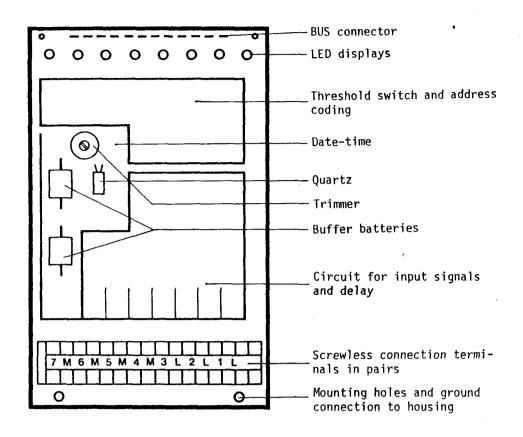
15...7ØmA

<sup>1)</sup> The date-time takes the various months and leap years into account.

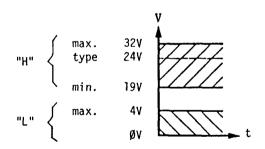
<sup>2)</sup> Day of the week Ø1 stands for Monday, Ø7 stands for Sunday.

<sup>3)</sup> Life of buffer battery approx. 5 years Spare part no. 4'507'11'950

#### Presentation and terminal layout



## Definition of the input voltages



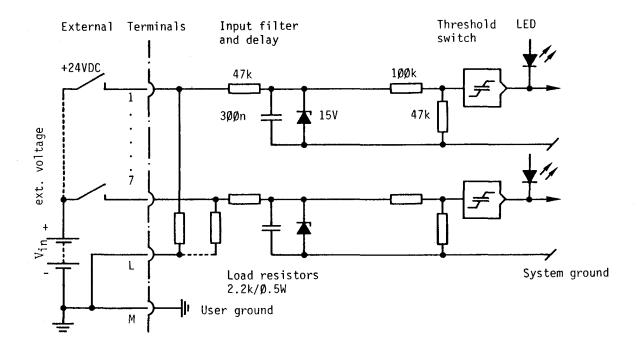
Pulsating DC-voltage is sufficient as supply voltage, because of the 9ms input delay.

The 7 inputs (addresses 1...7) can be used without restrictions and independently of the date-time. The address  $\emptyset$  is reserved for the data transfer from and to the date-time.

#### Input circuit

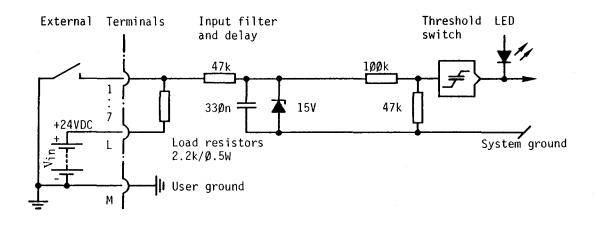
Depending on the external circuitry this module can be used either in source or sink operation.

## Source operation or positive logic (normal case):



Switch closed (positive at input): "H"  $\triangleq$  LED ON Switch open (negative at input): "L"  $\triangleq$  LED OFF

## Sink operation or negative logic:



Switch closed (negative at input): "L" 

LED OFF
Switch open (positive at input): "H" 

LED ON



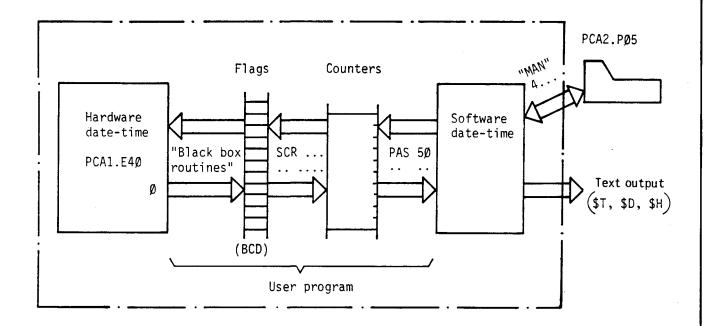
#### Handling of the date-time

Owing to its higher accuracy, the hardware date-time is considered the master as compared with the software date-time. The comfortable instructions such as PAS 50 and the special text characters \$T, \$H and \$D (see PCA14 manual), however, refer only to the software date-time. It is therefore necessary to synchronize the hardware and the software date-time at times (e.g. every 24h). Moreover, the date and time values of the hardware date-time must be set on the first start-up.

Make sure that synchronization of the software date-time and setting of the hardware date-time are performed only when required in order to prevent the hardware date-time from being permanently blocked.

Its handling will be described in detail on the following pages.

Principle of the data transfer between software and hardware date-time



As evident from the above figure, a flag field (for the whole contents  $\underline{60}$  or  $\underline{68}$  flags) as well as 1 counter must be reserved for the duration of the data transfer between both date-times. The transfer from the hardware date-time to the flag field or vice versa is effected serially with the address 0. The addresses 6 and 7 are used as control signals.

- Address  $\emptyset$ : This address is used for the <u>data transfer</u> between the date-time and the flags.
- Address 6: With address 6 a <u>clock</u> is generated. With every clock signal a data bit is received or transmitted by the hardware date-time.
- Address 7: Chip select. In order to activate the data transfer, this address must be set to "H". As soon as the transmission is finished, address 7 must be reset to "L".



Format of the data transfer (4 control bits followed by 7 x 8 bits BCD)

## a) Setting of the hardware date-time

Control   bit	Hours	Minutes	Day of the month	Month	Year	Day of the week	Seconds
-2E4	00/80/51/5	2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	32222222	8 8 8 8 8 8 8			
9 6	Ω	12	<b>a</b>	28 MSB	ST (S US)	1	

Transfer direction

MSB must be transmitted before LSB.

MSB = Most Significant Bit

LSB = Least Significant Bit

## b) Reading of the hardware date-time

	5	e	0	nd	ls				D	ay	o f e e		e					Ye	ea	r					i	Мо	nt	h				D		f	th	e	-	٨	1i n	ut	es					ı	Ho	ur	·s			1		nti oi:	rol t	
				I				I			I	_						I			I	I	I			$\prod$	I			I	I															brack									floor	
MSB W	•						7 LSB				•			٠.	12 128	9					•	٠,	651	4	•					22 MCD							33 136		•				<u>'</u>	48 MSR	2		•			•	 55 LCB	55 135	3		. 0	23

Transfer direction

When reading the hardware date-time the individual bits are read in the sequence LSB...MSB. To guarantee that the format corresponds to the read-in instruction for 2 x 4 bits BCD (code 16 in the 2nd line of the instruction SCR), make sure that the LSB of the individual date-time values is at the highest flag address. For the sake of an optimum transfer routine "hardware date-time to software date-time" the control bits are fitted with the 4 highest (out of  $6\emptyset$ ) flag addresses. This results in the above "inverse" transfer direction.

## Function of the control bits

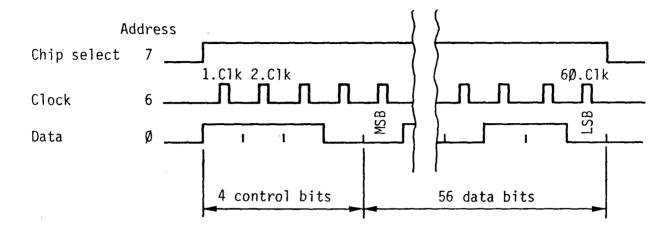
The 4 control bits tell the date-time "what to do". The first three bits received by the date-time define the data to be transmitted. The 4th bit is used to determine whether the date-time is set or read.

These 4 control bits must be transmitted before every data transfer, irrespective of whether the date-time is set or read.

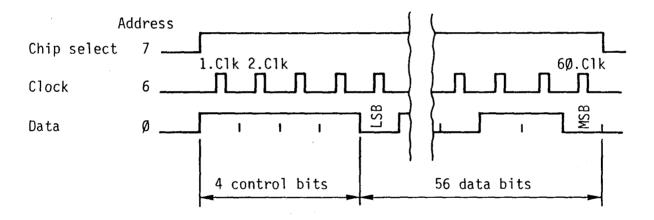
1.	2.	3.	4.	Bit
1	1	1	х	Whole contents
1	1	Ø	х	Year
1	Ø	1	х	Day of the week
1	Ø	Ø	х	Month
Ø	1	1	х	Day of the month
Ø	1	Ø	X	Hours
Ø	Ø	1	х	Minutes
Ø	Ø	Ø	х	Seconds
х	х	х	Ø	<u>Set</u> date-time
Х	х	х	1	Read date-time

# Transfer diagram

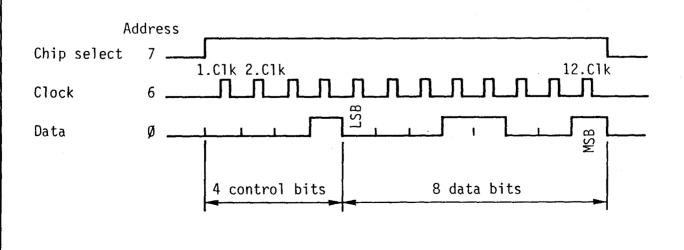
## a) Setting the whole date-time contents



# b) Reading the whole date-time contents



# c) Reading the seconds



#### Examples

1. Setting the hardware date-time (whole contents)

During the <u>first</u> startup of the hardware date-time, the correct values must be set. Proceed as follows:

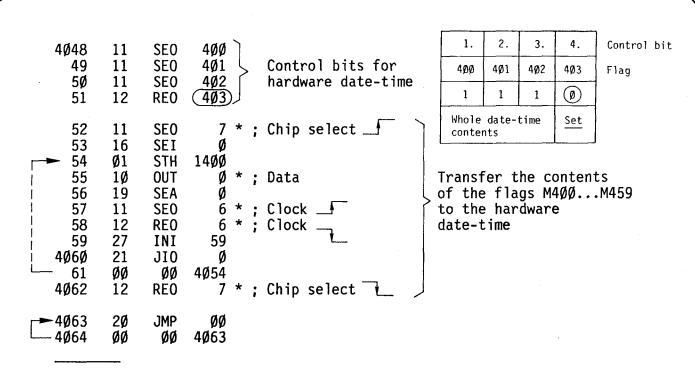
- The current date-time values are introduced into the software date-time (e.g. with a PCA2.PØ5, see chapter "Operating modes").
- In the STEP-mode the following routine is selected and executed. The hard-ware date-time automatically accepts the values of the software date-time and keeps on running, irrespective of whether the PLC stays switched on.

This procedure can be repeated, if after months the deviation from the actual date-time has become too great.

#### Program

4Ø2Ø 21 22 23	29 17 15 20	PAS 17 SCR 20	50 260 260 459 Seconds	
24 25 26 27	29 11 15 2Ø	PAS 11 SCR 2Ø	$ \begin{array}{c} 50 \\ 260 \\ 260 \\ 451 \end{array} $ Day of the week	
28 29 4ø3ø 31	29 12 15 2Ø	PAS 12 SCR 20	50 260 260 443	
32 33 34 35	29 13 15 20	PAS 13 SCR 2Ø	50 260 260 435 Month Transfer contents of software date-time to	
36 37 38 39	29 14 15 20	PAS 14 SCR 2Ø	50 260 260 Day of the month worth worth 435 260 427	Day of the week
4040 41 42 43	29 16 15 20	PAS 16 SCR 20	50 260 260 419 Minutes 260 419 Transfer direct:	LSB 443 MSB 444 LSB 451 MSB 452
44 45 46 47	29 15 15 20	PAS 15 SCR 2Ø	50 260 Hours 260 Flags — Hardware d	late-time

\*) With code 20 in the 2nd line of the instruction SCR 20 bits BCD are transferred. Therefore, the flags 392...403 must also be reserved, with M400...M403 serving as control bits for the hardware date-time. On the whole, 68 flags are required for setting the hardware date-time.

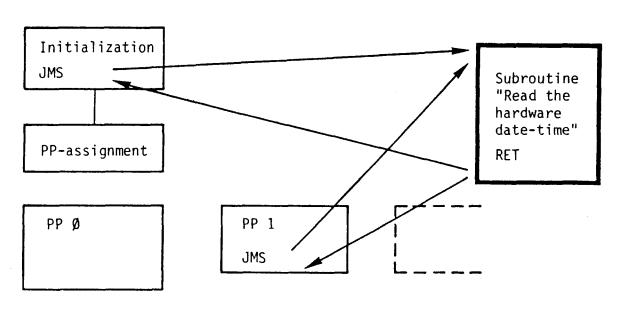


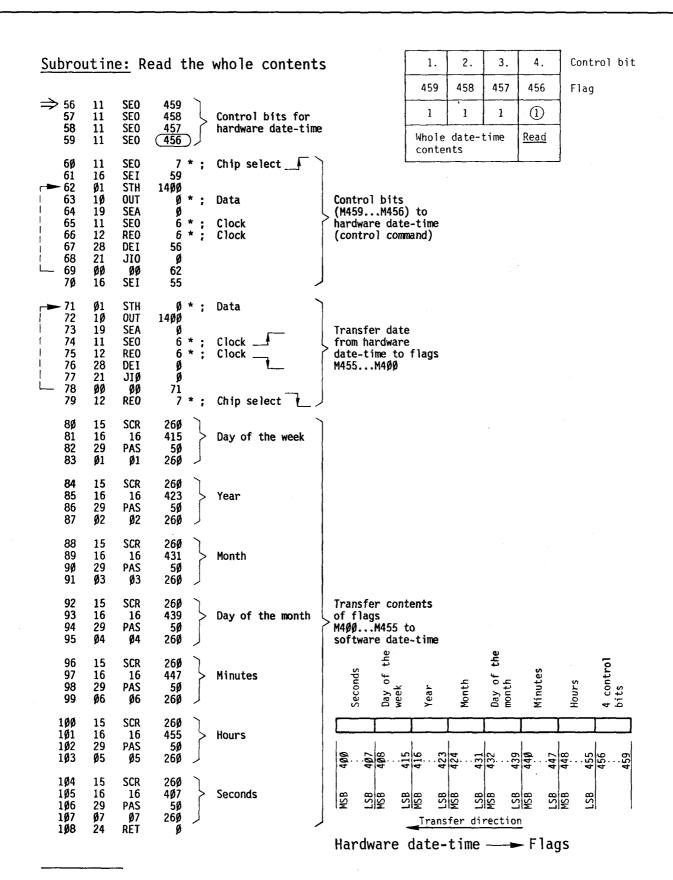
<sup>\*)</sup> These addresses do not depend on the plug-in location of the module (example for addr.  $\emptyset...7$ ).

## 2. Reading the hardware date-time (whole contents)

The routine "Reading the hardware date-time" <u>must</u> be executed after each voltage failure upon switching on the PLC again. It can also be called in the main program depending on internal or external conditions, ensuring that the software date-time does never deviate much from the hardware date-time. It is of advantage to write the program "Reading the hardware date-time" as a subroutine.

#### Program structure





<sup>\*)</sup> These addresses depend on the plug-in location of the module.

3. Transferring the seconds from the hardware date-time (to software date-time)

As is well known, it is also possible to transfer only single values of the date-time. If the software date-time is regularly synchronized with the hardware date-time, it may be sufficient to transfer only the seconds (accuracy of the software date-time: <3s/day).

<u>S</u>	ubrout	ine:	Read	the seconds					,		_
$\Rightarrow$	5Ø1 5Ø2	12 12	REO REO	411 41Ø	Control bits for		1.	2.	3. 4ø9	4. 4ø8	Control bit Flag
	5Ø3 5Ø4	12 11	REO SEO	409	hardware date-time		Ø	Ø	Ø	1	
	505 506 507 508 509 510 511 512 513	11 16 Ø1 10 19 11 12 28 21	SEO SEI STH OUT SEA SEO REO DEI JIO ØØ	7 *; 11 1400 Ø *; 6 *; 8 Ø 507	Chip select  Data  Clock Clock	>	Contro (M411 to hai (conti	M4 rdwar rol i	Ø8) e da		
	515	16	SEI	7			400	401	403	405	46
	516 517 518 519 520 521 522 523 524	Ø1 1Ø 19 11 12 28 21 ØØ 12	STH OUT SEA SEO REO DEI JIO ØØ REO	0 *; 1400 6 *; 6 *; 9 516 7 *;	Data  Clock Clock Chip select	>	ጀ Transt hardwa flags	are d	ate-	ds fr time	
	525 526 527 528	15 16 29 Ø7	SCR 16 PAS Ø7	26Ø 4Ø7 5Ø 26Ø		`	Transf softwa				
	529	24	RET	Ø							

<sup>\*)</sup> These addresses depend on the plug-in location of the module.

# B 1.1.13 Type PCA1.W1.. Analog I/O module with 8- or 7-bit resolution

#### Technical data

#### Inputs:

Number of channels 6, electrically connected Voltage range  $\emptyset...5V=^{1}$ )
Resolution 8 bits  $(1/256 riangleq \emptyset.4\%)$ Accuracy (absolute deviation) 1 1/2 bits riangleq 0.6%)
Input impedance riangleq 1.0%Time constant of input filter riangleq 0.2%A/D conversion time 6, electrically connected  $0...5V=^{1}$ )
8 bits (1/256 riangleq 0.4%)1 2 bits riangleq 0.6%)
2 1M $\Omega$  2.7%
6, electrically connected  $0...5V=^{1}$ )
8 bits 0.2%0.2%
8 bits 0.2%0.2%
8 connected  $0...5V=^{1}$ 0.2%
9 connected  $0...5V=^{1}$ 0.2%
9 connected  $0...5V=^{1}$ 0.2%
9 connected  $0...5V=^{1}$ 0.2%

All inputs are protected against positive and negative overvoltages.

#### Outputs:

Number of channels  $\emptyset$ , 1 or 2  $^{2}$ )
Voltage range  $\emptyset$ ...1 $\emptyset$ V, can be changed to  $\emptyset$ ...2.56V

Resolution 7 bits  $(1/128 riangleq \emptyset.8\%)$ Accuracy 1 1/2 bits riangleq 1.0%Load impedance riangleq 1.0%Power consumption (5V) 3 $\emptyset$ ...4 $\emptyset$ mA 25mA

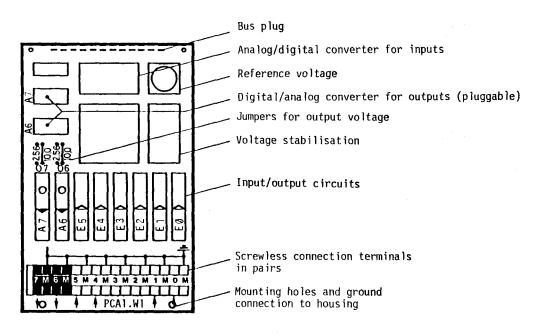
1) Special variants PCA1.W1.. ZØ9:  $\emptyset$ ...2 $\emptyset$ mA input impedance 296 $\Omega$  PCA1.W1.. ZI $\emptyset$ :  $\emptyset$ ...1 $\emptyset$ V input impedance 2 $\emptyset$ k $\Omega$ 

2) Number of analog outputs

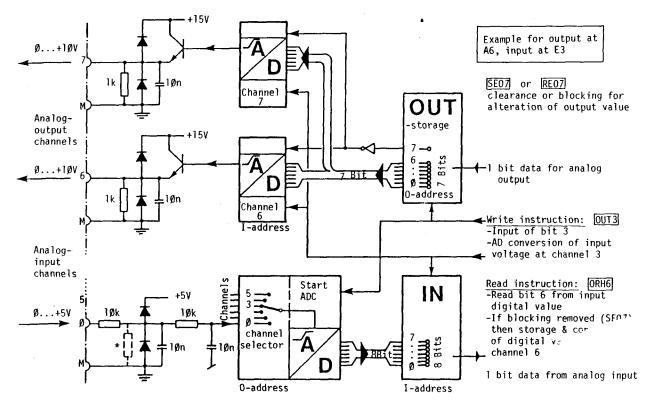
without output: PCA1.W1Ø with 1 output: PCA1.W11 (A7)

with 2 outputs: PCA1.W12 (A7 and A6)

Presentation



## Input/output circuit and block circuit diagram



\*) Only required at 10V or 20mA

#### Programming example for address location $\emptyset...7$

Read analog input voltage present on channel 3 (ADDR 3). The corresponding binary value is to be transferred to counter 260.

```
100 OUT 3^2; Select I-channel 3 and trigger A/D conversion 101 SCR 260 Transmit binary value (8 bits) to counter 260 102 24 7^2
```

Transfer an analog value to 0-channel 6 (ADDR 6). The numerical value  $(\emptyset...255)$  is stored in counter 310.

200 SCR 310
201 21 71)2)

Transmit value 0...255 from counter to D/A converter

202 SEO 72)

Clearance for altering the output value

Storage of binary value, conversion and output to output channel 5

204 REO 72)

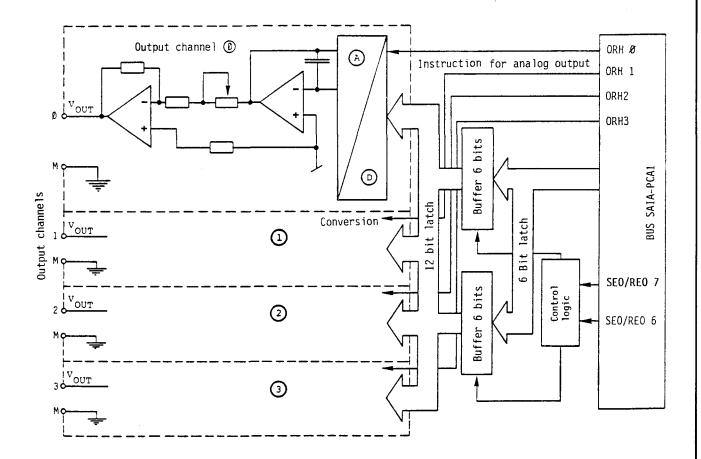
Blocking of output value

1) The counter value of  $\emptyset$ ...255 corresponds to an output voltage of  $\emptyset$ ...1 $\emptyset$ V. The resolution, however, is only 7 bits.

<sup>2)</sup> If this module uses, for example, the addresses 24 to 31, it must be noted that the highest address of the card is 31. This means that input channel 3 corresponds to address 27, the output channel corresponds to address 30 and the block or clear command is assigned to address 31.



## Block circuit diagram PCA1.W2

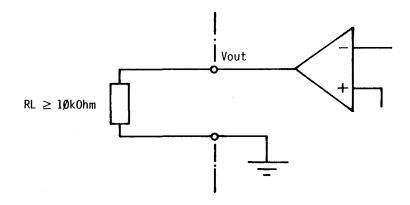


## Connection to the process

A voltage output is made up of the plug-in D/A-converter and the two soldered-in amplifiers.

The standard output voltage is  $\emptyset...1\emptyset$ V. For special applications, appropriate precision resistors are soldered in.

The signals are always measured potential to ground.



#### Software

#### Output analog value

The 12-bit digital value to be output must be applied at the inputs of the D/A-converters. By means of an instruction (ORH  $\emptyset$ ...3) this value is stored and output as analog value by the D/A-converter.

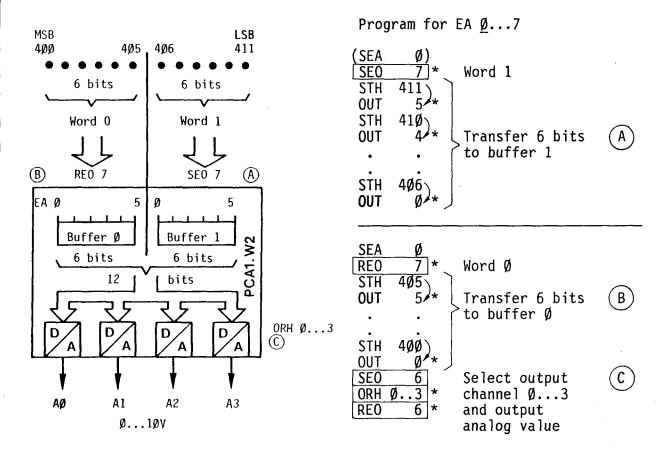
The unchanged analog values of all 4 outputs are available to the process as long as they are not redefined by means of a new instruction.

#### Procedure

With the series PCA1 only 8 element addresses are available per I/O-module. In order to process the 12-bit data, they are split up into two words consisting of 6 bits each and processed one after the other.

The following steps must be distinguished:

- A) Transfer the first 6 bits (starting with LSB) to buffer 1 (SEO 7)
- B) Transfer the second 6 bits (up to MSB) to buffer Ø (REO 7)
- C) Select the output channel with ORH  $\emptyset \dots 3$  and trigger D/A-conversion at the same time.



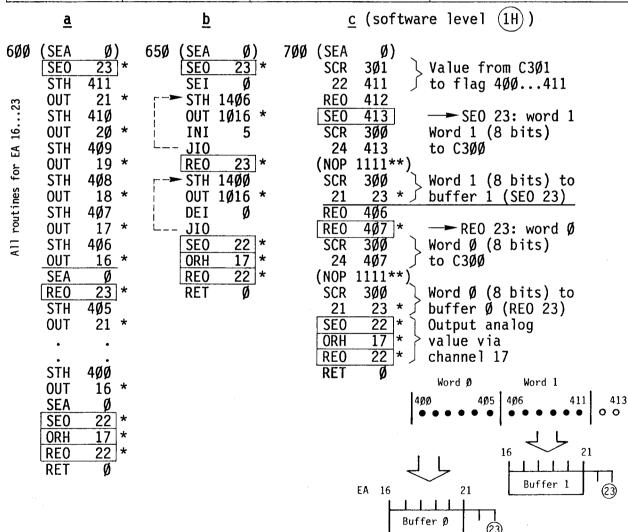
<sup>\*)</sup> If the module is placed to a position other than  $\emptyset$ , the corresponding basic address must be added.



#### Analog value output in the form of subroutines

The following versions a to c are distinguished by their software levels, program lengths, execution times and the number of program changes. Due to the standard execution time of 2.13 ms the PP-change is blocked and the serial interface is no longer operated for this period. If the interface is to function with a baud rate of 4800 or 9600 baud simultaneously, either version a or b can be used or version c with the commands NOP 1111 (operation of the data interface) given in brackets.

Subroutine version	Number of program lines	Execution time PCA14/15	Number of program changes (incl. RET) PCA14/15
a	31	3.09 ms	11
b	15	4.31 ms	13
c	18	2.13 ms	1



For versions a and b flags 400...411 are used. Version c uses counter C301 as an output register. 14 flags 400...413 are used in version c to load the buffers.

For basic address 16.

<sup>\*\*</sup> PCA14 as of version V6.034 for a baud rate of 9600 bauds.

## B 1.1.15 Type PCA1.W3.. 12-bit analog input and output module

#### Technical data

## Inputs:

Number of input channels

4

Input circuit

Differential with filter

Signal ranges: - voltage

ØV...+1ØV Selectable for 2) - 5V...+ 5V each module by 3) -1ØV...+1ØV means of a plug

- current

Ø ...+2ØmA 2) -1Ø ...+1ØmA 3) -2Ø ...+2ØmA

Alternatively pluggable as current loop. Current

range acc. to voltage range selected above

Resolution

12 bits = 1/4096

Accuracy (measured value)

typ. Ø.4% (max. Ø.8% during bipolar

operation)

Repeatability

± 2 LSB\*

Input impedance

voltage

 $\geq 1 M\Omega$ 

- current

499 Ω

Time constant of the input filter

Ø.1ms

A/D-conversion time

≤ 30µs

Max. admissible voltage

±15V

#### Outputs:

Number of output channels

max. 2

Resolution

12 bits = 1/4096

D/A-conversion

≤ 20μs

Signal ranges: - voltage

Standard: ØV...+1ØV

ØV...+ 5V -1ØV...+1ØV

Accuracy (actual value)

in range  $\emptyset...5V$  or  $\emptyset...1\emptyset V$ 

typ.  $\emptyset.4\% \pm 30mV**$ ;

max.  $1\% \pm 30mV**$ 

Load impedance

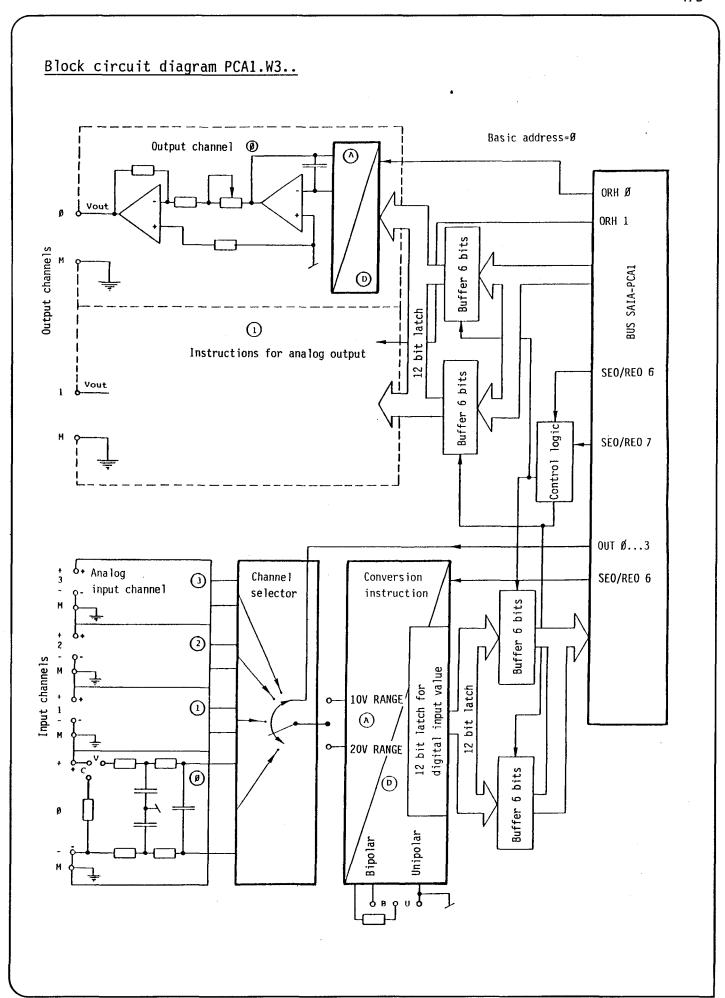
 $\geq 10 k\Omega$ 

Current consumption 5V

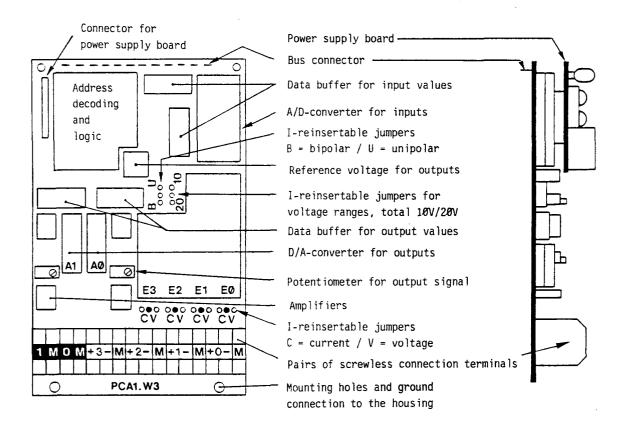
100...120mA

6Ø...1ØØmA

<sup>\*)</sup> LSB: Least Significant Bit; e.g. 10V divided by 4096: approx. 2.5mV \*\*) Max. constant offset value



## Presentation



## Versions, order specifications

Type PCA1.W3Ø with 4 I-channels, without output channel Type PCA1.W32 with 4 I-channels + 2 output channels (AØ +A1)

Signal ranges for inputs : selectable by jumpers

Signal ranges for outputs:  $\emptyset...1\emptyset V$  (other ranges of values on request)

#### Connection to the process

## Connection of the input channels

The common-mode voltage range of all input channels is  $\pm 10V$ , i.e., both potentials of each input channel must be within  $\pm 10V$  with respect to the ground. Under this condition correct registration of the measured data is ensured.

#### Preselection of the I-ranges:

- The process ground or measuring amplifier ground must be connected to the user ground of the PLC.

- The input voltage range of 10/20V is preselected jointly for all inputs of a module via the connector.

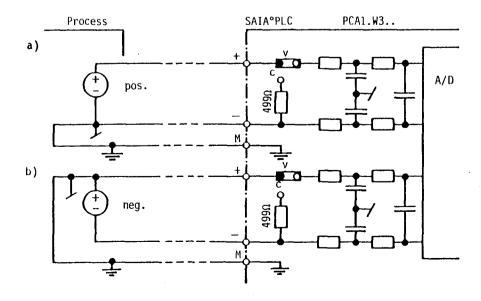
- Whether bipolar voltages (±V) or unipolar voltages are to be registrated, is preselected jointly for all inputs of a module via the connector B/U.

- Operation with current can be selected for each input individually via the plug (C = current, V = voltage). If the connector is plugged into C, a precision resistance of 499 $\Omega$  is switched into this input circuit, the voltage of which is evaluated. The current range depends on the selected voltage range (10V  $\cong$  20mA).

The following table shows the three basic ranges with respect to the corresponding digital value:

Digital value	Unipolar U	Bipolar op	eration B
	(connector 10V)	(connector 10V)	(connector 20V)
4Ø95 2Ø48 Ø	+1ØV (+2ØmA) +5V (+1ØmA) ØV ( ØmA)	+5V (+1ØmA) ØV ( ØmA) -5V (-1ØmA)	+1ØV (+2ØmA) ØV ( ØmA) -1ØV (-2ØmA)

<u>In case of unipolar operation</u> the positive potential is applied to the plusterminal. Figures a and b show the connection scheme for the measurement of positive or negative voltages respectively.



#### Software

With the version PCA1 only 8 element addresses are available per I/O-module. In order to process the 12-bit data, they are split up into two words consisting of 6 bits each and processed one after the other.

Word  $\emptyset$ : contains the high-order 6 bits including MSB Word 1: contains the low-order 6 bits including LSB

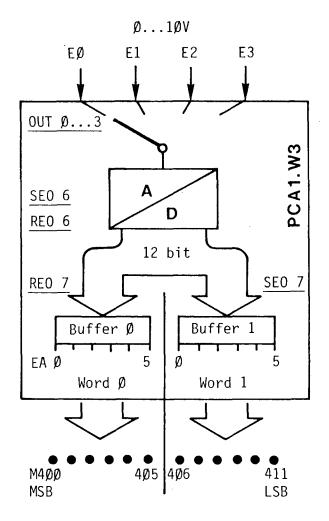
#### Read analog value (input channels)

For reading an analog value the following 3 steps are necessary:

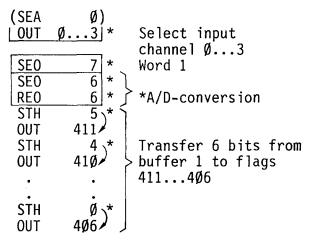
A) Select input channel (OUT Ø...3)

B) Initiate actual A/D-conversion (SEO 6, REO 6)

C) Select the 6-bit word group Ø or 1 (REO/SEO 7)



Program for EA  $\emptyset$ ...7



SEA	Ø	
RE0	7 * \	Word Ø
STH	5 \*	
OUT	4Ø5 ✓	Transfer 6 bits from
•	• (	Transfer 6 bits from > buffer Ø to flags
•		4Ø54ØØ
STH	Ø /*	
OUT	ر 400/	

<sup>\*)</sup> If the module is placed to a position other than Ø, the corresponding basic address must be added.

## Read the analog value in the form of a subroutine (input channel)

The following versions a to c are distinguished by their software levels, program lengths, execution times and the number of program changes. Version c results in the shortest execution time. With the standard execution time of 2.03 ms, however, the PP-change is blocked and the serial interface is no longer operated for this period. If the serial interface is to function with a baud rate of 4800 or 9600 bauds simultaneously, either version a or b can be used or version c with the commands NOP 1111 (operation of the data interface) given in brackets.

Subroutine version	Number of program lines	Execution time PCA14/15	Number of program changes (incl. RET) PCA14/15
a	3Ø	3.10 ms	11
b	15	4.35 ms	13
c	17	2.03 ms	1

<u>a</u>	<u>b</u>	$\underline{c}$ (software level $(\overline{1H})$ )
400 (SEA 0)   OUT 17   * SEO 23   * SEO 22   * SEO 22   * SEO 22   * STH 21   * OUT 410   * STH 19   * OUT 409   STH 16   * OUT 406   SEA 0   REO 23   * STH 21   * OUT 405   * OUT 405   * STH 21   * OUT 405   * OUT 400   RET 0	45Ø (SEA Ø) OUT 17 * SEO 23 * SEO 22 * REO 22 * SEI Ø STH 1Ø16 * OUT 1416 INI 5 JIO REO 23 * STH 1Ø16 * OUT 14ØØ DEI Ø DEI Ø RET Ø	SEA

With all three versions the analog value is available as 12-bit binary value in the flag area 400...411. With version c the flags 412 and 413 are also used (because of the transfer of 8 bits instead of 6 bits). The routine c finally transfers the value to counter C300.

For basic address 16.

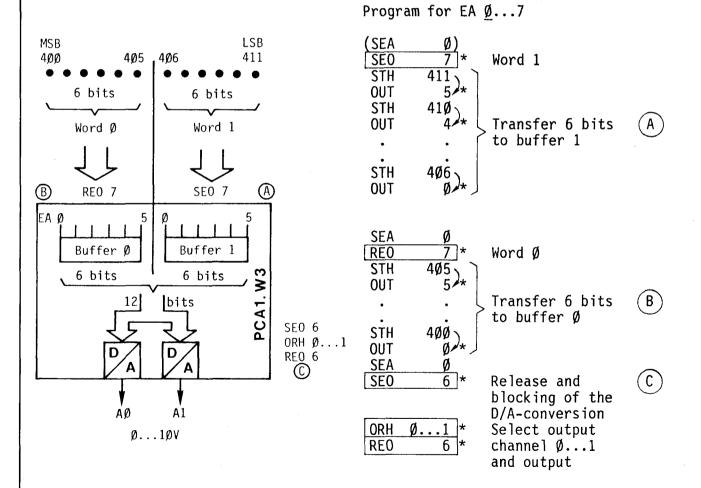
<sup>\*\*</sup> PCA14 as of version V6.034 for a baud rate of 9600 bauds.

#### Output analog value (output channels)

The 12-bit digital value to be output must be applied at the inputs of the digital/analog converters. This value is stored by means of an instruction (ORH  $\emptyset$  or 1) and output as analog value by the D/A-converter. The unchanged analog values of the 2 outputs are available to the process as long as they are not redefined by another instruction.

In order to output an analog value from a bit pattern in the flag area, 3 steps are necessary:

- A) Transfer the first 6 bits (starting with LSB) to buffer 1 (SEO 7)
- B) Transfer the second 6 bits (up to MSB) to buffer  $\emptyset$  (REO 7) Release of the D/A-conversion (SEO 6)
- C) Select the output channel with ORH  $\emptyset...1$  and trigger the D/A-conversion at the same time. Block D/A-conversion again (REO 6).



<sup>\*)</sup> If the module is placed to an address other than  $\emptyset$ , the corresponding basic address must be added.

#### Analog value output in the form of subroutines (output channels)

The following versions a to c are distinguished by their software levels, program lengths, execution times and the number of program changes. Version c results in the shortest execution time. Due to the standard execution time of 2.13 ms, however, the PP-change is blocked and the serial interface is no longer operated for this period. If the serial interface is to function simultaneously with a baud rate of 4800 or 9600 bauds, either version a or b can be used or version c with the commands NOP 1111 (operation of the data interface) given in brackets.

Subroutine version	Number of program lines	Execution time PCA14/15	Number of program changes (incl. RET) PCA14/15
a	31	3.Ø9 ms	11
b	15	4.31 ms	13
c	18	2.13 ms	1

<u>a</u>	<u>b</u>	$\underline{c}$ (software level $(1H)$ )
SEO 23 * STH 411 * STH 409 OUT 17 * STH 406 OUT 16 * SEA Ø REO 23 * STH 405 OUT 21 * STH 405 OUT 16 * SEA Ø REO 23 * STH 405 OUT 21 * * * * * * * * * * * * * * * * * *	65Ø (SEA Ø)  SEO 23 *  SEI Ø  STH 14Ø6  OUT 1Ø16 *  INI 5  JIO  REO 23 *  STH 14ØØ  OUT 1Ø16 *  DEI Ø  JIO  SEO 22 *  ORH 17 *  REO 22 *  RET Ø	700 (SEA 0) SCR 301 22 411 REO 412 SEO 413 SCR 300 24 413 SCR 300 24 413 SCR 300 (NOP 1111**) SCR 300 REO 406 REO 407 * SCR 300 24 407 (NOP 1111**) SCR 300 24 407 SCR 300 CNOP 1111**) SCR 300 CNOP 1111** SC

For versions a and b flags 400...411 are used. Version c uses counter  $\underline{C301}$  as an output register. 14 flags 400...413 are used in version c to load the buffers.

<sup>\*</sup> For basic address 16.

<sup>\*\*</sup> PCA14 from version  $\overline{V6.034}$  onwards for a baud rate of 9600 bauds.

# B 1.1.16 Type PCA1.W4Ø Analog input module for temperature sensor PT 1ØØ

## Technical data

Number of inputs

6, electrically connected 2-, 3- or 4-wire technology,

independent of each other

Temperature sensor

PT 1ØØ

Measuring ranges

 $-20^{\circ}$ C to  $150^{\circ}$ C or  $0^{\circ}$  to  $400^{\circ}$ C <sup>1)</sup>

Resolution

8 bits  $(1/256 \triangleq \emptyset, 4\%)$ 

Accuracy (absolute deviation)

3 bits (\( \text{1.2\%}\)

Power supply per sensor

2mA

Time constant

dependent on the sensor response time

Internal power requirement 5V

4ØmA 4ØmA

24V

1) Measuring range selectable by jumpers:

Measuring range	Jumpers	
-20°C to 150°C 0°C to 400°C	A ; D (factory setting) B ; C	

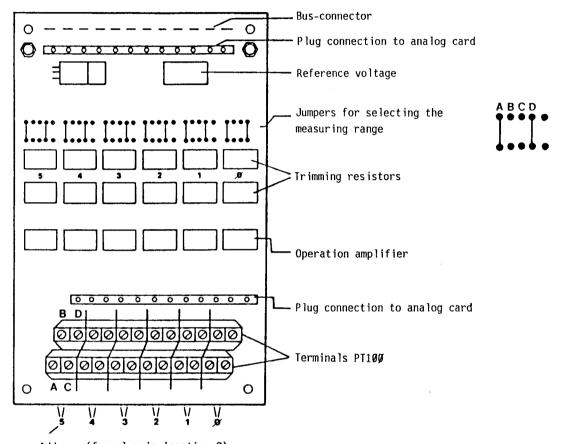
# Resistance table PT 100/binary value PCA1.W40

Sensor	Sensor	Binary value	
temp.	res. R	Meas. range	Meas. range
°C	Ω	-20°C - 150°C	ذC - 400°C
-2Ø	92.2	Ø	(Ø)
Ø	100.0	3Ø	Ø
65	125.15	128	42
15Ø	157.28	255	96
200	175.76	( <u>255</u> )	128
400	246.60	(255)	255

## **Presentation**

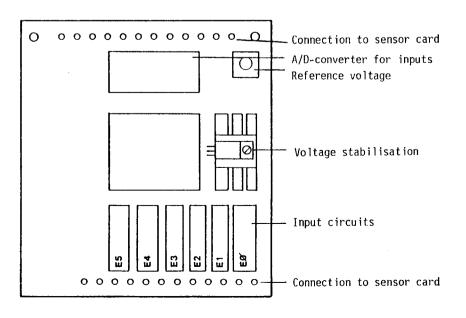
The analog module for the PT 100 temperature sensor consists of two pc-boards arranged on top of one another.

Sensor adapter card (lower)

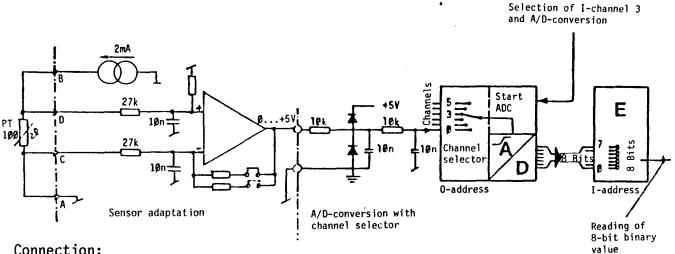


Address (for plug-in location Ø)

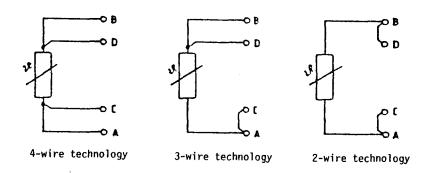
## Analog/digital card (upper)



#### Input/output circuit and block circuit diagram



# Connection:



## Programming example for address range Ø...7

Reading in the analog input value at channel 3 (ADDR 3). The corresponding binary value is to be transferred to counter C260.

31) Select I-channel 3 and start A/D-conversion 100 OUT 260 1Ø1 SCR Read binary value of 8 bits to counter C260 102 24 71)

Please note the basic address, i.e. on which location the module is mounted.

Example with basic address 24: OUT TUO 🖚 27 (24+3) 3 -

> SCR 26∅ — ➤ SCR 26∅ **→** 24 31 (24+7)

## B 1.1.17 Type PCA1.F11/F12 Preselector module for entering numerical values

#### Application

With the preselector module numerical values can directly be entered without external wiring. If they are transmitted to the non-retentive flags or to counter registers, these values can be used as times, counter states or preselections of analog values.

#### Technical data

Number of input circuits

8

Range of digital values

ØØ...99

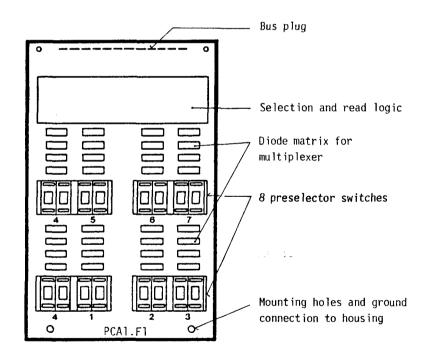
Input mode

Multiplex

Internal power consumption of the module (5V)

3ØmA

## Presentation and switch allocation

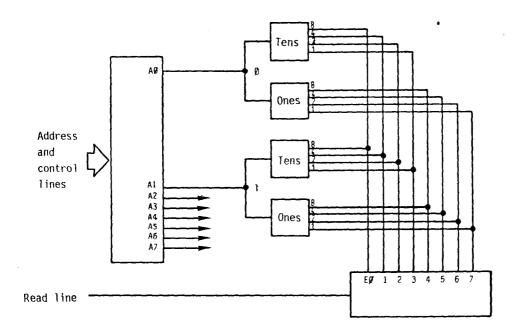


The following versions are available:

- PCA1.F11 with 4 pairs of preselectors, addresses  $\emptyset...3$
- PCA1.F12 with 8 pairs of preselectors, addresses Ø...7

Due to removable BCD switches on sockets, every desired combination is feasible.

#### Principle scheme



The allocated pair of preselector switches (ones and tens) is activated by setting of output  $A\emptyset...A7$ . The preselected value can be read from the 8 address elements  $E\emptyset...E7$  and afterwards be written on a non-retentive flag or be loaded into the desired register by a set timer or set counter operation. The activated outputs have to be reset afterwards.

#### Programming example:

The preselector module uses the address range 24...31.

a) The 2-digit value selected by preselector 2 shall now be read and loaded into counter register 262.

```
(SEA Ø)
SEO 26; Setting the pair of preselector switches (addr. 24+2)
SCR 262; Setting the counter with
16 31; BCD-input x 1
REO 26; Resetting the pair of preselector switches
```

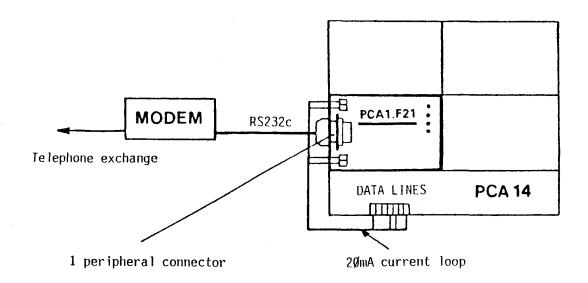
b) The value of pair 6 of the preselector switches shall be loaded into non-retentive flags 424...431.

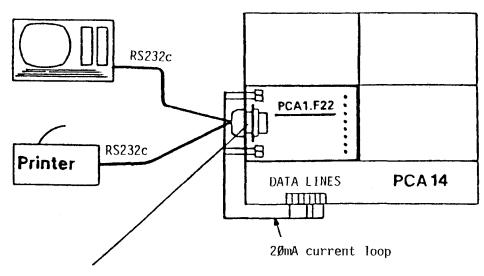
```
(SEA Ø)
SEO 3Ø; Setting the pair of preselector switches (addr. 24+6)
SEI Ø
STH 1024
OUT 1424
INI 7
JIO 7
REO 30; Resetting the pair of preselector switches
```

#### B 1.1.18 Type PCA1.F21/PCA1.F22 Data line switching module (only PCA14)

#### **Application**

The module PCA1.F21 is fitted with one, the module PCA1.F22 with two serial interfaces of the type RS 232c. Via the DATA LINES of the CPU PCA1.M4.. data can be transferred between the SAIA°PLC and the peripheral units connected to the PCA1.F2. The module PCA1.F21 is particularly suitable for connection to a modem.





2 peripheral connectors one above the other

## Technical data

	PCA1.F21		PCA1.F22
Number of peripheral interfaces	1		2
Type of interface	RS 232c	1	RS 232c
Used addresses	8		8
Data transfer	The data transfer is performed between the CPU PCA1.M4 via PCA1.F21/F22 and the connected peripheral units.		
Management of the peri- peral interfaces	By means correspon	of the user produced	ogram with the nd status signals
Number of control and	Total 6		
status signals per peripheral interface	CTS DSR DCD Re	adable signals	(status signals)
	RTS DTR ADC Se	ttable signals	(control signals)
Transmission speed	110 to max. 9600 bauds*, defined in the software by the PAS 100 instruction		
Signal level of the data lines (according to standard RS 232c)	"L" : + 12V "H" : - 12V		
Level of control and status signals (acc. to standard RS 232c)	"L" : - 12V "H" : + 12V		
Connector for RS 232c	25-pole miniature connector, female (for details refer to section "Pin assignment")		
Power consumption (internal)		F21	F22
	5 <b>V</b>	125 mA	23Ø mA
			<del>                                     </del>



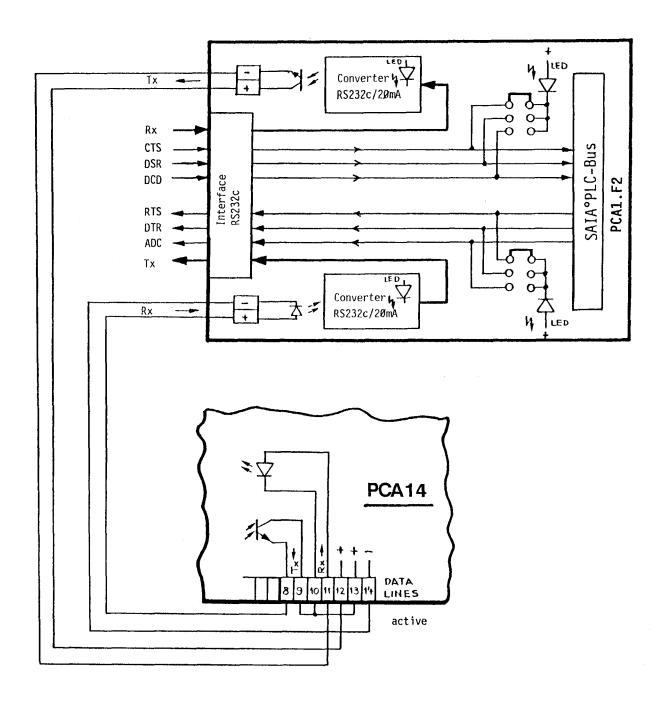
<sup>\*)</sup> High baud rates depend on the program structure.

## Presentation PCA1.F21 - Bus-connector 0000 - LED-displays Jumpers for selecting the displays of one control and status signal each Circuit Voltage supply ±12V for RS 232 c Transm./receiv. 2ØmA Screw terminals for connection for the 20mA-current loop of the PCA14 Mounting holes and ground connection to the housing Peripheral connector 1 PCA1.F22 00000000 -LED-displays for peripheral connector i Jumpers for selecting the displays of one control and status signal each for peripheral connector Ø Voltage for peripheral connector 1 Circuit supply ±12V for RS 232 c Transm./receiv. 2ØmA Screw terminals for connection for the 20mA-current loop of the PCA14 Mounting holes and ground connection to the housing -Peripheral connector Ø Peripheral connector 1

#### DATA LINES connection between PCA1.F2 and PCA14

Like an I/O-module, the module PCA1.F2 can be plugged into any location on the PCA14. Wiring must be effected in such a way that the 20mA-current loop of the PCA14 is active.

The external connection CPU ---> F2 is performed observing the same rules which apply to the cable layout of a 20mA-current loop. Two PCA1.F2-modules can be connected in series resulting in an increase of the number of interfaces to max. 4.



#### Address assignment and function of the signals

The peripheral interface of the PCA1.F21 or the two interfaces of the PCA1.F22 respectively must be managed by the user program. In order to make this possible, 3 status and 3 control signals each which can be set or read in the user program are available for each connector.

#### Address assignment

	Address *	Abbreviation	Treatment
	Ø	SEL Ø	Settable and readable
. Ø : only)	1	DTR DSR	Only settable Only readable
Connector (PCA1.F22	2	RTS CTS	Only settable Only readable
Con (PC	3	ADC DCD	Only settable Only readable
	4	SEL 1	Settable and readable
or 1	5	DTR DSR	Only settable Only readable
Connector	6	RTS CTS	Only settable Only readable
O	7	ADC DCD	Only settable Only readable

<sup>\*)</sup> The addresses are valid for the mounting location Ø. The respective basic address must be added for other locations.

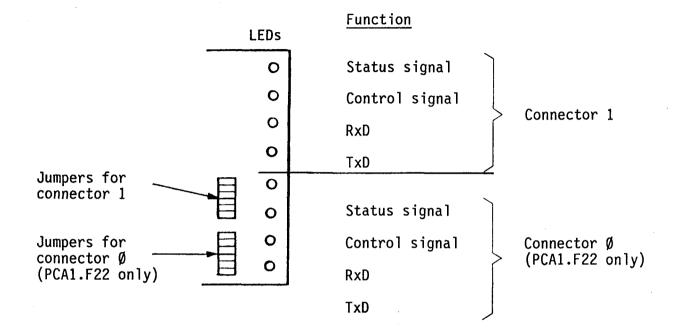


## Function of the control signals

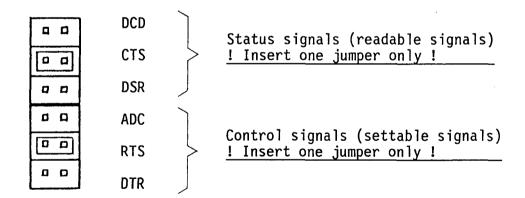
SEL Ø, 1 (Select)		With the instruction SEO SEL Ø, 1 the data lines (TxD, RxD) of the respective peripheral connector Ø or 1 are connected to the DATA LINES of the PCA14.  With the read commands (e.g. STH SEL Ø, 1) it can be determined which peripheral connector was connected to the DATA LINES.
DTR (Data Terminal Ready)  RTS (Request to Send)  ADC (Auto Dialer Control)	<u>}</u> 1)	These three signals are control signals as described in the standard RS 232c. They can be <u>set</u> in the user program, thus supplying certain instructions or states to the connected peripheral unit. The signals can be interpreted in different ways depending on the peripheral unit.
DSR (Data Set Ready)  CTS (Clear to Send)  DCD (Data Carrier Detect)	<u>}</u> 1)	These three signals are status signals as described in the standard RS 232c. They can be read in the user program. The individual signals are interpreted depending on the peripheral unit and must be processed correspondingly in the user program.

1) Similar to the input/output module PCA1.B9Ø two signals each use the same address. (DTR/DSR, RTS/CTS, ADC/DCD). Consequently, one signal can only be set, the other one can only be read (see also "Address assignment").

#### Meaning of the LEDs



Jumpers for status and control signals:



For each connector 1 status signal and 1 control signal each can be displayed on the corresponding LED. The jumpers can be reinserted during operation, which permits checking the function of the connected peripheral unit.

If no jumper is inserted for the status or control signals, the corresponding LED is permanently illuminated.

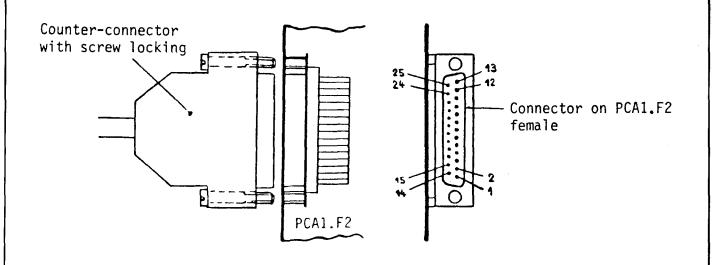
The LEDs "TxD" and "RxD" light up, if data is being transmitted or received. Depending on the baud rate and telegram length only a short flash or a long flickering is recognized.

#### RS 232c interface cable

The standardized guidelines hold true for laying the signal cable of the RS 232c, i.e. screened cable with a max. length of 15m (if possible not in the same cable duct as the power cables).

## Pin assignment (according to RS 232c)

Pin no.	Abbreviation	Signal name	Direction of signal
			Periph. PLC
1	PGN	Protective Ground	
2	TxD	Transmitted Data	
3	RxD	Received Data	
4	RTS	Request to Send	
5	CTS	Clear to Send	
6	DSR	Data Set Ready	
7	SGN	Signal Ground	
8	DCD	Data Carrier Detect	
9	ADC	Auto Dialer Control	
2Ø	DTR	Data Terminal Ready	
18	- 12V	Imax: 5mA	
21	+ 12V	Imax: 5mA	

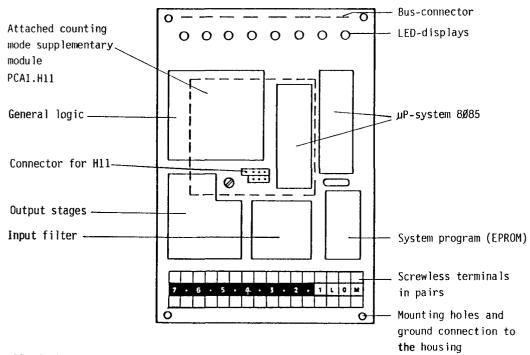


## B 1.1.19 Type PCA1.H1.. Rapid counter or pulse generator up to 10kHz, 6 decades

#### **Applications**

- Counting of pulses up to a frequency of 10kHz: For example, from pulse generators, which are used for the determination of angles of rotation, throughput quantities, number of items or digital lengths.
- Recognition of the sense of rotation with 2-channel incremental shaft encoders: For example, for positioning with DC-current motors and connected pulse generators.
- Output of control pulses (2-fold): This allows positioning of x-y-tables, palletizing devices, handling robots with an appropriate stepping motor control.
- Measuring of frequencies, period lengths or pulse lengths, e.g. for determining the speed, number of revolutions, flow, synchronization, frequency, etc.
- Output of register contents to display modules PCA2.D12 (4 decades) or PCA2.D14 (2 x 6 decades).

#### Presentation



#### Detailed documentation and software modules

The detailed manual is available in German and English and consists of about 100 pages.

It also includes software modules and practical examples of application. The software modules may also be used as macros for the SAIA°PCA ASSEMBLER.

Please contact our selling agencies.

#### Technical data

#### Counter module PCA1.H1#

Number of counting systems	1
Counting frequency	max. 10kHz
Counting capacity	max. 9991999 (6 decades)
Counting direction	up and down
Data memory	volatile (data can be saved via CPU-registers)
Counter state display	with 2 display modules PCA2.D12
Inputs	- clock for counting pulses - up/down for counting direction
	Display of the logic states by 2 LEDs
	24VDC/10mA, source or sink operation input delay 50µs
Outputs	Direct coincidence outputs  - COOR: Low if Z = R  - COOØ: Low if Z = Ø  High by setting in the user program
	Outputs comparator or display mode  - Z > R  - Z = R  - Z < R  - Z = Ø  Display mode selectable via user program
	Display of the logic states by 6 LEDs
	532VDC/500mA, positive switching load resistance min. 48 $\Omega$ for 524V
Connection	Pairs of screwless terminals

## Counting mode supplementary module PCA1.H11

(can be plugged onto counter module)

Counting modes	<pre>phase decoder (M1) or up/down mode (M2), can be selected by plug-in jumpers</pre>	
Phase decoder (M1) 2-phase at inputs A and B, type o pulse processing (x1, x2, x4) selectable with plug-in jumpers		
Up/down mode (M2)	Pulses at input A counting up, Pulses at input B counting down	
Inputs A and B	24VDC/10mA, source or sink operation input delay 50μs	
Counting frequency max. 10kHz		

# Counter module PCA1.H1Ø as pulse generator

(the same module functions either as counter or pulse generator)

Number of channels	2
Frequency	max. 10kHz
Frequency selection	via user program divisible into steps of approx. 5%
Stability	better than <b>0.1%</b> above the temperature range
Signal	symmetrical square-wave signal
Start generator	via the user program
Stop generator	after output of the programmed number of pulses or via inputs stop
Single pulse	via user program pulse length according to the programmed frequency
Outputs	- FØ1: Generator 1 - FØ2: Generator 2
	Supply voltage 532VDC/500mA, positive switching

# Counter module PCA1.H1# as measuring module

(identical hardware)

Number of channels	2	
Measuring frequency	max. 5kHz	
Accuracy	1%o (25°C)	
Modes (software)	- Frequency measurement - Period length measurement - Pulse measurement	
Frequency measurement	Duration 6-digit in ms	
Period length	Number of periods to be measured, 6-digit	
Pulse length	Number of pulses to be measured, 6-digit	
Inputs	E1 signal input	
Outputs	A7 duration of measurement A6 overflow	

#### Available versions

PCA1.H1# Counter module for deries PCA1
(alternatively usable as pulse generator)
PCA1.H11 Counting mode supplementary module (delivered separately)

In order to diminish the internal power consumption (at 5V) from 350mA to 190mA, a special version using CMOS technology was developed. It is referred to as PCA1.H10 Z16. This is now the standard version.



## B 1.2 Internal power requirement of the PCA1 modules

The internal power supply for 5V and 24VDC is provided by the power supply unit in the basic module or extension module respectively. The total current required for CPU, I/O-modules and programming or display module must not exceed the nominal power handling capacity.

Nominal power handling capacity of the internal power supply and constant loads of CPU, D11, D13, P10 and P05.

Nominal power handling capacity of the power supplies of PCA1.M4, M5, C45	5V side mA <u>1'700</u>	24V side mA <u>8</u> ØØ
Power requirement CPU M4  CPU M5 Extension C45 *	6ØØ 45Ø 9Ø	Ø Ø Ø
Power requirement D11 D13 (D12) (P10) (P05)	100 10 0 (200) (150)	Ø Ø external Ø Ø

<sup>\*)</sup> It must be noted that the ..C45 extension is able to supply about 500mA more current than the M4/M5 modules, because of the removal of the  $\overline{\text{CPU}}$  on the 5V side.

## Power requirement of the PCA1 I/O-modules

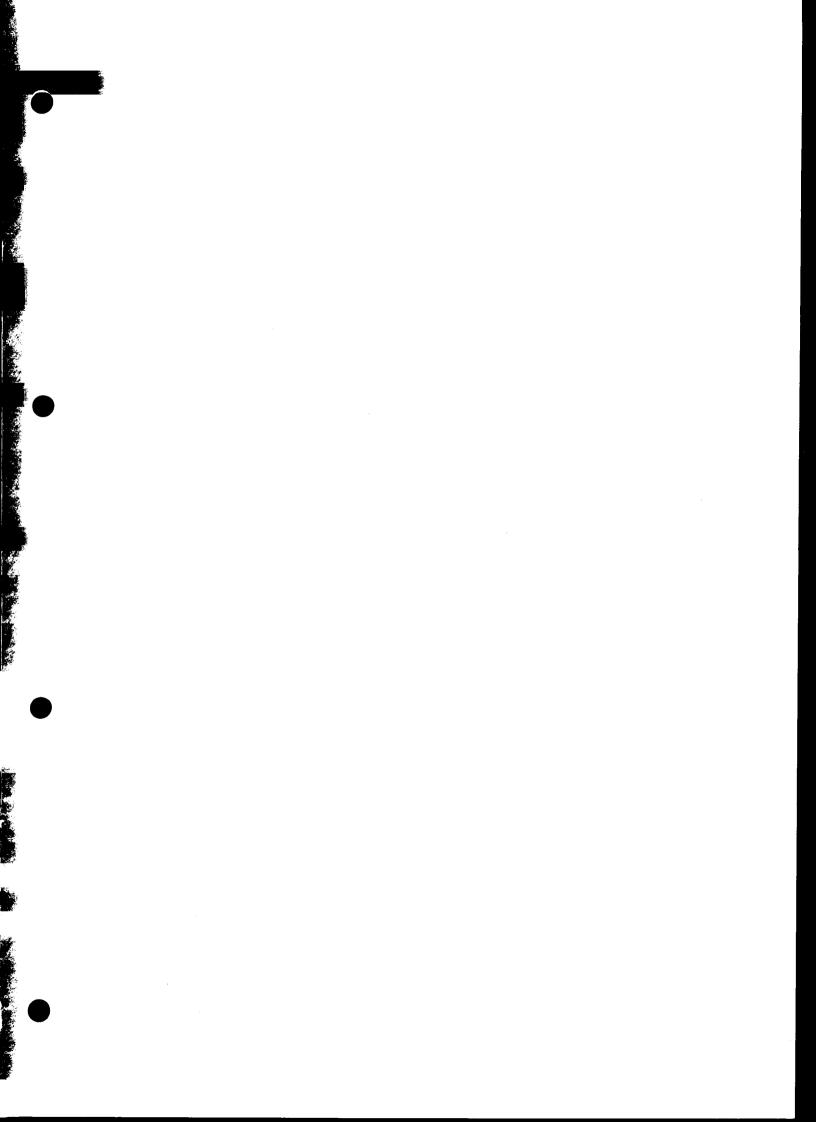
Series	I at	5V (A)	I at	25V (A)
PCA1	H (max.)	L (min.)	H (max.)	L (min.)
E1Ø/E11 E2Ø E4Ø E5Ø	68 7Ø 7Ø 68	11 1Ø 15 11	Ø Ø Ø	Ø Ø Ø
A1Ø	146	86	7	18
A21	9Ø	34	14Ø	Ø
A3Ø	1ØØ	26	7	7
A5Ø	9Ø	35	3Ø	Ø
B1Ø	112	54	4	9
B8Ø	120	3Ø	Ø	Ø
B9Ø	105	5Ø	5Ø	5Ø
F12	3Ø	3Ø	Ø	Ø
F21	125	125	25	25
F22	23Ø	23Ø	45	45
W12	4Ø	3Ø	25	25
W24	7Ø	6Ø	70	<b>40</b>
W32	12Ø	1ØØ	100	<b>60</b>
W4Ø	appr. 4Ø	appr. 4Ø	appr. 40	appr. 40
H1Ø Z16	19Ø	19Ø	55	55
H1Ø	35Ø	35Ø	55	55
H11	22	22		
R2Ø	85	85		- <i>-</i>
R2Ø + R25	95	95		

H: all LED are on or max.
L: all LED are off or min.

## Example:

	5Ø% I/O = H		
	5V/mA	24V/mA	
PCA1.M47 4 x B9Ø 2 x A1Ø 2 x A21 1 x P1Ø	600 210 + 100 146 + 86 90 + 34 200	Ø 1ØØ + 1ØØ 7 + 18 14Ø Ø	
TOTAL	1466 mA	365 mA	

(< 1700 mA) (< 800 mA)



### B 2 Programming units, additional units and accessories

### Additional units used for programming (simulation, starting-up, documentation)

PØ5	Hand-held programming unit	PCA2.PØ5
PØ1	Programming interface	PCAØ.PØ1
S1Ø	Input simulation unit	PCA2.S1Ø
K8Ø	Cable	PCA1.K8Ø
SØ5	Input simulation unit	PCA2.SØ5
P18	Programming unit	PCA2.P18
<b>PCASS</b>	SAIA°PCA AŠSEMBLER	PCASS
P16	EPROM-Kopiergerät	PCA2.P16

#### Memory modules

R95	Memory module 4K, non-volatile	PCA1.R95
R96	Memory module 4K, non-volatile	PCA1.R96
R2Ø	Text memory extension module	PCA1.R2Ø
R25	Data memory extension module	PCA1.R25

#### Display modules

D11	Display module, 4-digit	PCA1.D11
D12	Display module (remote display), 4-digit	PCA2.D12
D13	Display interface for D12	PCA1.D13
D14	Display module (remote display), 2x6-digit	PCA2.D14

## External interface module, type KOM

KOM 111B	Dual-input interface,	220 VAC,	type D4,	output 24VDC/40mA
	pulsating per input			

KOM 111B Dual-input interface, 110 VAC, type C8, output 24VDC/40mA pulsating per input

## KOM 121B Dual-relay output interface, type M4

Switching power AC1: 6A, 25Ø VAC (per output) AC11: 1A, 25Ø VAC (per output)

#### B 2.1 Programming units

#### B 2.1.1 Hand-held programming unit PCA2.PØ5

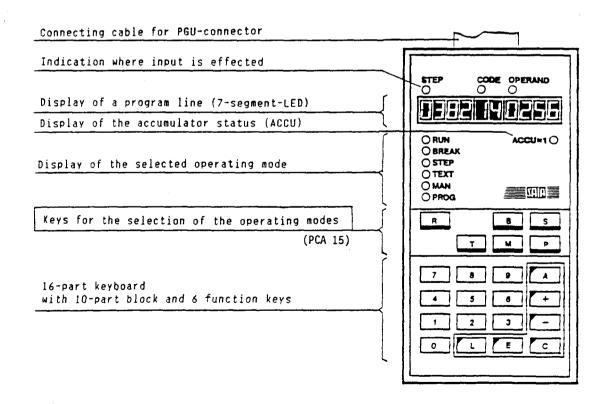
This compact programming unit was developed in particular for the series PCAØ, but it can also be used for the series PCA1 and PCA2.

All operating modes can be selected with keys. Programming is performed in the "PROG"-operating mode by means of a 10-part keyboard in simple numerical code. All elements (inputs, outputs, flags, timers, counters) can be queried or set in the "MAN"-operating mode.

All timer and counter values can be indicated in the RUN-mode. In the operating mode "STEP" a jump can be effected to any program line (= step address) of the user memory. Finally, "BREAK" permits the program processing up to a set break-point and continuation in step-by-step operation. For details refer to chapter C "Operating modes".

It must be noted that the keys for selecting the operating modes must be pressed at least  $\emptyset.5s$  for safety reasons. The selected mode is displayed by the corresponding LED.

In the case of PCA14, the operating modes are selected with the sliding switch on the basic module.



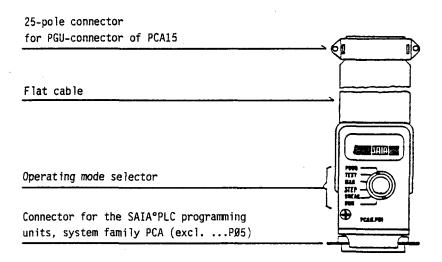
#### B 2.1.2 Programming interface PCAØ.PØ1 for PCA15

This interface allows connection of the following SAIA°PLC programming units to the series PCA15:

PCA2.P18 - Hand-held computer with a wide range of possibilities (from software version V18-Ø4 onwards)

PCASS - IBM-PC with SAIA°PCA-ASSEMBLER

As a result, all upwards compatible tools of the SAIA°PLC, system family PCA, are available also for the PCA15.

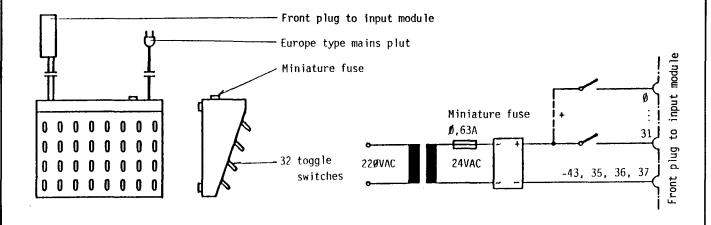


#### B 2.1.3 PCA2.S1Ø Input simulation unit

Its purpose is to simulate input signals via toggle switches so that a program can be tested "at the desk". This considerably facilitates the commissioning of the actual control system.

A transformer with rectifier is supplied from a mains cable. From the rectifier is a branch to 32 numbered toggle switches, the signals from which are fed to the PLC inputs via a system cable and plug.

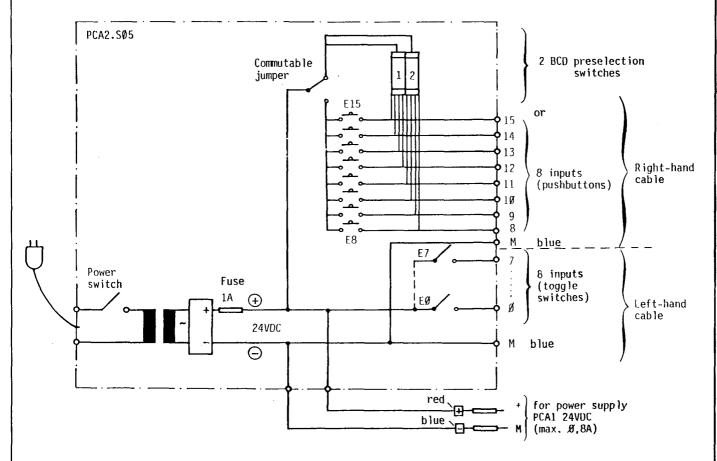
Ordering designation for connection to 220VAC: PCA2.S10 D4



#### B 2.1.4 PCA2.SØ5 Input simulation and supply module

Ordering designation for connection to 220VAC: PCA2.SØ5 D4

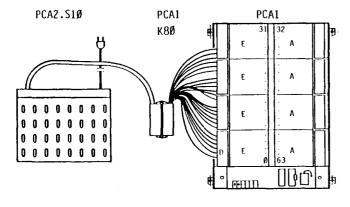
The housing is identical to that of the S10, except that it has an integrated supply of 24VDC and a pair of BCD-switches for entering numerical values. A reversing switch also allows using the pulse keys. Direct connection of cables to inputs (see also dimensional diagram, chapter B 2.4).

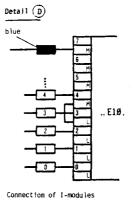


### Intermediate cable type PCA1.K8Ø for PCA2.S1Ø

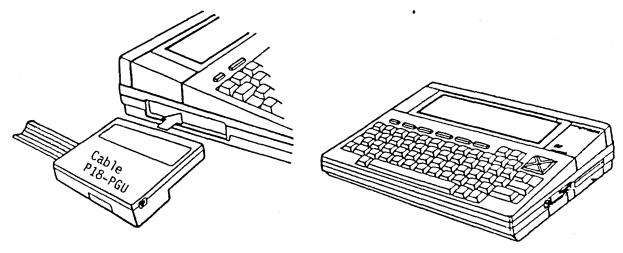
The cable K8Ø is connected to the connector of the S1Ø-device and led out via 33 pins with the aid of hardened steel pins. Each of these pins can be plugged into the I-terminals and removed without tools.

The K8Ø-cable can be used for all input modules (E1Ø, E11, E2Ø, E4Ø und B1Ø, B8Ø, B9Ø). However, the respective bridge circuit of the minus (M, L or -) must be observed.





#### B 2.1.5 Programming unit PCA2.P18



#### Brief description

The programming unit PCA2.P18 is a compact and versatile means which can be used for programming all SAIA°PLC as well as for servicing.

The P18 uses the commercial hand-held computer, type NEC 82Ø1A, as hardware. Compactness combined with a high degree of intelligence, an efficient firmware and a variety of peripherals form an ideal portable programming unit, be it on your desk or out in the field.

With the SAIA°PLC connected (via PGU-connector), the P18 makes programming very easy. Moreover, SAIA°PLC texts can be edited or all PLC-registers can be accessed on-line for servicing purposes via the 20mA-data line of the PCA14 and PCA15.

In short, the following functions are possible:

- Programming in numerical or mnemonic code
- Display of program sections and texts
- Search functions
- Storage and loading of user programs and texts
- Printing of programs (on an external printer)
- Editing and output of SAIA°PLC texts
- Acces to data and registers of the SAIA PLC while user program is running.

Thanks to the permanently stored BASIC-interpreter and the text processing program, the P18 can also be used as a portable personal computer. Numerous additional interfaces and the corresponding software support communication with peripheral units such as printer, modem, tape unit, disk drive unit and bar code reader.

A detailed description is supplied with each unit.

#### B 2.1.6 SAIA°PCA ASSEMBLER

The software package SAIA°PCA ASSEMBLER for comfortable programming, documentation and starting-up

The PCA-ASSEMBLER makes programming of the PCA-family of controllers very easy. The user is efficiently supported in his work by practical menus and the appropriate auxiliary pages which means that he virtually does not require a manual or a knowledge of MS-DOS.

The user program is written in the so-called "Editor" using a conventional text processing program (e.g. Personal Editor or Wordstar). It is possible to use practice-oriented designations for the operands to mark jumps in the form of symbols and labels which are then converted to a PCA-program by the actual "Assembler" and "Linker". Macros with parameters can be implemented for frequently used routines and comments can be used for clearly documenting the new program.

Further possibilities of the new PCA assembler include the modular and global documentation, presentation as flow-charts, an efficient cross-reference list and it is also possible to load the program directly into the RAM-memory of the PCA.

Its advantages become obvious particularly when the controller is started up. In RUN-mode the "Online Debugger" allows the actual states of elements such as inputs, outputs, flags, timers, counters, registers and the date-time to be displayed and also modified. The programs "P10" and "CI" permit direct access to the RAM user memory of all PCAs. By selecting the submenu "Program eproms", tested user programs can be directly loaded into the EPROM programming units PCA2.P16 or ERTEC PGS49.

The software package SAIA°PCA ASSEMBLER can be run on all IBM-PC/XT/AT or PS/2 or compatible units which fulfil the following conditions:

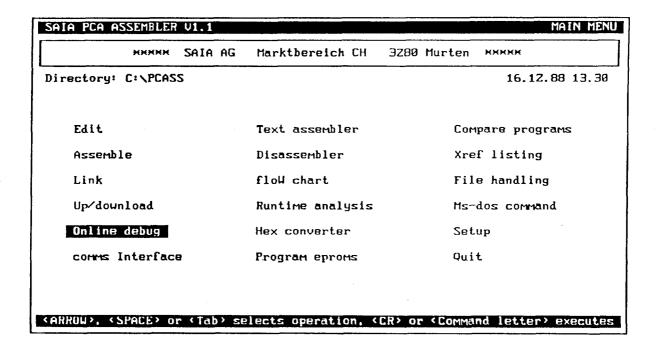
- 512 Kbyte main memory
- 2 floppy disk drives of 360K or even better 1 floppy disk drive and a hard disk
- 1 or even better 2 bidirectional, parallel interfaces for controlling a printer and for connection to the PGU-connector of the PCA
- Monochrome or colour VDU (with MCGA, CGA, EGA, VGA or Hercules cards)
- Keyboard as desired
- Operating system MS-DOS 3.0 or a higher version
- Cable PCA2.K43 for connection to the PGU-connector of the PCA
- Text processing program as desired (Personal Editor and Wordstar are recommended)

A detailed description is available for every software package.

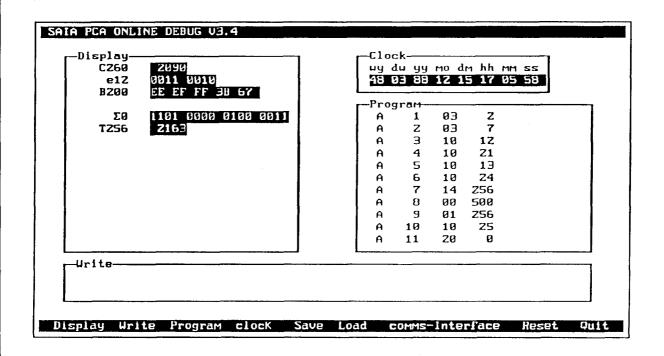


#### Screen

### Main menu of PCA-ASSEMBLER

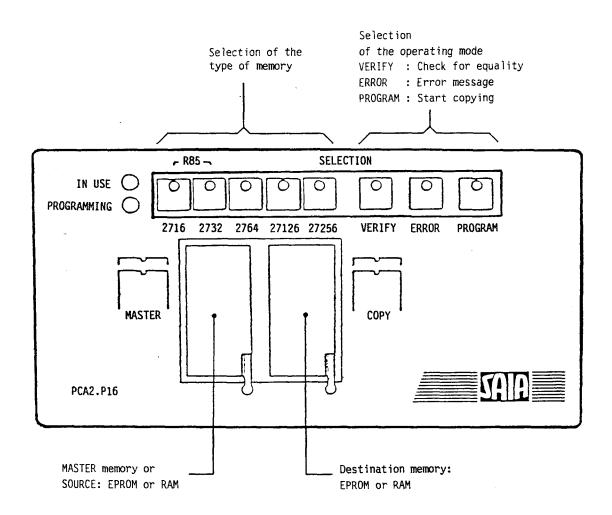


#### ONLINE DEBUG menu of PCA-ASSEMBLER



#### B 2.1.7 Type PCA2.P16 EPROM-copying unit

Owing to two high- quality sockets (Texttool) the unit can be used for copying and comparing EPROMs and buffered RAMs independently of other units. The serial interface RS 232c permits connection of any commercial personal computer. A program supporting operation of the P16 from the IBM-PC is part of the PCA-assembler (package no. 3).



The P16 meets especially the requirements of the SAIA°PLC. In addition to the usual EPROM types 2716 to 27256, the buffered RAMs PCA1.R95 and PCA1.R96 can be written to and read.

#### Technical data

Supply voltage 220 VAC 50 Hz  $\pm$  10% Power requirement 20 VA Microprocessor MC 6809 Serial interface RS 232c (9600, 2400, 1200 and 300 bauds) Dimensions 222 x 47 x 172 mm (W x H x D) Weight 1.7 kg

With the P16 the following memory modules can be programmed:

Туре	Programming		voltage:
2716 2732	25V 25V	1) 3)	
2732A 2764 27128	21V 21V 21V	1)	
27256 2816	21V	2) 3)	
PCA1.R95 (buffered RAM) PCA1.R96 (buffered RAM)		•	

1) For the type 2732A the P16 has been set to a programming voltage of 21V (factory setting).

For the type 2732 which has a programming voltage of 25V, a jumper needs to be re-soldered on the pc-board EP 8Ø Ø67.

2) For the type 27256, which has a programming voltage of 12.5V, the resistor

R3 (3k6) needs to be changed to 2k on the pc-board EP 80 066.

3) Do not use with SAIA°PLC.

#### Copying

During copying, data is read from a master-IC and written to a copying-IC. When working without the Personal Computer, i.e. without using the serial interface, copying can usually be performed only using the same types of EPROM. However, mixed operation is possible using the EPROM 2764 and buffered RAMs PCA2.R95 or PCA2.R96. Only the <a href="mailto:entire memory contents">entire memory contents</a> can be copied from the MASTER socket to the COPY socket.

- 1. Select the copying EPROM with the appropriate key. The corresponding LED lights up. For the EPROM-emulators R95 and R96 the keys 2716 and 2732 must be pressed simultaneously.
- 2. Insert the master-IC and the copy-IC in the frames. Take care that the notch or pin 1 respectively is at the top on the left.

  The ICs are retained in the frames by pressing down the levers. In the case of the 24-pole ICs it must be noted that the <u>upper</u> contact openings must not be covered.

3. Press key "PROGRAM". The LED "IN USE" lights up for a short time. During this time a check is performed to determine whether the memory module to be programmed has been erased. Afterwards the LED "PROGRAMMING" also lights up until programming is finished. Any errors which occur during programming, are displayed by the flashing LED "ERROR". Moreover, an LED lights up in the keys indicating the type of error.

#### Error messages

Key 2716 : EPROM cannot be programmed
Key 2732 : EPROM has not been erased

Key 2764: EPROMs are different

Key 27128: EPROMs are different and copy-IC empty

Key 27256: 2816 cannot be erased

The error display is cleared with the key "ERROR".

#### Comparing

The procedure is similar to copying. However, The LED "PROGRAMMING" does not light up. Proceed as follows:

- 1. Select copying-EPROM with the appropriate key.
- 2. Press key 'VERIFY'.

If no error message appears, the contents of the two memory modules are the same. The flashing LED "ERROR" indicates an error (see list of errors).

#### Erasing the 2816 (EEPROM)

In order to erase the 2816, press the key 'ERROR' and '2716' simultaneously.

Important: The memory module 2816 cannot be used together with the SAIA°PLC.

#### Serial interface RS 232c

The integrated serial interface offers the experienced user manifold possibililities of programming the P16 from a Personal Computer. See also chapter B.6 of the manual PCA2.P16.

When the PCA2.K46 cable is used, the transfer of data is supported under menuguidance by the SAIA°PCA ASSEMBLER with the "Program eproms" program.

#### B 2.1.8 Type PCA1.R95/R96 Buffered RAM chip

RAM-memories are read-/write-memories, which means that the information can be modified at any time with the aid of a programming unit (as data memory in the PCA14 also via the user program).

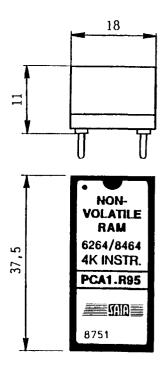
The buffered RAM chip is the ideal memory chip serving as a program and text memory from the programming stage to the start-up. Owing to the incorporated buffer battery and the protective electronic system this memory chip can be detached from the PLC and transported without modifying its contents.

The slightly conductive plastic socket protects the pins against static charges, thus avoiding memory content changes. The internal battery is thereby not discharged.

Memory type	PCA1.R95	PCA1.R96
Storage capacity		
- Program lines - Texts, data	4K 8K	4K 8K
Number of pins	28	28
Buffer battery life	approx. 8 years	approx. 6 years

Application in PCA14/15, PCAØ and PCA2.

#### Presentation



## B 2.1.9 Type PCA1.R2Ø Text memory extension module, 32 characters (for PCA14 as of version V6.Ø34)

The text memory card PCA1.R2Ø increases the storage capacity for texts five-fold. In addition, the text memory module offers the possibility of reserving the whole memory mounted in the CPU for user steps or as data memory and of storing all texts on the text module.

#### Technical data

Text capacity

4 x 8K characters = 32K text characters

Types of memory (sockets)

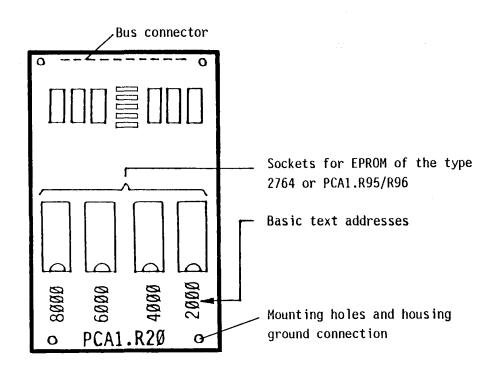
- for buffered RAM-memory PCA1.R95 or R96

- for EPROM type 2764 (order no. 4'502'4719'0)

Mounting of module

like I/O-module, however, only on socket ∅

#### Presentation



The module PCA1.R2Ø must always be mounted on socket Ø of the PCA14 (addresses  $\emptyset...7$ )!

#### Memory structure

Memory socket	TEXT ADDRESSES not indexed	TEXT ADDRESSES indexed	
Right socket on the CPU	0 - 818	1000 - 1818 1)	as usual
Socket 2000 on R20	2000 - 2818	3000 - 3818	
Socket 4000 on R20	4ØØØ - 4818	5ØØØ - 5818	
Socket 6000 on R20	6ØØØ - 6818	7000 - 7818	
Socket 8000 on R20	8ØØØ - 8818 <sup>2)</sup>	9000 - 9818	

Compared to the normal text address assignment on the CPU ( $\emptyset$ ...818), the addresses on the R2Ø module are increased by 2ØØØ to 8ØØØ (depending on the socket). The following footnotes should be read for indexed text output and limit addresses.

2) Starting with text address 8192 the text number can no longer be entered directly in PAS 23, the multiple of 2 K must rather be entered in the code and the remainder in the operand.

	Code	Operand	
Example: text no. 8400	PAS	23	
	<b>Ø</b> 4	Ø2Ø8 ; (4 x 2Ø48) + 2Ø8	= 8400

<sup>1)</sup> As is known, texts may be output in indexed form. For <u>text subroutines</u> (CPU socket) in the address range  $\emptyset...818$  only 3 figures are available for addressing. Details see manual "PCA Software level c", chapter "Text output".

#### Text input

A text input effected directly on the PCA1.R2Ø card is not provided for. There are two possibilities of entering texts:

- 1. Using PCA14. Texts are entered into a buffered RAM-memory module (R95 or R96), which is located on the right socket of the CPU. Therefore, the text addresses  $\emptyset$ ...818 are used. Upon termination of the input, the memory module is plugged into the corresponding address location on the R2 $\emptyset$  module.
- 2. Using the text assembler of the SAIA°PCA ASSEMBLER and the PCA2.P16 EPROM copying unit or the programming unit PCA2.P21.

  Proceed as described under 1.

Text output (call text in the user program with PAS 23)

When calling the text, the basic addresses of the text (2000 to 8000) must be added in the 2nd line of the PAS 23 instruction in accordance with the selected socket. For indexed text calls those basic addresses exceed the basic addresses by 1000 (3000 to 9000), see description in chapter "Memory structure".

#### Important notes:

- a) Text stored on the PCA1.R20 module are addressed using 4 digits. It must be noted for text subroutines that \$L must always be followed by 4 digits.
- b) A text subroutine which uses the addresses 2000...8818 cannot be called by a text using the addresses 0...818. However, a subroutine in the address range 0...818 can be called by a text in the address range 2000...8818, whereby the subroutine address must be entered using 4 digits (e.g. \$L 0412).

#### B 2.1.10 Type PCA1.R25 Data memory extension module, 16K words

The PCA1.R25 module serves as an additional module for the text memory extension module PCA1.R2 $\emptyset$ . It has a large buffered data memory of 16K words of 16 bits each.

#### Technical data

Data memory capacity

Type of memory

Firmware version

Mounting of module

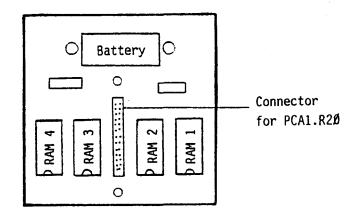
16K words of 16 bits each

RAM, battery-buffered with PAS 58 instructions, for writing and reading (16 bits)

PCA14 from version V6.036 onwards

on module R2Ø, on socket Ø

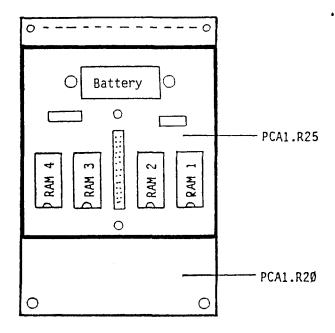
#### Presentation



#### Memory organization

	Word address (16 bits)
RAM 1	Ø 4Ø95
RAM 2	4Ø96 8191
RAM 3	8192 12287
RAM 4	12288 16383

#### Mounting on text memory extension module PCA1.R2Ø



The data memory module PCA1.R25 is plugged onto the text memory extension module PCA1.R20 and fastened with 2 screws. Due to the module R20 + R25, the PCA14 is additionally provided with a text memory of 32K ASCII-characters and a data memory of 16K words or 32K bytes.

#### Buffer battery

When the PCA14 is switched off, the NiCd battery protects the RAM-memory against data loss for at least 2 months (battery completely charged).

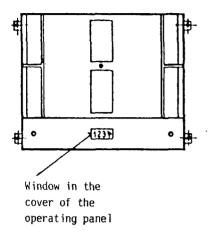
The pluggable battery lasts at least 5 years. Spare part no. 4'507'1360'0.

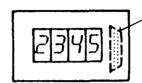
In order to prevent data loss on the R25 when replacing the battery, proceed as follows:

- 1. Switch off PCA14
- Remove cover above the inputs/outputs
- 3. Switch on PCA14
- 4. Remove old battery
- 5. Install new battery
- 6. Check data on R25
- 7. Leave the PCA14 switched on for several hours (charging of battery!)

#### B 2.2 Display modules

#### B 2.2.1 PCA1.D11 Operand display module





For PGU-connector on the operating panel

PCA1.D11 module, attachable to the operating panel

## Description:

With the two instructions

- DTC: Display Timer or Counter

- DOP: Display Operand

4-digit figures can be displayed in the RUN-mode. Thus, counter states (as well as step numbers), timers or, with the DOP-instruction, operands (e.g. as error numbers) can be displayed elegantly without using inputs or outputs.

Depending on the user program the following displays are possible:

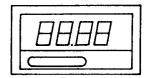
- fixed display according to the user software

- various displays selectable by selector switch

- various displays periodically altering

#### B 2.2.2 PCA2.D12 Display module

#### General



The PCA2.D12 module is a remote display which can be controlled via SAIA°PLC outputs. It has a 4-digit display and is able to indicate a decimal point. The display can be built in anywhere at a greater distance to the PLC e.g. in the door of a control cabinet or an operating panel. Due to data transmission being effected via outputs, several displays can be controlled by one PLC. In conjunction with the display interface PCA1/2.D13 the D12 can be connected even at a greater distance to the PGU-connector where the comfortable instructions DTC and DOP are available.

#### Structure, function

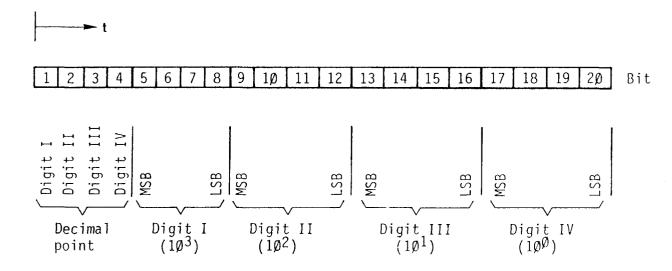
The module is in the same housing as the electronic totalizing counter of the CKG type. It consists of the following main components:

- power supply 24VDC
- 3 inputs for 24VDC
- decoder/driver
- 4-digit, 7-segment display with decimal point

The 3 outputs of the PLC resp. the 3 inputs of the display are designated "Enable", "Data" and "Clock". The <u>Enable signal</u> activates the display, i.e. Enable = "L" --> display is able to receive data, Enable = "H" --> display is inactive (it is not able to receive new data). Via the "DATA" line data in BCD-format is transmitted sequentially, i.e. bit by bit from the SAIA°PLC to the display. The display accepts each bit with the falling edge of the "Clock" signal.

For a complete indication (4 digits with or without decimal point) always  $2\emptyset$  clock signals must be generated and  $2\emptyset$  data bits must be transmitted (4 BCD-values + 4 bits for the decimal point).

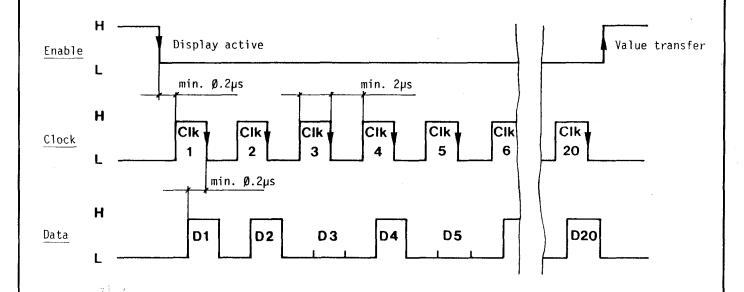
The following sequence of the 20 data bits must be adhered to:



The following 16 characters can be presented per segment:

Character	<u>Code</u>	Character	<u>Code</u>	
Ø 1 2 3 4 5 6 7 8 9	9999 9991 9919 9911 9199 9191 9119 9111 1999	∏ ↓↓ - "blank"	1010 1011 1100 1101 1110 1111	

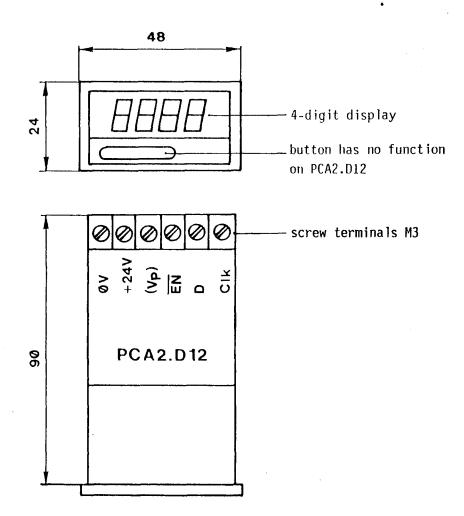
The connection between "Enable", "Clock" and "Data" is illustrated in the time-dependency diagram:



For the generation of the "Clock" as well as for the transmission of data the user must write a short program (examples will follow at the end). In this program, all functions shown in the above diagram, must be realized.

The minimum clock pulses and waiting times are short, so that the instruction set of the SAIA°PLC can easily be applied directly without waiting for certain periods to elapse.

## Presentation and terminal arrangement



#### Technical data:

- Supply voltage:

Input voltage for EN, D, CLK:

- Input current for 24VDC:

- Definition of the input voltages:

- Input delay:

- Usable SAIA°PLC output modules:

- Control

24VDC ± 20%, two-way rectification is sufficient

24VDC, smoothed

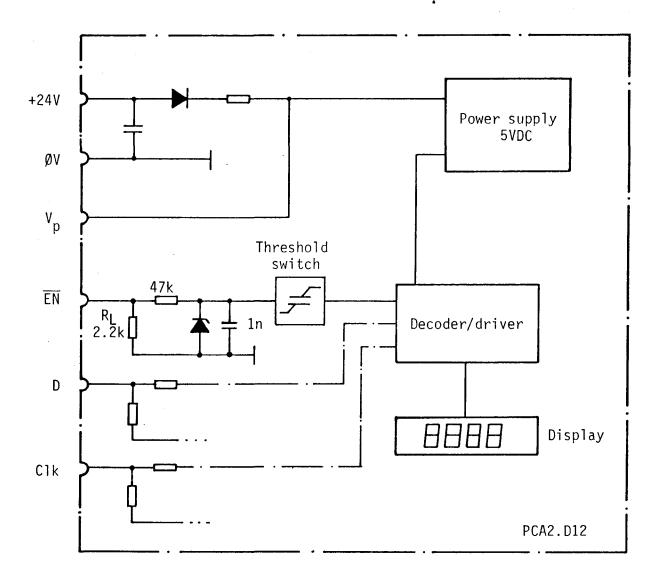
1ØmA

"H": 19V...32V "L": ØV... 4V

< 1ms PCA1.A1Ø, B1Ø, B8Ø, B9Ø PCA2.A4Ø

serially via 3 PLC-outputs or via interface D13

## Input circuit and block circuit diagram



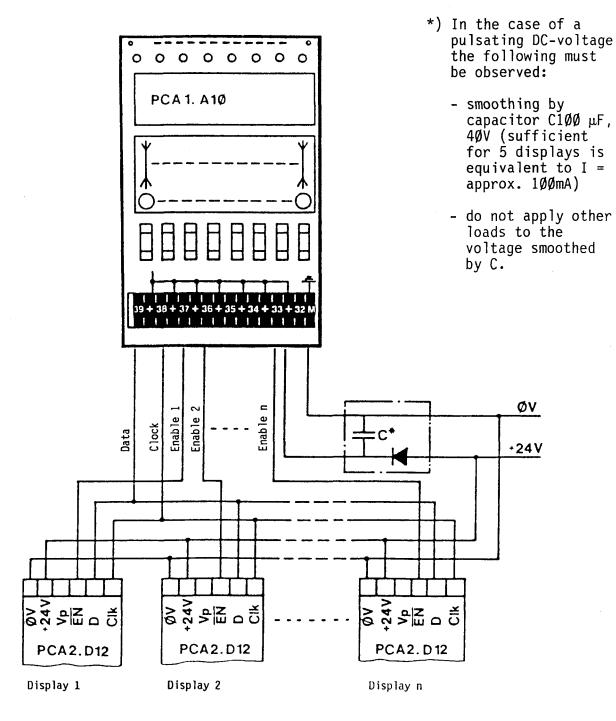
## Note:

 $\mbox{V}_{\mbox{\tiny P}}$  supplies display interface D13.

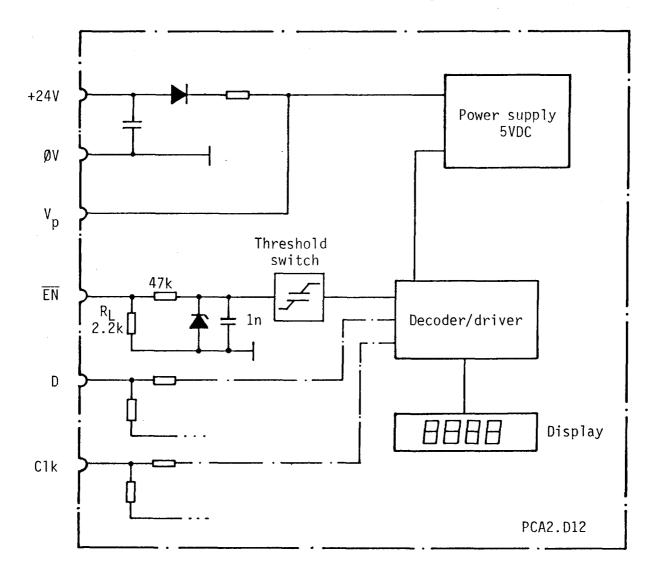
### Connection of several displays to a PLC

Since the PCA2.D12 module is able to transmit an "Enable" signal, i.e. it can be switched to be active or inactive, the same "Clock" and "Data" signals can be used for several displays. These are transmitted to each display simultaneously. The "Enable" signal decides which display is controlled. This means that for each display one "Enable" signal is necessary (1 output per display). This also means, however, that for as many displays as desired only one data and one clock output must be provided.

Connection: (e.g. PCA1.A1Ø - PCA2.D12)



# Input circuit and block circuit diagram



#### Note:

 $V_P$  supplies display interface D13.

#### Examples

#### Example 1

<u>Six PCA2.D12 displays</u> are to be connected to one SAIA°PLC. How many outputs are required?

#### Solution 1

Per display one "Enable" signal 1 "Data" signal (simultaneously to all displ 1 "Clock" signal (simultaneously to all disp	
<u>Tota</u>	8 outputs

#### Example 2

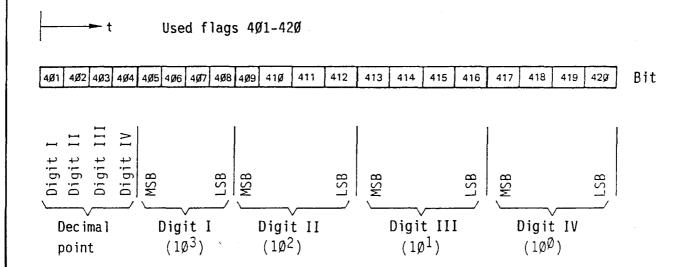
Every half second a counter is to be incremented up to the value 9999 and then reset to zero. Its content is to be indicated on the PCA2.D12 display module with a decimal point in the 2nd place.

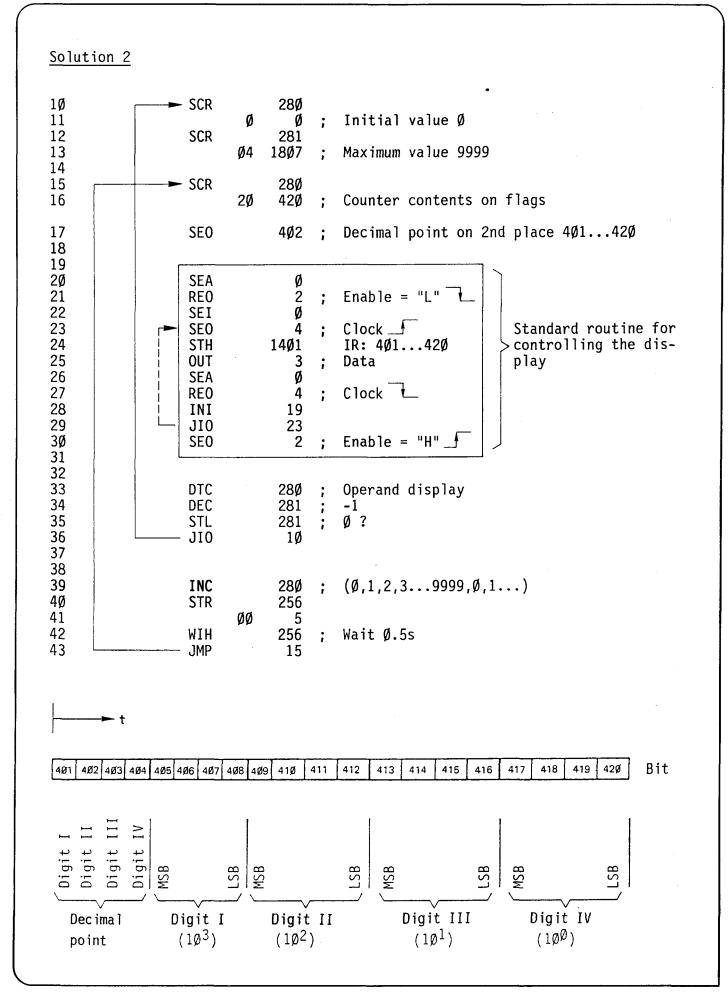
The following outputs must be assigned for "Enable", "Data" and "Clock":

EN: 02 D: 03 CLK: 04

Used counters: C280

C281





#### B 2.2.3 PCA1.D13 Display interface

#### Description

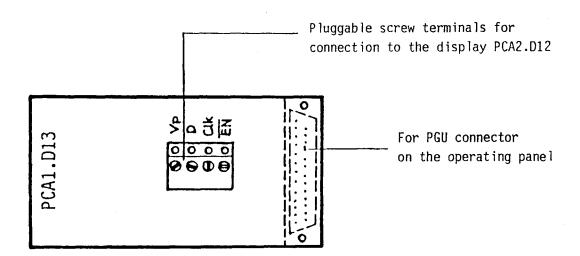
The display interface D13 combines the advantages of the display module PCA1.D11 (simple software handling via the instruction DTC and DOP for 4-digit decimal displays) and those of the display PCA2.D12, which need not be located anywhere near the SAIA°PLC.

The D13 is inserted in the PGU-plug of the SAIA°PLC and connected to the display PCA2.D12 by means of pluggable screw terminals.

#### Technical data

- Supply voltage Vp: 24VDC, ±20%, full-wave rectified is sufficient (supplied by the display module PCA2.D12)
- 3 opto-isolated outputs for EN, D, CLK
- Connection of 2 displays PCA2.D12 is possible (same display)
- Control by means of the instructions DOP and DTC (see manual Software 1H)
- Concerning the cable layout and type of cable between D12 and D13 no special measures are required. The same general criteria as for the cabling of input and output modules apply (see chapter A 5).

#### Presentation

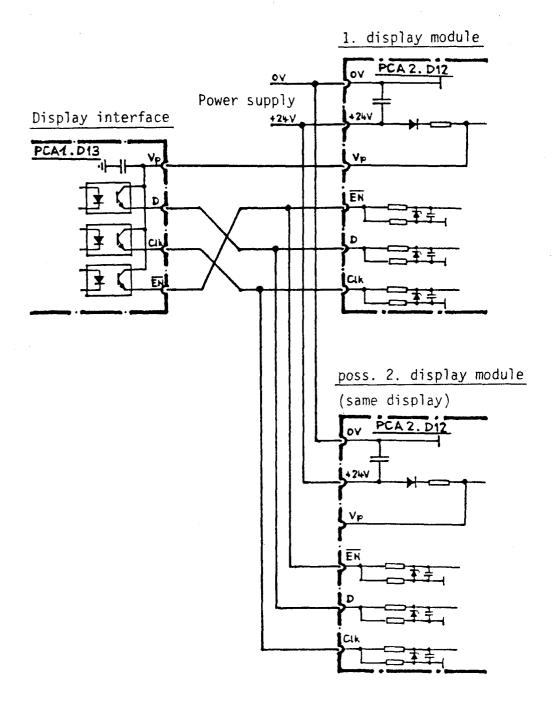


The open module PCA1.D13 is plugged into the PGU-connector of the operating panel. The pluggable screw terminals for connecting the display module protrude through the window.

Various screws are supplied for the attachment and the mechanical protection of the module.



# Connection diagram

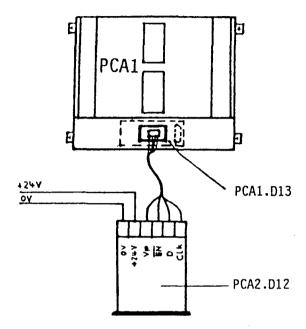


#### Note:

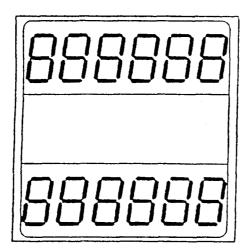
- Both displays indicate the same data.
- Module D13 is supplied by module D12 at the back via the terminals Vp. This and the use of optocouplers ensure maximum interference protection of the PCA1.



# Connection to display module PCA2.D12



#### B 2.2.4 PCA2.D14 Display module



#### General

The PCA2.D14 module is a remote display module which is controlled via 3 outputs of the SAIA°PLC. The module has two 6-digit displays. Several PCA2.D14 can be connected in series in case of more than two displays.

# Application, control

The module was developed in connection with the fast counter module PCA1.H1Ø. In this application controlling is performed by the counter module alone. The user must only program the appropriate mode in the user program.

When the PCA2.D14 is used without the H10 module, the information to be displayed is most easily transmitted serially with a standard program routine from a flag field via 3 SAIA $^{\circ}$ PLC outputs.

## Technical data

Display Digit height Supply voltage

Input voltage for EN, D, CLK Input current at 24VDC Definition of the input level

Input delay
Usable SAIA°PLC output modules

Control

2 times 6 digits, 7-segment LED
10mm
24VDC ± 20%, full-wave rectified is
sufficient
24VDC smoothed
10mA
"H" = +19...+32V
"L" = 0...+4V
< 1ms
PCA1.A10, B10, B80, B90
PCA2.A40
serially via 3 SAIA°PLC outputs
irrespective of the number of D14

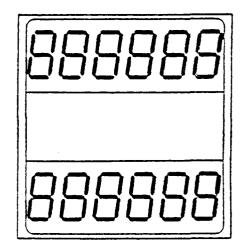


#### Structure, function

The module is located in the same housing as the electronic totalizing counter CKG/AC.

Terminals: Screw terminals combined with connection strips (2.8  $\times$  0.8 mm) for flat pluggable bushes or soldering.

PLC-output	Clock	>	Clk	
PLC-output	Data-In	>	D-IN	
PLC-output	Enable	>	EN	PCA2.D14
Carry	Data-Out	>	D-OUT	PCAZ.014
Voltage supply	+24V	>	+24V	
Voltage supply	ø۷	>	Ø۷	



Upper display

Lower display

The data for a display of 2 x 6 digits are most easily presented in a complete flag field, e.g. M500...547 in BCD-notation. If these values are kept in counters, they must be transferred to the flag fields first.

#### Software routine

Every time the following routine has been executed the current information in the flag field is indicated on the display until the display is updated by a new piece of information after a further run.

## Softlevel 1 \*

(6Ø 61	SEA REO	Ø)	ENABLE
62	SEI	ø	
63	SE0	2 Ø 3	DATA
64	SCR	28Ø	AUX. COUNTER
	ØØ	4	
66	SE0	4	CLOCK -
67	RE0	4	CLOCK
68	DEC	28Ø	AUX. COUNTER
69	STH	28Ø	AUX. COUNTER
7Ø	JI0	66	
71	SCR	28Ø	AUX. COUNTER
	ØØ	16	
73	STH	15ØØ	FLAGS -
74	OUT	3	DATA
75	SEA	Ø	
76	SE0	4	CLOCK
77	RE0	4	CLOCK
78	<u>INI</u>	47	
79	JIZ	84	
8Ø	DEC	28Ø	AUX. COUNTER
81	STH	28Ø	AUX. COUNTER
82	JI0	73	
83	JMP	63	
84	SE0	2	ENABLE -
(85	RET	Ø)	

When <u>not</u> used as a subroutine

<u>Used address</u>	
Enable	A2
Data	A3
Clock	A4
Flag	M5ØØM547
Aux. counter	C28Ø

for M500...547

for 1 D14 upper and lower display \*\*)

When used as a subroutine

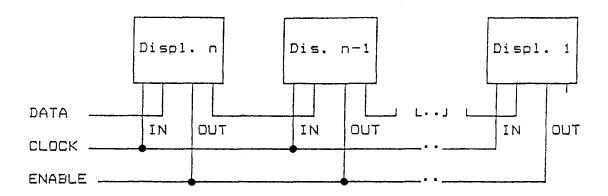
500					523	
M o o o o MSB LSB	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	oooo MSB LSB	display
100'000	10'000	1'ØØØ	100	1Ø	1	upj
524					547	
M o o o o MSB LSB	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	oooo MSB LSB	lower display
100'000	1Ø'ØØØ	1'ØØØ	1ØØ	1Ø	1	. •

<sup>\*\*)</sup> For connecting several D14 in series see following page.



<sup>\*)</sup> The display module D14 can thus be controlled from any SAIA°PLC (including PCA13 and PCA21).

The following diagram shows several PCA2.D14 connected in series.: Each D14 displays its own data.



The flag field containing the information to be displayed must be expanded correspondingly:

```
for 1 PCA2.D14 = 1 x 48 flags
for 2 PCA2.D14 = 2 x 48 flags
for 3 PCA2.D14 = 3 x 48 flags etc.
```

The routine in the user program remains the same, only the instruction "INI" must be changed accordingly:

```
for 1 PCA2.D14 = INI 47
for 2 PCA2.D14 = INI 95
for 3 PCA2.D14 = INI 143 etc.
```

In other words, INI  $(n \times 48) - 1$  with n = number of PCA2.D14.

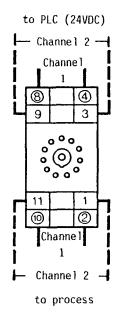
The following 16 characters per segment can be presented:

<u>Character</u>	Code	Character	<u>Code</u>
Ø 1 2 3 4 5 6 7 8 9	ØØØØ ØØØ1 ØØ1Ø ØØ11 Ø1ØØ Ø101 Ø110 Ø111 1ØØØ 1ØØ1	 	1010 1011 1100 1101 1110 1111

For examples refer to the Software manual.

#### B 2.3 KOM series external interface module

The purpose of the external interfaces is for adapting the I/O levels of the PLC from 24VDC to the process requirements. They are constructed in two-channel form and mounted in plug-in housings for an 11-way round socket. LEDs indicate the logic status ("H" = ON), facilitating the rapid checking of the signal lines as far as the terminals of the process. To render the wiring easy to view, the cables from the process or to the PLC are arranged on the opposite side of the plug holder.



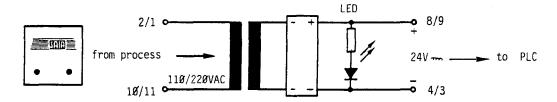
Plug-socket holder Order no. 4 408 4817 Ø

#### B 2.3.1 Type KOM 111B Dual input interface

The purpose of this input interface is for the isolation of the mains control lines from the 24V signal level of the PLC. The isolation is accomplished by means of inductive transmitters; this has the advantage of providing a safeguard against surge voltages.

Front

Switching scheme (per channel)



#### Technical data

Surge voltage on

Input voltage 220V, 50...60 Hz  $\pm$  20% type KOM 111B D4 110V, 50...60 Hz  $\pm$  20% type KOM 111B C8

Input current in each case Ø.5A

Output voltage 24VDC pulsating

Output current in each case max. 40mA

Reaction time max. 10ms (acc. to phase length)

max. Ipms (dee. to phase length)

process side 5kV, 1/5Ø μs

Connection 11-way round socket

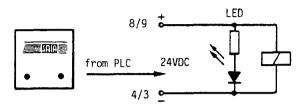
Order specification KOM 111B D4 or C8 (see input voltage)

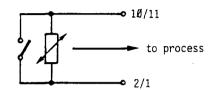
#### B 2.3.2 Type KOM 121B Dual-relay-output interface

Electric isolation in this interface is achieved by relays, the contacts of which are able to directly switch mains voltages. The normally-open contact to the relay is used corresponding to the PLC output.

Front

Switching scheme (per channel)





## Technical data

Input voltage

Input current

Relay contact

Switching power

Contact life (AC1)

Order specification

24VDC ± 20%, smoothed or pulsating

in each case 20mA

in each case 1 normally-open contact with

hard silver contacts

in each case 6A, 25ØVAC AC1 1A, 25ØVAC AC11

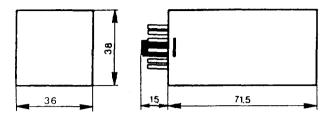
3A. 22ØVAC Ø.1 mio. switching cycles

1.5A, 220VAC 0.5 mio. switching cycles

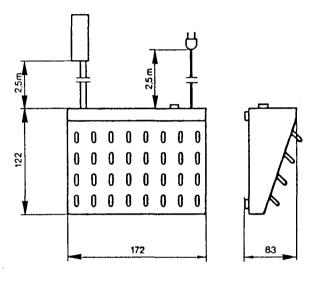
Ø.3A, 22ØVAC 5 mio. switching cycles

KOM 121B M4

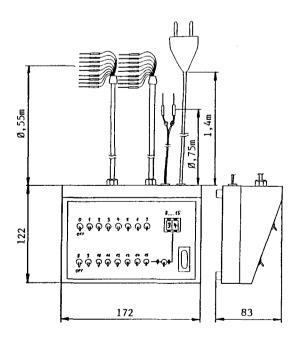
# B 2.4 Dimensions of additional units



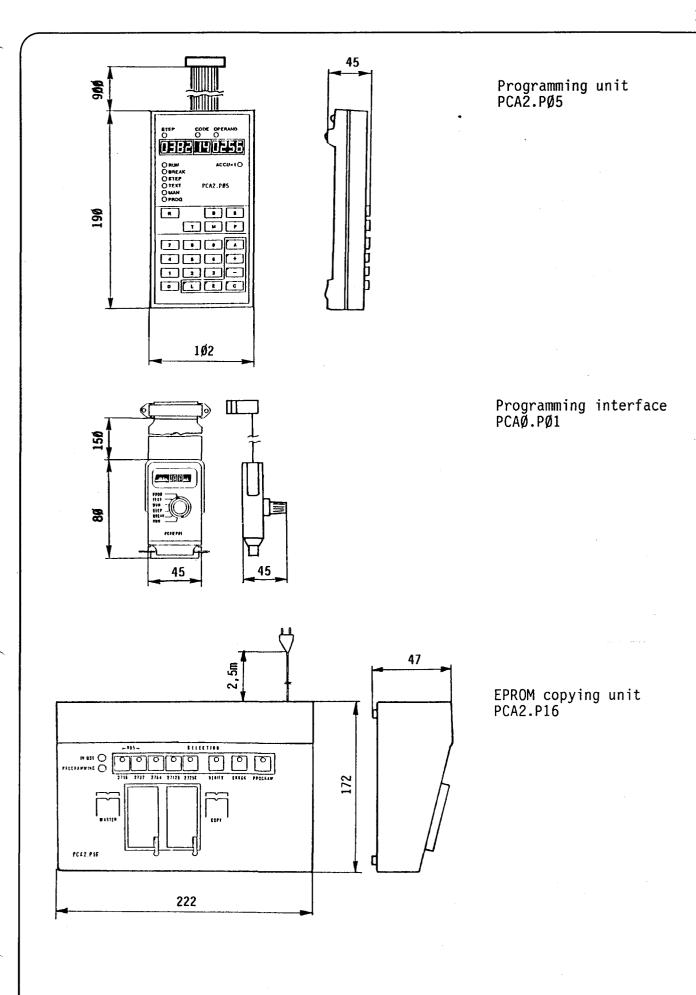
External interfaces KOM 111B and 121B



Input simulation unit PCA2.S1Ø



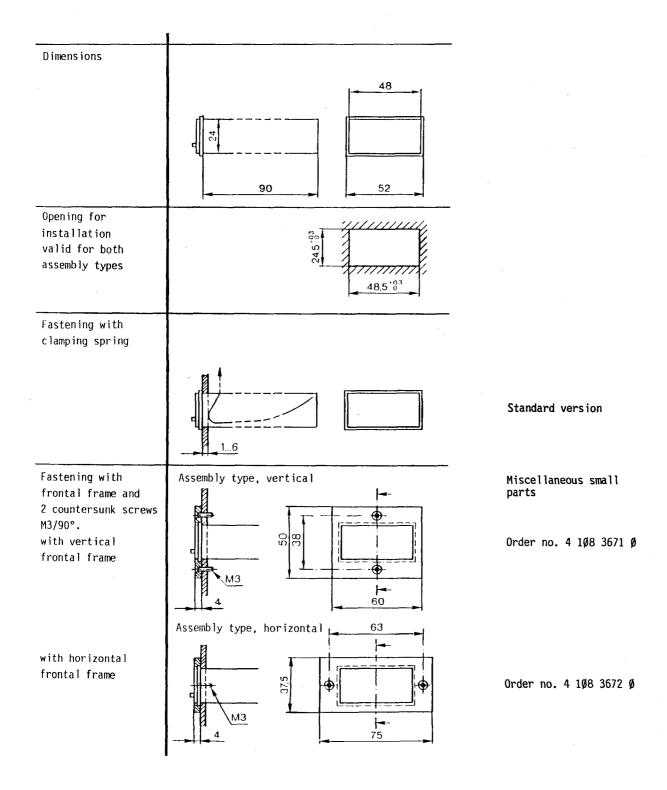
Input simulation unit PCA2.SØ5



# B 2.5 Dimensions, assembly and installation of PCA2.D12

The display can be installed in any position desired anywhere in a control cabinet door or an operating panel.

The display can be fastened in three ways:



## B 2.6 Dimensions, assembly and installation of PCA2.D14

The display module can be installed in any location desired.

It can be fastened in two ways:

- with a clamping springwith a frontal frame and screws

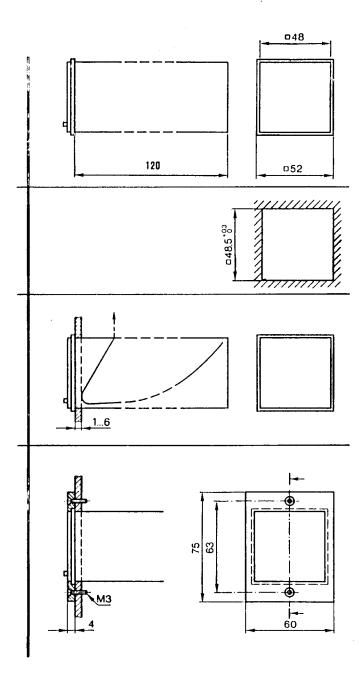
(The clamping spring and the frontal frame are supplied with every PCA2.D14).

## Dimensions

Opening for installation valid for both assembly types

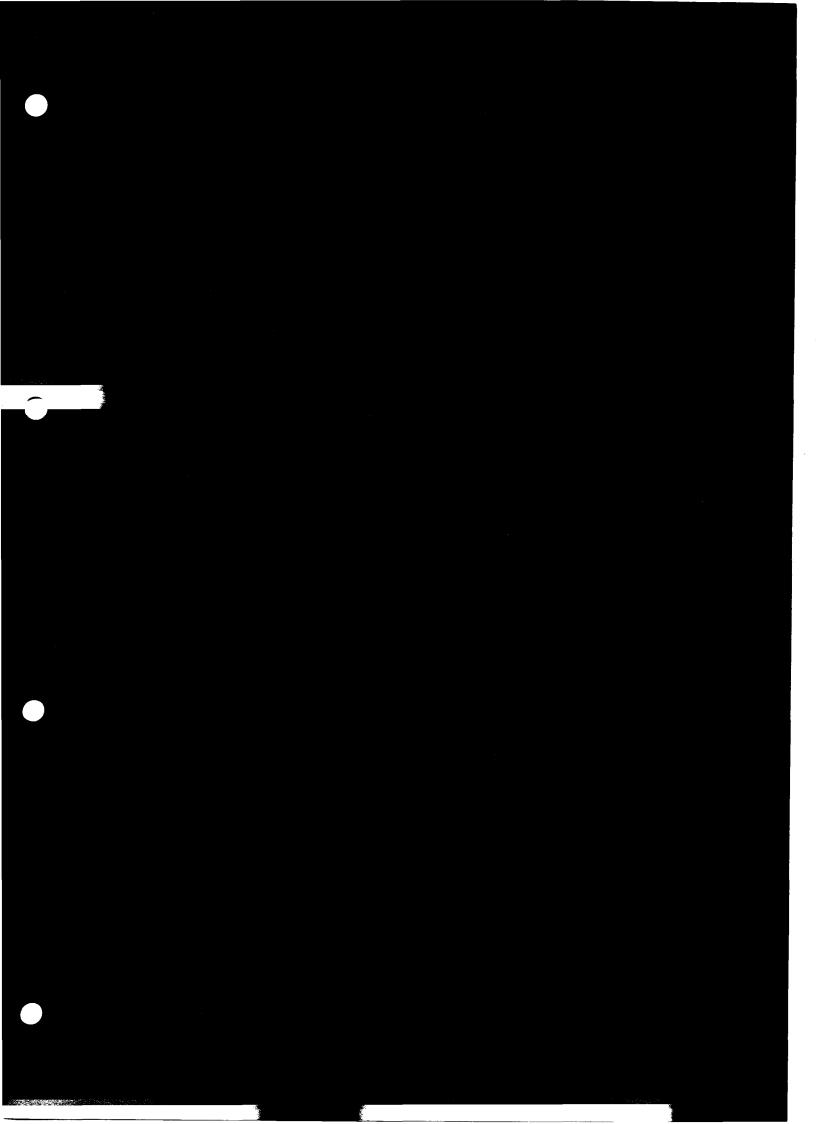
Fastening with clamping spring

Fastening with frontal frame and 2 countersunk screws M3/90°



Notes:





#### **OPERATING MODES**

- C 1 Selection of operating modes for PCA14 and PCA15
- C 1.1 Operating modes, level 1H for PCA15 and PCA14
  - RUN
  - PROG
  - MAN (Bit)
  - BREAK
  - STEP
- C 1.2 Summary of operating modes
- C 1.3 Detailed description of operating modes
- C 2 Further operating modes (only PCA14)
  - MAN with date-time
  - TEXT or text memory as data register



#### Setting of operating modes

A PLC can operate in various operating modes for preparing, testing and editing a program.

PCA14: A sliding switch for selecting the operating modes is provided on the operating panel. This sliding switch is always active.

PCA15: The operating modes are preselected outside the PLC. The keys of the programming unit PCA2.PØ5 are used, or in case a different programming aid such as the handheld computer P18 or an IBM-PC is used, to select the operating modes with the programming interface PCAØ.PØ1.

The selected operating mode remains active, when the connection between the programming units and the PCA15 is ended.

The following operating modes are automatically selected when the PCA15 is switched on.

- With programming unit PØ5 connected: STEP

(LED "STEP" lights up, the green LED "RUN" does not light up!)

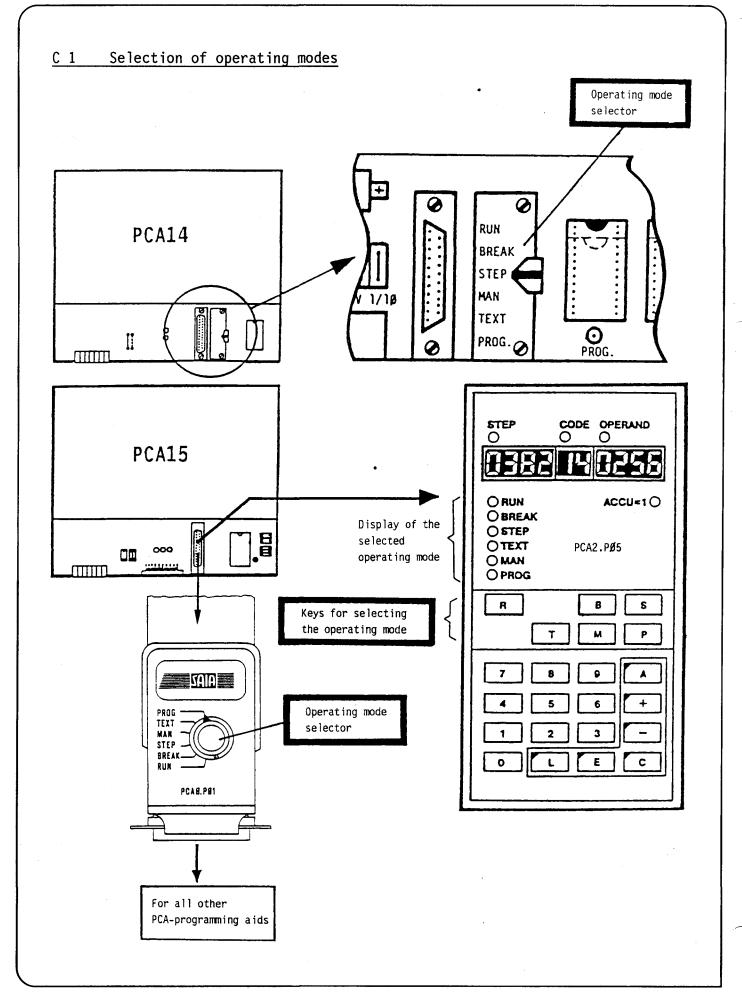
- Without programming unit:

RUN

(LED "RUN" lights up)

- With PØ1 connected:

According to selector switch position



## C 1.1 Operating modes, level 1H for PCA15 and PCA14

R RUN Normal program processing (lamp RUN on PCA15 lights up)

P PROG A user program can be loaded into a RAM memory (plugged onto the user plug-in socket of the PCA15).

M MAN Manual interrogation and setting of elements (inputs, outputs, flags, timers, counters)

S STEP Jump to a preselected step address (program line) of the user program and step-by-step operation

B BREAK Program processing up to a set "breakpoint" and subsequent step-by-step operation

<u>C 1.2</u>	Summary	of operating modes
R	RUN	Normal program execution
		The PCA1 is automatically in the RUN-mode when switching on if no programming unit is connected.
Р	PROG	Programming
		A program can be stored in a RAM-memory (on the user socket of the PCA1) or overwritten (corrected).
		Step Code Operand  A x x x x E x x x x x
		E xx xxxx or C to delete a wrongly entered line
		+ Terminates the input
		Test program
M	MAN **	Manual testing or setting of elements
		(Elements = inputs, outputs, flags, counters, timers)
		Testing: Step  A $\times \times \times$ A display of the logic state in the operand (0/1)
		Element address
		Setting: $A \times X \times E $ or $\emptyset$
		Element address
S	STEP	+ Display showing where the program is.
		Jump to the preselected step address of the user program
		A 139 + Program jumps to step 139, then
		+ + step-by-step execution of the program with the result of the logic operation being checkable * ACC = 1*. Switching to RUN is always possible.
		In case of parallel programs, <u>only the activated parallel program</u> is executed in the STEP-mode.
В	BREAK	Interruption of the program run and subsequent step-by-step-operation
		+ Display showing where the program is
		+ + step-by-step execution of the program with the result of the logic operation being checkable # ACC = 1*. Switching to RUN is always possible.
		In case of parallel programs, all programs are executed simultaneously (as in the RUN-mode).
		Setting of a breakpoint
		A 820 + Program runs up to step 820, then
		+ + + step-by-step operation skipping the "criterial" point.
If	ACC = 1	umulator is used to indicate the result of the logic combination (conditions of the logic combination fulfilled = 1), the
		switching instructions are executed. Iress of a timer or counter is preceded by a 3 (e.g. 3260 for
co	unter 26	50), the value of this register can be read or entered manually value [+].

<u>C 1.</u>	3 Detai	led descripti	on of the ope	erating modes				
R	RUN	The PCA15 i	ram processing automatical amming unit be in posit	Πy in the RUN-π is connected. Fo	node when switch or PCA14, the sl	ing on iding		
Р	PROG		ng can be stored in a RAM memory (on the user plug-in the PCA1) or overwritten (corrected).					
		STEP xxxx	E xx	OPERAND xxxx				
			E xx	xxxx				
			C Deletes	s a wrongly ente	red line			
			+ Termina	ates the input				
			+ + or	to disp	lay the program			
M	MAN	Manual test (Elements =	ing or settin inputs, outp	ng of elements outs, flags, cou	nters, timers)			
		Testing:	A xxx		-display of the state	logic		
		Setting:	A xxx	E	1 or Ø			

A [E] +, -, A, E 3xxx value

For an example see following page.

<sup>1)</sup> STEP = Element address If the address of a timer or counter is preceded by a 3 (e.g. 3260 for counter 260), the value of this register can be read or entered manually with:

Continued from footnote 1)

Example: Input of values 23419 or 127 into counters 290 or 291.

Input:

Display:

CODE

**OPERAND** 

A 329Ø

329Ø

**STEP** 

ØY YYYY

Units Ten-thousands

Always Ø

Input:

Display:

STEP

CODE

**OPERAND** 

329Ø

329Ø

ØY

YYYY

23419 E 127

329Ø

3291

Ø2 Ø1 3419 ØØ27

Correction before storing

127\*

3291 3291

ØØ 00\*

ØØØØ Ø127

<sup>\*</sup> Values <10'000 have to be preceded by a leading  $\emptyset$ .

S	STEP	+ Display showing where the program is.
		Jump to the preselected step address of the user program
	·	A 139 + Program jumps to step 139
		+ + step-by-step processing of the program with the linkage result being checkable: **ACCU = 1 2)
		Switching to RUN is always possible. In case of parallel program, only the activated parallel program is processed in the STEP mode.
В	BREAK	Interruption of the program run and subsequent step-by-step operation
		+ Display showing where the program is.
		+ + step-by-step execution of the program with the linkage result being checkable: # ACCU = 1 2)
		Switching to RUN is always possible. In case of parallel programs, <u>all programs</u> are processed simultaneously (as in the RUN-mode).
		Setting of a "breakpoint"
		A 820 + Program runs up to step 820 in slow RUN operation
		+ + step-by-step operation over the "critical" point

<sup>2)</sup> ACCU (= accumulator) is used to indicate the status of the logic combination. When LED lights up, the ACCU = 1 (conditions of the logic combination fulfilled, linkage result = 1), and the following switching instructions are executed.

## C 2 Further operating modes (only PCA14)

M "MAN"

#### Manual access to the software date-time

In case you use the date-time module E4Ø refer to chapter B 1, where reading and writing to the hardware date-time will be explained (black box routines, Software manual).

All programming units allow direct access to the software date-time (reading and writing).

Contrary to the buffered hardware date-time (PCA1.E40 module), the software date-time works only as long as voltage is applied to the PLC. Therefore, all values have to be introduced each time the PCA14 is started up. The date-time has a max. deviation factor of 3s/day.

The following table shows the signification and the numerical range for the addresses 4000...4007.

Address	Meaning	Numerical range
4000 4001 4002 4003 4004 4005 4006 4007	Week of the year Day of the week Year (1989=89) Month Day of the month (Feb = 28)* Hours Minutes Seconds	153 17 Ø99 112 131 123 159 Ø59

\*) Contrary to the hardware date-time R27, the software date-time does not take the leap years into account (February = 28 days).

You may enter a maximum of 2 digits which appear in the operand (see examples on the following page).

• Examples: Input for Thursday, June 2nd, 89, 10h 12min 45s

Inp	ut:	Display:	STEP	CODE	OPERAND
	4000 22* 4* 89 6* 2* 10 12	bisping.	4000 4000 4001 4002 4003 4004 4005 4006 4007		ØØYY ØØ22 ØØØ4 ØØ89 ØØØ6 ØØØ2 ØØ1Ø ØØ12 ØØ12
+	13		יעעד.	עע	כדעע

After entering the seconds (4007), key + is depressed, provided that the input corresponds to the actual time. Do not press key E again, since otherwise the input of the calendar week is erased.

#### • Display:

Input: Display:

A 4000 + + + + + + +	4000 4001 4002 4003 4004 4005 4006 4007	99 99 99 99 99 99 99	ØØ22 ØØØ4 ØØ89 ØØØ6 ØØØ2 ØØ1Ø ØØ12 ØØ45	22. week of the year Thursday 1989 June 2 10h 12min 45s 46s 47s

<sup>\*</sup> Calendar week and day of the week must correspond to month and date!

# T <u>"TEXT" or text memory as data register</u>

#### Input and reading of texts in the text memory

Input of texts is effected on RAM 6116, 6264 or 8464 or on the buffered RAM modules PCA1.R92/95/96 which are plugged onto the <u>right-hand text socket</u> of the basic module.

The following 2 possibilities are available:

- a) Using one of the PCA programming units, connected via the PGU connector.
- b) With a peripheral unit with current loop interface, connected to the serial data interface (7 terminals on the right).

For detailed description refer to manual Software level 2.

Manual access to the text memory as data register (PAS 54) (as of system program version V6.004)

As mentioned in connection with the instruction PAS 54, the text memory can also be used as data register. In order to understand the monitor function of the system program, the formats which are used for organizing the various registers must be brought to mind:

Counter register

: binary 16 bits

Text memory

: binary 8 bits or 16 bits

(as data register)

or BCD 8 bits

For manual access to the text memory as data register the operating mode selector switch must be set to "TEXT".

- Display of the text memory contents
  - a) Immediate display of a character value of 8 bits (1 byte) in binary notation

Upon actuation of key  $\boxed{\text{A}}$ , and subsequent input of the character number to be displayed ( $\emptyset$ ...8191), the stored value ( $\emptyset$ ...255) is displayed in the operand field in binary notation.

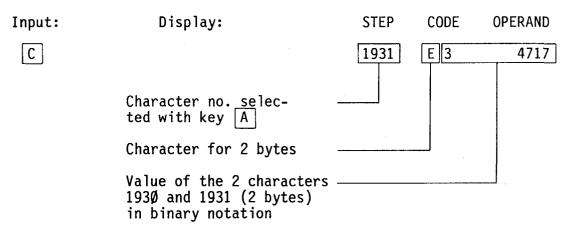
Input:	Display:	STEP	CODE	OPERAND
A 1931		1931	ØØ	Ø 135
	Character no			
	Always ØØ Ø -			
	Value of 8 bits - (1 byte) in binar notation	у		

SAIA

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b) Display of the contents of 2 character no. (2 bytes = 16 bits) in binary notation

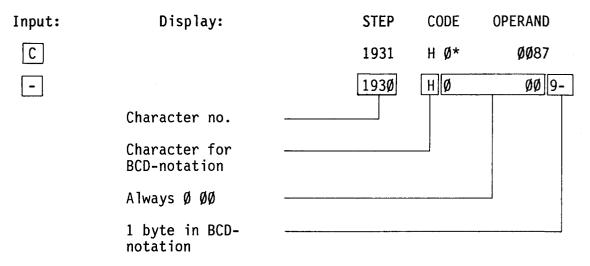
Actuating the key  $\boxed{\text{C}}$  once has the result that in addition to the selected character number the value of the preceding character can also be combined to form a 16-bit value (2 bytes) in binary notation. Consequently values in the range  $\emptyset...65'535$  can be displayed in the CODE and OPERAND field.



In this way, the contents of transferred counters can be displayed with their total capacity of 16 bits.

c) Display of 1 character no. (1 byte = 8 bits) in BCD-notation

By actuating key  $\boxed{\text{C}}$  (convert) <u>a second time</u>, the bit pattern is displayed in BCD-notation.



<sup>\*)</sup> Character in the code applies to PØ5. For P10 refer to the table on the following page.

Real BCD-bit patterns are displayed as decimals. If other characters are present as e.g. at character no. 1930, these are no BCD-bit patterns. In order to be able to interpret their values nevertheless, the following 7-segment characters are defined in the OPERAND:

Binary value	7-segment P1Ø	character   PØ5
10		
11		Е
12		В
13	8	Е
14	Е	8
15	blank	blank

•	Manua 1	data	inputs	into	the	text	memory
	(limite	ed RAN	1-memory	/ in -	this	area	)

Key	Α	:	subsequent be stored	input	of	the	character	no.,	at	which	the	value	is	to
			pe storea											

Corresponding to the reading of data, 3 cases are distinguished for the manual input of data:

# a) Input of a binary value of 1 byte (e.g. 48) at a character no. (e.g. 7436)

Input:		Display:	STEP	CODE	OPERAND
Α	7436		7436	ØØ	ØXXX
E	48		7436	ØØ	<b>Ø</b> Ø48
+			7437	ØØ	ØYYY

b) <u>Input of a binary value of 2 bytes (e.g. 1487) at character no. 7456 and 7457</u>

Input:			Display:	STEP	CODE	OPERAND
Α	7457	1)		7457	ØØ	ØXXX
C		2)		7457	EY*	YYYY
E	1487	3)		7457	E1*	Ø487
C	Ø1487			7457	EØ*	1487
+				7459 4)	EZ*	ZZZZ

- 1) Always the higher address of a pair of 2 bytes is entered.
- 2) C before E results in the conversion to 2 bytes.
- 3) If values < 10'000 are entered, a 0 must be typed first. Correction with  $\boxed{\text{C}}$ .
- 4) The character no. is automatically increased by 2.
- c) Input of a BCD-value (e.g.  $3\emptyset$ ) at character no. 766 $\emptyset$  (in BCD-notation, only values from  $\emptyset$ ..99  $\cong$  1 byte can be entered)

Input:		Display:	STEP	CODE	OPERAND
Α	766Ø		766Ø	ØØ	ØXXX
C			766Ø	EY*	YYYY
C			766Ø	HØ*	ØØZZ
E	3Ø		766Ø	HØ*	ØØ3Ø
+			7661	нø*	ØØAB

<sup>\*)</sup> Characters apply to PCA2.PØ5.

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